

# Update on SoLID Track Reconstruction

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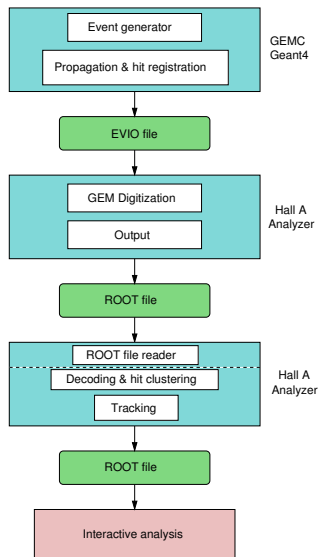
SoLID Collaboration Meeting  
March 22, 2013

# TreeSearch Reconstruction Algorithm

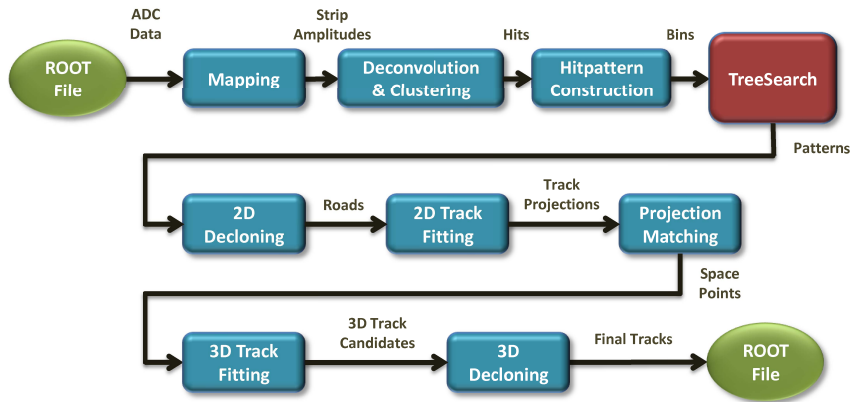
- Global recursive template matching
- Pros
  - ▶ Efficient. High speed:  $\mathcal{O}(\log N)$ . Small memory footprint:  $\mathcal{O}(10 \text{ MB})$
  - ▶ No seed point needed
  - ▶ Available in Hall A analyzer
  - ▶ Successfully used with BigBite data and SBS simulations
- Cons
  - ▶ May not fully solve the problem: requires (nearly) straight tracks
  - ▶ Allowing for small track curvature adds complexity
  - ▶ Code must be adapted to SoLID geometry

# Track Reconstruction Simulation

- solgemc EVIO files as digitization input (S. Riordan)
- GEM digitization based on SBS work (E. Cisbani, R. Holmes)
  - ▶ APV25 pulse shape simulated
  - ▶ Ad-hoc noise simulation (random time offset)
  - ▶ No other detectors digitized yet
  - ▶ Partial passthrough of generated data (tracks, vertices)
- ROOT file interface
- Tracking



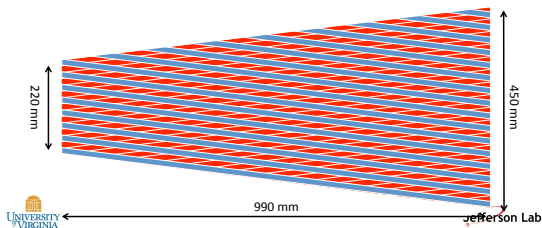
# TreeSearch Track Reconstruction Chain (GEM version)



# Code & Algorithm Modifications Made for SoLID

- Support SoLID geometry
  - ▶ Decoder for simulation output
  - ▶ Support detector positioning in cylindrical coordinates
  - ▶ Cut on non-rectangular active detector area
  - ▶ Particular difficulty: Chambers may have angular an offset!
- Make all sectors appear as one spectrometer, not 30 separate ones
  - ▶ Automatically supported in C++ analyzer, but could be more efficient
- Note yet done: Allow for (small) track curvature in 2D and 3D fits
  - ▶ Need efficient algorithm
  - ▶ Implement parameter range limits
  - ▶ Stability?

# GEM Chamber Strip Layout (illustration from Nilanga)



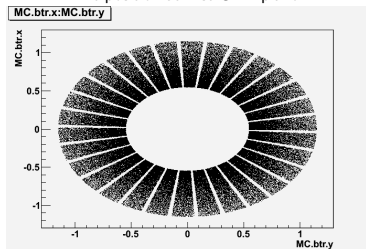
- Strips in different planes **MUST** be parallel for TreeSearch.
- If chambers in different planes have angular offsets, then strips must be rotated wrt chamber frame in the offset planes. (Sorry, no picture.)
- Probably don't want to manufacture GEM chambers with rotated strips!
- If chambers are to have angular offsets, and GEM chambers are to have strips as shown above (not rotated), then the tracking algorithm must be able to handle **non-parallel strips** in different planes. Not impossible, but harder.

# SoLID Track Reconstruction: 1<sup>st</sup> attempt

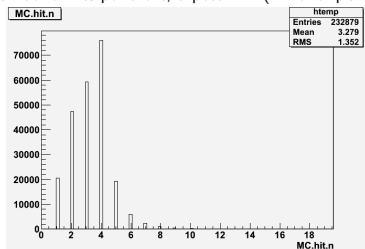
- “Ultra-clean” input data
  - ▶ Muons, no field
  - ▶ Electrons, with field (not yet analyzed)
  - ▶ Very limited materials (basically only the trackers)
  - ▶ No background from target
- Full reconstruction chain
- Standard cuts
  - ▶ Require 3/4 hits per coordinate
  - ▶ Allow 1 missing amplitude correlation
  - ▶ Accept wide  $\chi^2$  range for fits (up to about 10/dof)

# MC input data: tracks, hits (All plots are for "muons, no field")

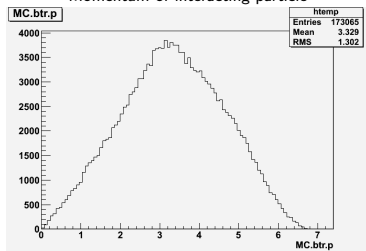
Hit position at first GEM plane



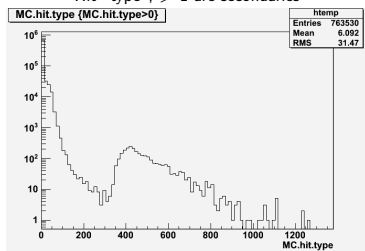
Number of hits per event, expect  $\approx 4$  (= no. of planes)



Momentum of interacting particle



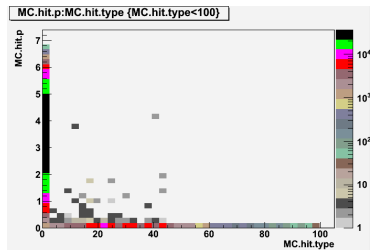
Hit "type", > 1 are secondaries



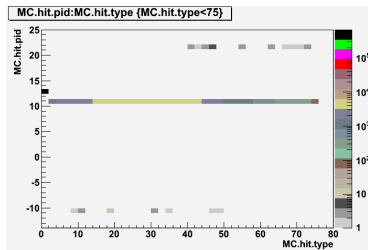


# MC Secondaries

Momentum vs type  $\rightarrow$  secondaries have very low  $p$

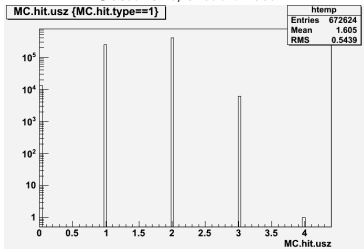


PID vs type  $\rightarrow$  secondaries are mostly  $e^-$

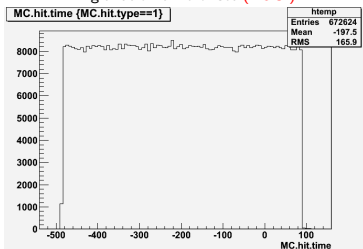


# Digitization

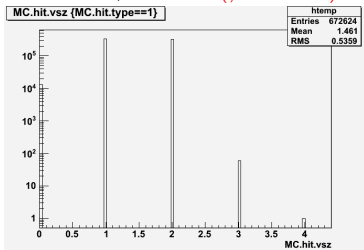
Cluster size,  $u$ -coordinate



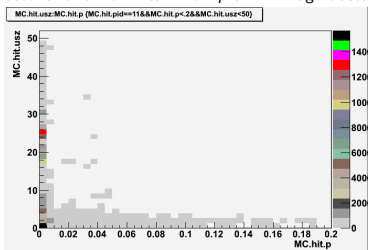
Digitization time offset (BUG!)



Cluster size,  $v$ -coordinate ( $\neq u \rightarrow$  BUG?)

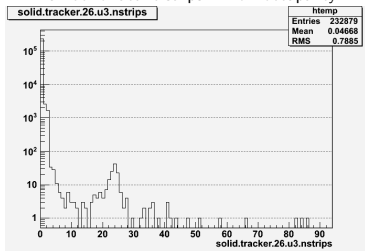


Cluster size vs momentum: low  $p e^- \rightarrow$  huge clusters

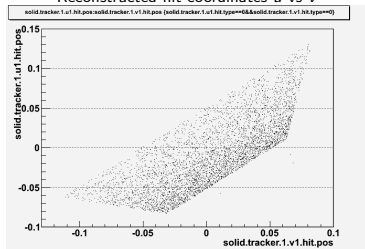


# Decoding & Clustering

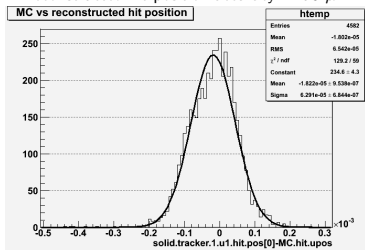
Number of active strips  $\rightarrow$  low occupancy



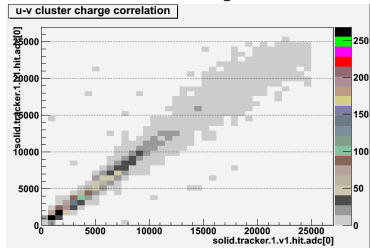
Reconstructed hit coordinates  $u$  vs  $v$



Reconstructed hit position accuracy  $\approx 70 \mu\text{m}$

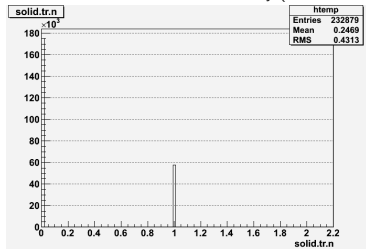


2D readout cluster charge correlation

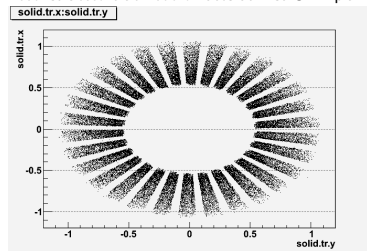


# Track Reconstruction

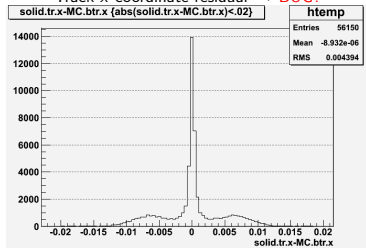
Number of tracks found:  $\approx 35\%$  efficiency (173k MC tracks)



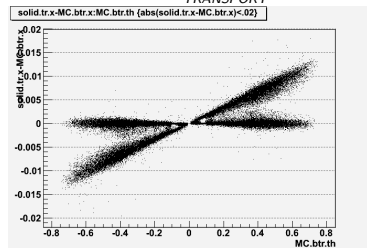
Reconstructed track coordinates at first GEM plane



Track x-coordinate residual  $\rightarrow$  **BUG?**



x residual vs track  $\theta_{\text{TRANSPORT}}$   $\rightarrow$  **BUG!**



# Observations

- It works!
- Digitization still has problems
  - ▶ Time offset for trigger tracks
  - ▶ Small cluster size
- Fairly low tracking efficiency, but not surprising given still un-optimized items:
  - ▶ Digitization
  - ▶ Detector and GEM strip alignment
  - ▶ Reconstruction parameter tuning (many available)
- Track residuals look really “interesting”. Bug? Alignment problems?

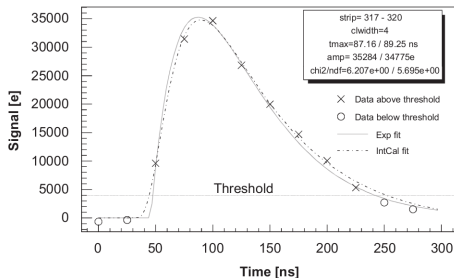
## Next Steps

- Address obvious problems from previous slide. Should really get close to 100% tracking efficiency.
- Analyze “electrons with field” to study effect of track curvature
- Simulate realistic conditions
  - ▶ Add all materials
  - ▶ Add background
  - ▶ Add vertex reconstruction
- With full realistic simulation, get estimates for
  - ▶ Tracking efficiency
  - ▶ Vertex resolutions
  - ▶ Ghost & clone track rate
  - ▶ Computing performance

# Backup Slides

# APV25 Pulse Shape Deconvolution & Noise Filtering

S. Gadomski *et al.*, NIM A 320, 217 (1992)



- For first-order RC circuit, signal amplitudes  $s_k$  can be deconvoluted using **three measured values**  $v_k$ :

$$s_k = w_1 v_k + w_2 v_{k-1} + w_3 v_{k-2}$$

$$w_1 = e^{-x-1}/x, w_2 = -2e^{-1}/x, w_3 = e^{-x-1}/x, \text{ where } x = \Delta t/T_p$$

$$A \approx \sum_{k=1}^3 s_k$$

- Reject noise** by cutting on ratios,  $r_1 = v_3/v_1$  and  $r_2 = v_2/v_1$ , requiring rising slope



# GEM Hit Clustering

- Signals on adjacent readout strips typically belong to a single track crossing
- Sum signals to get
  - ▶ Total hit amplitude
  - ▶ Charge-weighted position centroid
- Currently use simple algorithm:
  - ▶ Look for local peak
  - ▶ When sequence “peak-valley-peak” is seen, split cluster at “valley”
  - ▶ Regardless of shape, limit clusters to a maximum size
- Improvements
  - ▶ Match hits by their pulse shape, *i.e.* timing centroid
  - ▶ Redo clustering after preliminary tracking (*e.g.* better cluster splitting)
  - ▶ ... possibly more
- *NB*: Clustering does not necessarily have to be separate from tracking, could be integrated into a progressive tracking algorithm

