

SENSOR PRODUCTS

Advance Information

APPLICATIONS

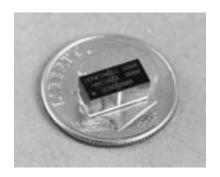
- Compassing
- Navigation Systems
- Attitude Reference
- Virtual Reality
- Traffic Detection
- Proximity Detection
- Medical Devices

Three-Axis Magnetoresistive Sensor HMC1023



Not actual size

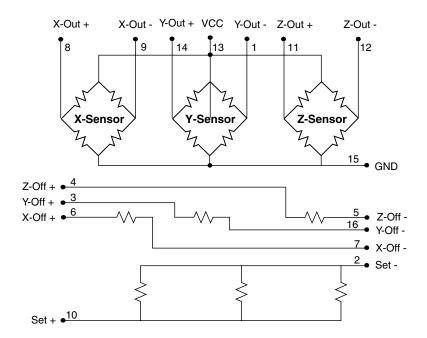
onfigured as three magnetoresistive sensors in x, y
and z orientation, these
highly sensitive sensors
convert all three magnetic
field axes to a differential
output voltage. This new
addition to our line of magnetoresistive sensors is
smaller, uses less power
and is ideal for applications that require orthogonal three-axis sensing.

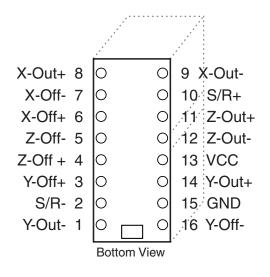


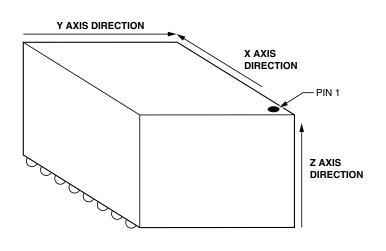
FEATURES AND BENEFITS

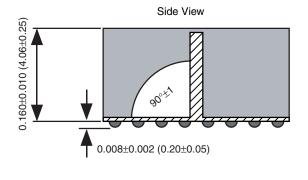
Cost Effective	The sensors were specifically designed to be affordable for high volume OEM applications.
Low Power	The patented on-chip set/reset and offset straps have been improved and now require 50% less power to drive the set-reset and offset functions. This sensor can be operated with a 3 to 25 volt power supply, lowering power consumption and reducing support circuitry.
Solid State	This small device reduces board assembly costs, improves reliability and ruggedness compared to mechanical fluxgates.
Small Package	Designed to work as a single stand alone three-axis (x,y,z) magnetoresistive sensing system. Custom Ball Grid Array (BGA), 1mm pitch, 16-pin miniature package provides a small footprint and accurate sensor placement for orthogonal three-axis sensing applications.
Wide Field Range	Field range of ± 6 gauss, (earth's field = 0.5 gauss) while maintaining high sensitivity with a minimal detectable field down to 85 μ gauss.

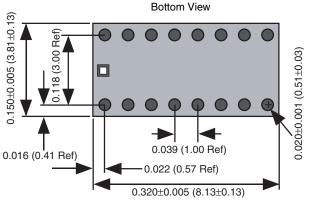
MR SENSOR CIRCUIT / PINOUT SPECIFICATIONS





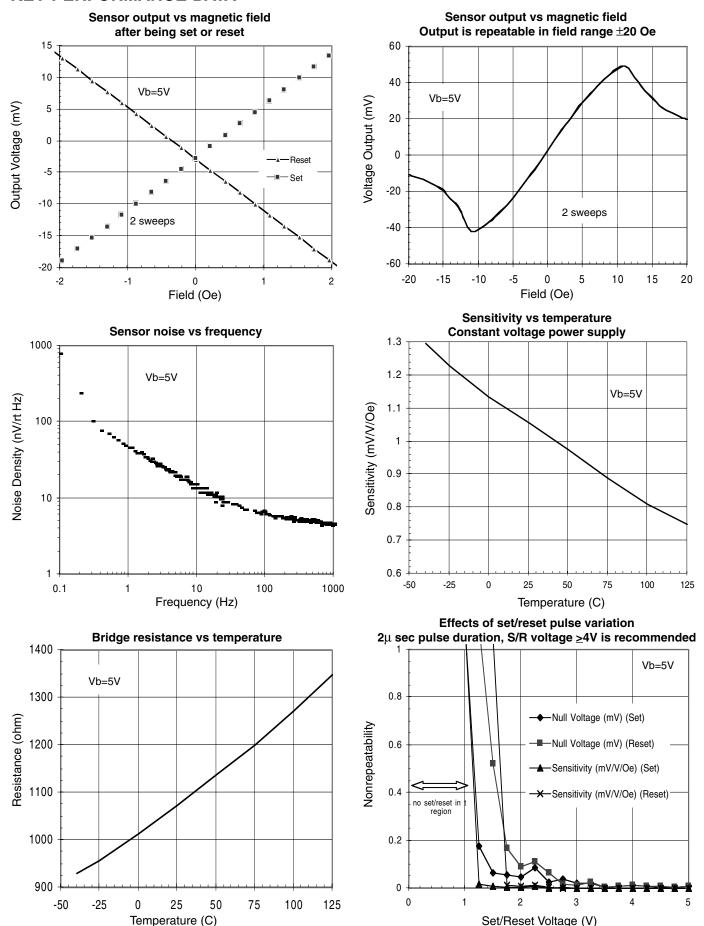






(millimeters)

KEY PERFORMANCE DATA



HMC1023 SENSOR PRODUCTS

SPECIFICATIONS

Characteristic	Conditions	Min	Тур	Max	Unit
Bridge Supply	Vbridge referenced to GND	3	5	12	Volts
Bridge Resistance	Bridge current = 5mA	250	350	450	Ω
Operating Temperature	Ambient	-40		125	° C
Storage Temperature	Ambient, unbiased	-55		125	° C
Field Range	Full scale (FS) — total applied field	-6		+6	gauss
Linearity Error	Best fit straight line ±1 gauss (at 25° C) ±3 gauss ±6 gauss		0.05 0.4 1.6		%FS
Three-Axis Orthogonality	Angle from 90°		±1		degrees
Hysteresis Error	3 sweeps across ±3 gauss @ 25° C		0.08		%FS
Repeatability Error	3 sweeps across ±3 gauss @ 25° C		0.08		%FS
Bridge Offset	Offset = (OUT+) - (OUT-), Field=0 gauss after Set pulse, Vbridge=5V	-10	±2.5	+10	mV
Sensitivity	At Vbridge=5V	0.8	1.0	1.2	mV/V/gauss
Noise Density	Noise at 1Hz, Vbridge=5V		48		nV/√Hz
Resolution	Bandwidth=10Hz, Vbridge=5V		85		µgauss
Bandwidth	Magnetic signal (lower limit = DC)		5		MHz
OFFSET Strap	Measured from OFFSET+ to OFFSET-	40	50	60	Ω
OFFSET Strap ΩTempco	Ta=-40 to125° C		3900		ppm/° C
OFFSET Field	Field applied in sensitive direction	4.0	4.6	6.0	mA/gauss
Set/Reset Strap (1)	Measured from S/R+ to S/R-	2.0	3.0	4.0	Ω
Set/Reset Current (1)	2μS current pulse	1.5	2.0	4.0	Amp
Disturbing Field	Sensitivity starts to degrade. Use S/R pulse to restore sensitivity.	20			gauss
Sensitivity Tempco	Ta=-40 to 125° C Vbridge=5V Ibridge=5mA	-2800	-3000 -600	-3200	ppm/° C
Bridge Offset Tempco	Ta=-40 to 125° C no Set/Reset Ibridge=5mA with Set/Reset		±500 ±10		ppm/° C
Resistance Tempco	Vbridge=5V, -40 to 125° C		2500		ppm/° C
Cross-Axis Effect	Cross field=1gauss (see AN-205) Happlied=±1 gauss		+0.3		%FS
Max. Exposed Field	No perming effect on zero reading			200	gauss

⁽¹⁾ Three in parallel.

Units: 1 gauss (G) = 1 Oersted (in air), 1G = 79.58 A/m, 1G = 10E-4 Tesla, 1G = 10E5 gamma

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