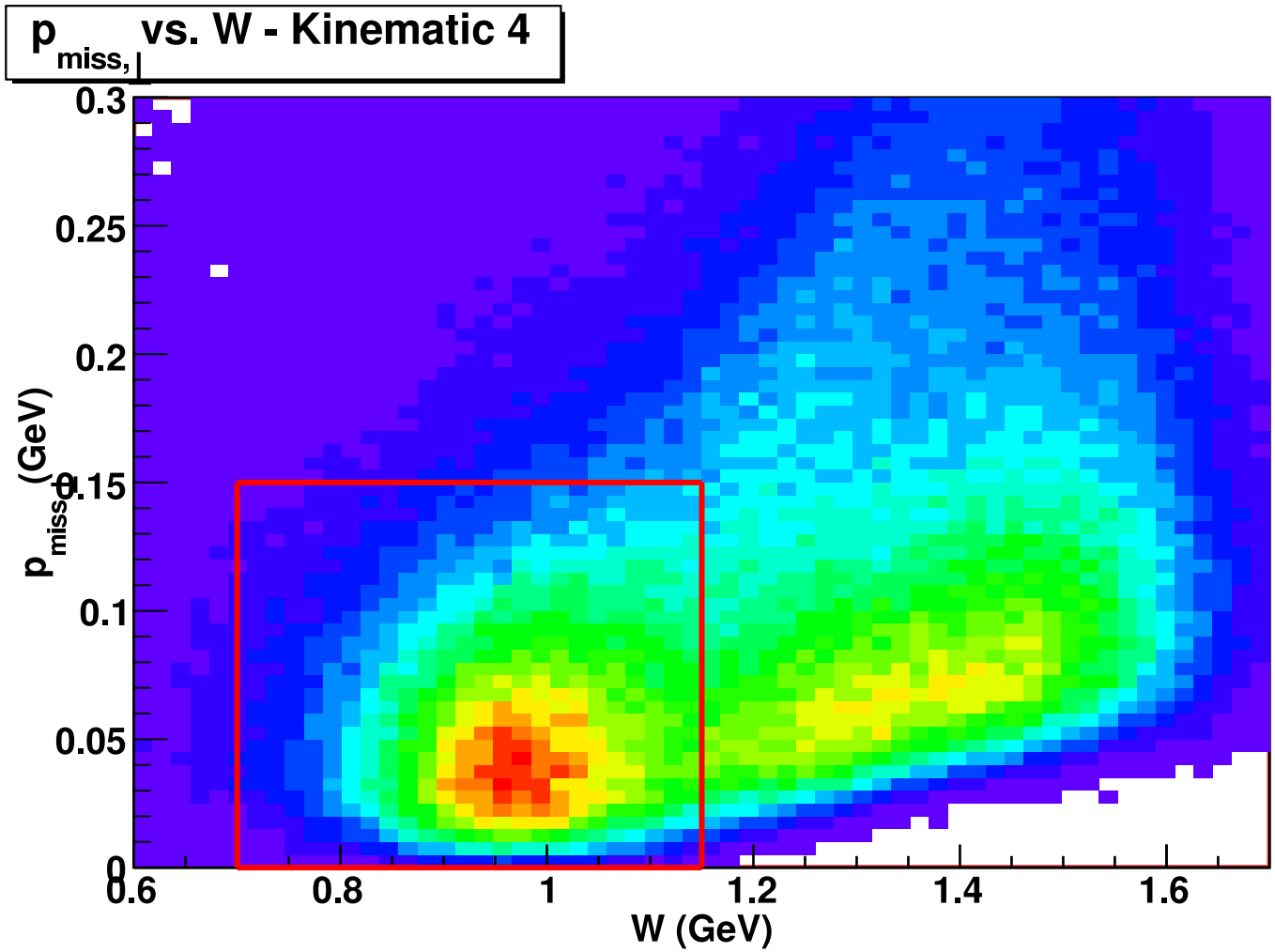
p miss, ⊥ vs. W - Kinematic 4
0.3
0.25
0.2
0.15
0.1
0.05
0
p miss, ⊥ (GeV)
0.6
0.8
1
1.2
1.4
1.6
W (GeV)