LoPRO[®]Linear Motion Systems

Complete Actuated Linear Guidance Systems



0

Motion without limits."

Guided Linear Motion Systems - Overview

Guided linear motion systems from the Bishop-Wisecarver Corporation[®] (BWC) consist of two main design elements:



DualVee[®] Motion Technology (DMT[™]) is an antifriction, "guide wheel-based" linear bearing design. DualVee[®] wheels are built with double row, angular contact, ball bearing construction and are characterized by their unique "double vee" outer race profile. DualVee[®] wheels engage with a mating 90 degree mating track producing a rigid, yet smooth running, antifriction linear guide. Pioneered and perfected over a 30 year period , DMT[™] offers "motion without limits" for actuated linear transport and positioning applications.

DualVee-Based Linear Motion Systems Features and Benefits

Complete Integrated System Package

A complete actuated system design eliminates the effort associated with integration of lower level components and assemblies. By specifying complete actuated linear systems, equipment designers are able to accelerate machine design and fabrication while reducing overall installed cost.

Proven Technology High Reliability

 $\text{DMT}^{\mbox{\tiny IM}}$ has been successfully employed in industrial linear motion systems for over 30 years.

Broad Product Range

A wide range of options including numerous standard actuator sizes and types (ball screw, acme screw, belt, and chain drives). Standard systems include 4 sizes of linear guide, each including options such as structural support beams, corrosion resistant bearing elements, and multiple wheel plate designs. Guide wheels can be supplied in 52100 bearing steel or 440C stainless, with either sheilds or seals, and can be internally lubricated with standard or special greases. Additional options include high temperature or clean room compatible wheels, and various wheel cover and lubricator configurations.

High Speed Capacity

Speeds up to 10 meters / second and accelerations to 5g can be achieved due to the circular raceway design of the DualVee $^{\odot}$ guide wheel.

Smooth, Antifriction Operation

Rolling contact interface, retained bearing balls, and dual circular raceway design produces smooth, antifriction operation.

Long Stroke Lengths

The ability to butt join DualVee[®] track allows for long system stroke lengths, limited only by the actuator technology. Belt driven systems in excess of 80 feet have been succesfully employed.

Low Noise / Low Vibration

DMT exhibits up to 50% lower noise than alternative round or square rail ball guides consiting of ball tracks that recirculate thru sharp 180 degree endcap deflectors. Guide wheel-based systems have circular raceways and retained bearing balls eliminating the collisons which produce both noise and vibration.

Impervious To Contaminated Environments

DualVee[®] guide wheels translating along a mating 90 degree vee way produces an inherent surface velocity gradient along the rolling contact surface. This acts to sweep debris aside, ejecting particulates from the interface as the wheel travels along the rail. Recirculating elements are protected from the environment in a well contained, radial bearing construction, eliminating the need for expensive bellows or way covers which are often required for alternative recirculating bearing technologies.

Low Profile Designs

Standard BWC system designs are configured with a very low profile footprint, made possible by the the thin cross section of DualVee $^{\circ}$ componentry.

Flexibility And Simplicity In Design

DMT allows for flexibility in linear bearing construction, permitting optimized engineered solutions for specific application requirements. Wheel-to-track fitup is accomplished via eccentric bushings or studs, making assembly and field maintenance easy to perform.

About Bishop-Wisecarver Corporation®

Bishop-Wisecarver Corporation[®] is a family owned manufacturing company specializing in guide wheels and motion control technologies. DualVee[®] was designed as a problem solver for automotive, machine tool, paper processing, textile, and general industrial automation applications where traditional guidance technologies proved ineffective. DualVee Motion Technology[®] (DMT[™]) has continued to evolve into an ideal technology for today's cutting edge industries such a laboratory equipment, bio-medical, semiconductor, and electronics assembly.

BWC[®] invented the DualVee[®] guide wheel and has been a world leader in guide wheel technology since 1970. DMT[™] integrates three main components, the DualVee[®] guide wheel, its mating DualVee[®] track with patented mounting shoulder, and the DualVee[®] support bushing. Our product line includes components, linear guides, linear systems, rotary guides and systems, and aluminum machine framing.

Actuated Linear Motion Systems

Since its introduction into the industrial equipment marketplace over thirty years ago, DualVee Motion Technology[®] has become an industry standard linear guidance solution. The LoPro[®] linear motion system is a modular, actuated system design, available in screw, belt, and chain driven configurations. Its low cost, ease of installation, and unique design characteristics make it the system of choice for many linear bearing applications.

Developed over 8 years ago, LoPro[®] belt, chain, and screw drive systems have been implemented in virtually every industry covering a wide range of applications. This catalog is an introduction to the revised LoPro[®] design, which includes a wider range of options and many new design enhancements.

From factory automation projects to OEM equipment designs, LoPro® linear systems offer a level of reliability unmatched in the industry. This is particularly true considering the wide range of environments in which it can be employed. Known primarily for it's ability to operate in harsh, contaminated environments, LoPro® linear systems are just as often employed in laboratory and clean room-grade equipment designs. When reliable, smooth, low friction guidance is mandatory, LoPro® linear systems perform well, even in the most challenging conditions.

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Screw Driven LoPro[®] Linear Motion System mounted to an optional aluminum support beam



Simple end bearing support for ball or lead screw driven systems.

Ball or lead screw actuation available –

Ball screw actuation is available in seven standard diameter and lead combinations. Lead screw systems are available in 23 standard combinations of screw diameter and leads – choice of pre-loaded and non-preloaded lead screw nuts.



LoPro® Track Plate Assembly -

Low profile, anodized aluminum plate supporting twin single edge DualVee® tracks – track is available in carbon or stainless steel, as formed or induction hardened.

Exploded view showing guide wheel mounting construction – Mounting hardware includes a wheel bolt, a bushing, and a washer. Also shown is a wiper cap, including oil saturated felt lubricator, and side guard.



Belt Driven LoPro[®] Linear Motion System mounted to an optional aluminum support beam



High strength anodized aluminum support beam with industry standard cross section and T-slot configuration. Steel cable reinforced, high performance polyurethane timing belt, ideal for high speed / high cycling applications.

> Idler end with belt tensioning adjustment – Rugged anodized aluminum housing; pulley is supported by dual radial ball bearing arrangement. Tension adjustment screw is easily accessed on the back plate of the assembly.

LoPro® track plate assembly -

Low profile, anodized aluminum plate supporting twin single edge DualVee® tracks – track is available with induction hardened veeways in either carbon or stainless steel.

System Composition

Chain Driven LoPro® Linear Motion System mounted to a steel support beam



Drive end -

Constructed with anodized aluminum housing, and hardened, stainless steel input drive shaft. Sprocket and shaft are supported by twin radial bearings.

Steel support beam – Rigid base structure for maximum strength and stiffness – excellent support beam for high and rapidly changing loads.



Idler end with tension adjustment -

Rugged anodized aluminum housing; sprocket supported by dual radial ball bearing arrangement. Chain tension adjustment screw is easily accessed on the back plate of the assembly.

Track plate assembly – Anodized aluminum plate with hardened steel DualVee[®] track.



System Configurations

All BWC[®] linear motion products are based on DualVee Motion Technology[®] which are available in various configurations, and are primarily characterized by their level of integration.

The three major DualVee® categories include:

- Components
- Linear Guides
- Actuated Linear Systems



- DualVee[®] componentry offers the ultimate in design flexibility for ground up linear motion design projects
- Choose from a variety of guide wheel, track, and mounting hardware configurations
- Accessories include wheel covers and lubricators
- Material options include stainless steel and carbon steel
- DualVee[®] track is available with optional black oxide finish, thin dense chrome plating, or electroless nickel plating (other platings and treatments are available - consult BWC Applications Engineering)
- Consult BWC Applications Engineering for special materials, configurations, and designs
- Covered in the Components and Linear Guides Catalog





- Standalone linear guides consist of prematched carriage and track assemblies
- Eliminates the design work associated with component integration
- Linear guides are easy to specify and even easier to install
- Bill of material control is simplified and the number of purchased items is consolidated
- Carriages come complete with adjustable wheels for track fitup and options such as wheel covers and track lubricators
- Standard prematched linear guides include either a 4-wheeled or a 3-wheeled carriage assembly, both consisting of DualVee[®] componentry
- Mating track assemblies are available in standard lengths with various options
- Covered in the Components and Linear Guides Catalog



- Covered on pages 12 thru 52
- Actuated linear systems are linear guides integrated with linear actuators
- Minimizes the integration design effort with minimal lead time (typical lead time: 2 weeks or less)
- Further reduces the number of elements within a machine design's bill of materials
- The LoPro[®] actuated linear motion system is the BWC standard; LoPro[®] integrates a 4-wheeled DualVee[®] carriage and a prematched track assembly with one of several standard actuator options
- Standard LoPro[®] actuators include belt, chain, ball screw and lead screw
- Custom engineered actuated linear systems are also available (consult applications engineering)

Multi-Industrial Applications



Large gantry assembly built with LoPro[®] linear guidance systems. Special steel beam mounted configurations provided complete from BWC. Photo courtesy of SWRi.

DualVee[®]-based linear mechanisms are popular worldwide and used throughout a broad range of industries:

- Machine tool
- Laboratory equipment
- Automotive production equipment
- General industrial automation
- Biomedical equipment
- Inspection equipment
- Material handling equipment
- Textile machinery
- Linear slides
- Paper processing and converting equipment
- Semiconductor equipment
- Packaging machinery
- Electronics assembly equipment
- Non-contact machining equipment

Visit our website at www.bwc.com to view specific application examples and success stories.



Typical Configurations

Single Axis Linear Motion



X-Y Gantry Arrangement



X-Y-Z Multi Axis arrangement





Specifications





Customized, vertically oriented, LoPro® linear system including chain counterbalance and rack drive, configured for use in a gantry robot application. Photo courtesy of SWRi.

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LoPro[®] Linear Motion Systems

Overview

LoPro[®] Linear Systems consist of two main design elements:

- A linear guide built with DualVee Motion Technology[®]
- A linear actuator standards include belt, screw, and chain drive units

LoPro® linear motion system, disassembled to show the major components. In this case, the linear actuator is a ball screw assembly and its two end supports. The linear guide is shown with wheel plate mounted on its mating track assembly. In the foreground is a partially disassembled wiper wheel plate, showing guide wheel, wiper cap, side guard, and mounting hardware. This particular system is unsupported (has no steel or aluminum beam supporting the track plate). The low profile of the LoPro® linear system is particularly evident in an unsupported arrangement.

Linear Guide

Linear guidance in a LoPro[®] linear motion system is achieved using DualVee Motion Technology[®] (DMT[™]). DMT[™] is a low profile, guide wheelbased linear bearing arrangement which uses DualVee[®] guide wheels and 90 degree, induction hardened, vee-shaped rails. DualVee[®] guide wheels are characterized by their double vee outer race geometry including a 90 degree vee groove along the outermost diameter. In the LoPro[®] linear guide, guide wheels are configured into wheel plate assemblies, each containing four DualVee[®] wheels. Wheel plates are designed with two eccentrically mounted wheels opposing two fixed position wheels. This arrangement allows for easy wheel-to-track fitup adjustment.



Profile of a DualVee[®] guide wheel sitting atop an induction hardened stainless steel DualVee[®] track. Note that the recirculating bearing elements are not exposed to the environment at the track interface



LoPro® systems come with two wheel plate options, basic and wiper. The wiper wheel plate design captures the guide wheel on both sides of the bearing, and encapsulates the contact region with lubricating wiper caps and side guards.

LoPro[®] Linear Motion Systems

Two lengths of hardened steel track is mounted to a low profile aluminum track plate with veeways pre-aligned and parallel to within 0.002" (0.05mm). Track plate is available in single piece lengths up to 10 feet (3m), but are routinely butt joined with a staggered track arrangements for longer stroke length requirements (in some cases, in excess of 100 feet).



LoPro® trackplate assembly consisting of two lengths of induction hardened steel track mounted to an anodized aluminum substrate

Four different sizes of LoPro[®] wheel plate and track plate assemblies make up the main design element of the LoPro[®] linear motion system. DMT[™] offers a tough, low friction, low profile package, built to withstand a wide range of operating environments.

DualVee[®] guide wheels are built to tight tolerance specifications (ABEC 5, double row angular contact). All recirculating bearing elements remain tucked away within the radial bearing design which are proven to operate well in difficult, contaminated environments. This is in contrast to alternative recirculating element designs, specifically round and square rail linear bearing designs. In the round rail ball bushing, for example, recirculating elements are in direct contact with the shaft for the entire stroke length of the system. Such designs often require bellows or other costly methods of protection, to prevent the ingression of contaminants into the recirculating ball pathways. Contamination of the pathways interrupts smooth ball recirculation, which leads to premature, and ultimately, catastrophic bearing failure.

As a result of the differential surface velocity, the mesh between a DualVee[®] guide wheel and a mating 90 degree track remains largely unaffected by contaminants. As the carriage traverses along the track plate assembly, debris is simply swept aside.



DualVee[®] guide wheels employ a double row, angular contact radial bearing construction. DMT[™] performs reliably in difficult operating environments due to the sealed ball races.



Alternative linear guidance technologies have recirculating elements in direct contact with the rail entire stroke. This arrangement is susceptible to contamination in the recirculating pathways, which could lead to premature failure.

DualVee[®] guide wheels and track are available in carbon steel or 400 series stainless steel. Wheel plates and track plates are anodized aluminum. Corrosion resistant versions of LoPro[®] are also available.

Linear Actuator

LoPro[®] linear motion systems are available with the following standard actuator options:

- Belt Drive
- Chain Drive
- Lead screw Drive
- Ball screw Drive



Belt driven LoPro[®] linear system. System as shown includes an aluminum support beam and a basic wheel plate with wheel covers. Drive ends and carriage attachment features are designed for high performance, high cycling motion. High quality radial bearings are combined with a sleek, high strength, anodized aluminum housing. Belt and chain drive units include a 400 series stainless steel shaft, with pulleys and sprockets keyed into place. The key / keyway arrangement provides a reliable locking configuration with good rigidity. Bearing fits in the drive end construction are tightly controlled, ensuring smooth and rigid thrust capability. Belt and chain tensioning can be adjusted at the idler drive end. Adjustments are made via an easy to access hex nut that is located on the back of the idler end.

Motor Mounts

Standard flanges are available for NEMA and IEC motor faces.





Idler end of a LoPro[®] chain driven system. This particular system includes a steel support beam . Note the tension adjustment feature on the back plate of the Idler end.

LoPro[®] screw driven units utilize a fixed - simple bearing support configuration. The fixed end to which the drive motor is coupled, employs a double row, angular contact bearing mounted in a rigid, anodized aluminum housing. The simple end houses a Conrad style, radial ball bearing. Motor mount adapter flanges are available for all four sizes of LoPro[®]. Standard motor flanges include Nema and IEC. Other motor faces can also be accommodated.

Support Beam Options

LoPro[®] linear systems are available with two different standard support beam options. Support beams are convenient when the application calls for a self supported linear system. In a beam mounted LoPro[®] linear system, drive ends, actuator, and linear guide are bundled into a complete, integrated system. All design elements are rigidly affixed to the support beam, and therefore requires minimal preparation for mounting.





Aluminum support beam mounted, size 1 lead screw driven LoPro[®] with basic wheel plate (left). Unsupported, size 3 ball screw driven LoPro[®] (right) shows a wiper wheel plate driven by a non-preloaded ball screw assembly. Steel beam mounted track plate assemblies offer high system rigidity. Beams are predrilled and painted; custom shapes are available. **AT Belt-Drive Systems**

- Complete belt actuated linear system, ready for immediate installation
- Standard aluminum and steel support beam options available
- Two standard available wheel plate options
- Available in standard and corrosion resistant versions
- High speed and acceleration capacity
- Long stroke length capability
- Nema and IEC motor mounts available
- Guide system constructed with DualVee Motion Technology[®]

CA	CARRIAGE ASSEMBLY LOAD CAPACITIES										
System Size	Axial I Capa	Load city	Radial Capa	Load city							
	N	lbs	N	lbs							
1	988	222	1166	262							
2S/2L	2449	551	2805	631							
3	3 6668		6026	1355							
4	15682	3525	9220	2073							

AXIAL LOAD	

LOPRO SYSTEM BELT LOAD CAPACITIES										
System Size	Belt Part Number	Wor Lo	king ad	Ultimate Tensile Strength						
	runnson	N Ibs		N	lbs					
1	10AT5	630	142	2539	571					
2S	16AT5	1008	227	4063	913					
2L	16AT10	2085	469	8463	1902					
3	20AT10	2606	586	10579	2378					
4	32AT10	4170	937	16926	3805					

System Size	Belt Size	DRIVE E		
Oystelli Oize	Den Oize	Pitch Diameter	No. of Teeth	Material
1	10AT5	28.7 mm 1.128 in	18	
2S	16AT5	38.2 mm 1.504 in	24	
2L	16AT10	79.6 mm 3.133 in	25	Bodies with Aluminum or Plated Steel Flanges
3	20AT10	95.5 mm 3.759 in	30	hated steel hanges
4	32AT10	95.5 mm 3.759 in	30	



Note: Carriage starting positions may vary. Pictures do not necessarily represent the starting positions of all the lead screw systems, i.e. not all systems' starting positions have the carriage in intimate contact with the drive end housing as shown.

Beam-Mounted Systems: Wiper Wheel Plates



	Size	Track Plate Length TPL = TL + CL System Length					Tube Length TBL			ו	System Height SH				
		TPL SL					ALUMINUM/STEEL				ALUMINUM	STEEL			
	1	ΤL	+	94.0	mm	TPL	+	173.6	mm	TL	+	154.0	mm	63.0 mm	61.1 mm
ŧ		ΤL	+	3.701	in	TPL	+	6.835	in	ΤL	+	6.063	in	2.480 in	2.406 in
la	2S	TL	+	129.9	mm	TPL	+	227.5	mm	TL	+	209.9	mm	73.0 mm	71.1 mm
The second secon	20	ΤL	+	5.114	in	TPL	+	8.960	in	ΤL	+	8.264	in	2.874 in	2.799 in
he	21	TL	+	129.9	mm	TPL	+	318.1	mm	TL	+	209.9	mm	113.0 mm	109.2 mm
≥.	22	ΤL	+	5.114	in	TPL	+	12.522	in	ΤL	+	8.264	in	4.449 in	4.299 in
er	З	TL	+	177.6	mm	TPL	+	400.1	mm	TL	+	281.6	mm	163.0 mm	144.6 mm
dij	0	ΤL	+	6.992	in	TPL	+	15.752	in	TL	+	11.087	in	6.417 in	5.693 in
5	Δ	TL	+	243.8	mm	TPL	+	440.9	mm	ΤL	+	351.8	mm	N1 (A	156.6 mm
	4	ΤL	+	9.599	in	TPL	+	17.358	in	TL	+	13.851	in	N/A	6.165 in

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Beam-Mounted Systems: Basic Wheel Plates



	Size	Track Plate Length				Sy	stem Length				Tube Length TBL	1		System S	Height H		
		TPL		SL		ALUMINUM/STEEL			ALUMINUM STEEL		EL						
	1	TL	+	90.0	mm	TPL	+	173.6	mm	TL	+	150.0	mm	72.1	mm	69.8	mm
e		TL	+	3.543	in	TPL	+	6.835	in	ΤL	+	5.906	in	2.823	in	2.750	in
lat	25	TL	+	127.0	mm	TPL	+	227.6	mm	TL	+	207.0	mm	83.5	mm	81.1	mm
-	20	TL	+	5.000	in	TPL	+	8.960	in	ΤL	+	8.150	in	3.268	in	3.194	in
Jee	21	TL	+	127.0	mm	TPL	+	318.1	mm	TL	+	207.0	mm	123.5	mm	119.2	mm
Ś	26	TL	+	5.000	in	TPL	+	12.582	in	ΤL	+	8.150	in	4.862	in	4.694	in
er	2	TL	+	172.0	mm	TPL	+	400.1	mm	ΤL	+	276.0	mm	177.0	mm	158.6	mm
/ip	5	TL	+	6.772	in	TPL	+	15.753	in	TL	+	10.886	in	6.969	in	6.244	in
5	Λ	TL	+	242.0	mm	TPL	+	440.9	mm	TL	+	350.0	mm	N1//		170.6	mm
	4	ΤL	+	9.528	in	TPL	+	17.358	in	ΤL	+	13.780	in	N/A	A	6.717	in



AT Belt-Drive Systems

Unmounted Systems: Wiper Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length







	Size	Track Plate Length System Length		Carriage Height	DE1	DE2	
		TPL	SL	СН			
	1	TL + 94.0 mm	TPL + 173.6 mm	23.0 mm	30.0 mm	16.0 mm	
Ĕ		IL + 3.701 III	IFL + 0.030 III	0.900 III	1.101 111	0.030 III	
8	2S	IL + 129.9 mm	IPL + 227.6 mm	33.0 mm	40.0 mm	27.5 mm	
		TL + 5.114 in	TPL + 8.960 in	1.299 in	1.575 in	1.083 in	
Jee	21	TL + 129.9 mm	TPL + 318.1 mm	33.0 mm	40.0 mm	68.0 mm	
1	22	TL + 5.114 in	TPL + 12.522 in	1.299 in	1.575 in	2.677 in	
e	З	TL + 177.6 mm	TPL + 400.1 mm	43.0 mm	52.0 mm	77.4 mm	
lip	Ŭ	TL + 6.992 in	TPL + 15.753 in	1.693 in	2.047 in	3.047 in	
5	Λ	TL + 243.8 mm	TPL + 440.9 mm	55.0 mm	54.0 mm	75.0 mm	
	4	TL + 9.599 in	TPL + 17.358 in	2.165 in	2.126 in	2.953 in	

Unmounted Systems: Basic Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length







	Size	Track Plate Length	System Length	Carriage Height	DE1	DE2	
		TPL	SL	СН			
e	1	TL + 90.0 mm TL + 3.543 in	TPL + 173.6 mm TPL + 6.835 in	31.7 mm 1.250 in	30.0 mm 1.181 in	16.0 mm 0.630 in	
l Plat	2S	TL + 127.0 mm TL + 5.000 in	TPL + 227.6 mm TPL + 8.960 in	43.0 mm 1.694 in	40.0 mm 1.575 in	27.5 mm 1.083 in	
Whee	2L	TL + 127.0 mm TL + 5.000 in	TPL + 318.1 mm TPL + 12.522 in	43.0 mm 1.694 in	40.0 mm 1.575 in	68.0 mm 2.677 in	
/iper /	3	TL + 172.0 mm TL + 6.772 in	TPL + 400.1 mm TPL + 15.753 in	57.0 mm 2.244 in	52.0 mm 2.047 in	77.4 mm 3.047 in	
\$	4	TL + 242.0 mm TL + 9.528 in	TPL + 443.2 mm TPL + 17.358 in	69.0 mm 2.717 in	54.0 mm 2.126 in	75.0 mm 2.953 in	

Chain-Drive Systems

 Complete chain-actuated linear system, ready for immediate installation

- Standard aluminum and steel support beam options available
- Two standard available wheel plate options
- Available in standard and corrosion-resistant versions

- High load-carrying capacity
- Long stroke length capacity
- Standard NEMA and IEC motor mounts available
- Guide system constructed with DualVee Motion Technology®

AXIAL LOAD	
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CARRIAGE ASSEMBLY LOAD CAPACITIES											
System Size	Axial Capa	Load city	Radial Capa	Load acity							
	N	lbs	N	lbs							
1	988	222	1166	262							
2S/2L	2449	551	2805	631							
3	6668	1499	6026	1355							
4	15682	3525	9220	2073							

LOPRO SYSTEM CHAIN LOAD CAPACITIES									
System	Chain Size	Average Stre	e Tensile ngth	Working Load					
Size	Single Strand	N	lbs	N	lbs				
1	25	3892	875	625	141				
2S	35	9341	2100	2135	480				
2L	35	9341	2100	2135	480				
3	40	16458	3700	3600	809				
4	50	27134	6100	6225	1399				

System Size	Chain Size		DRIVE END SPROCI	KETS
System Size	Gildin Size	Pitch Diameter	No. of Teeth	Material
1	25	24.5 mm 0.966 in	12	
2S	35	36.8 mm 1.449 in	12	
2L	35	79.0 mm 3.111 in	26	Steel or Stainless Steel
3	40	97.3 mm 3.831 in	24	
4	50	91.4 mm 3.599 in	18	

Motion without limits."



Note: Carriage starting positions may vary. Pictures do not necessarily represent the starting positions of all the lead screw systems, i.e. not all systems' starting positions have the carriage in intimate contact with the drive end housing as shown.

Beam-Mounted Systems: Wiper Wheel Plate



	Size		Track Plate Length			Sy	stem Length	1	Tube Length TBL			System Height SH			
				TPL				SL		ALUMINUM/STEEL			ALUMINUM	STEEL	
	1	ΤL	+	94.0	mm	TPL	+	173.6	mm	TL +	154.0	mm	63.0 mm	61.1 mm	
e	'	ΤL	+	3.701	in	TPL	+	6.835	in	TL +	6.063	in	2.480 in	2.406 in	
ola.	25	TL	+	129.9	mm	TPL	+	227.6	mm	TL +	209.9	mm	73.0 mm	71.1 mm	
Ĩ.	20	ΤL	+	5.114	in	TPL	+	8.960	in	TL +	8.264	in	2.874 in	2.799 in	
Je	21	TL	+	129.9	mm	TPL	+	318.1	mm	TL +	209.9	mm	113.0 mm	109.2 mm	
S	ZL	ΤL	+	5.114	in	TPL	+	12.522	in	TL +	8.264	in	4.449 in	4.299 in	
er	2	TL	+	177.6	mm	TPL	+	400.1	mm	TL +	281.6	mm	163.0 mm	144.6 mm	
ġ.	3	ΤL	+	6.992	in	TPL	+	15.753	in	TL +	11.087	in	6.417 in	5.693 in	
5	4	TL	+	243.8	mm	TPL	+	443.2	mm	TL +	351.8	mm	N1/A	156.6 mm	
	4	TL	+	9.599	in	TPL	+	17.449	in	TL +	13.851	in	N/A	6.165 in	

Beam-Mounted Systems: Basic Wheel Plate



ΤI

TL

TL

ΤL +

TL

ΤL +

TL

2L

3

4

+

+

+

+

5.000

5.000

6.772

9.528

127.0

172.0

242.0

in

mm

in

mm

in

mm

in

TPL

TPL

TPL

TPL

TPL

TPL

TPL

+

+

+

+

+

8.960

12.522

15.753

17.358

318.1

400.1

440.9

TL

TL

TL

ΤL +

TL

ΤL +

ΤL

in

mm

in

mm

in

mm

in

+

+

+

+

8.150

8.150

10.886

13.780

207.0

276.0

350.0

in

mm

in

mm

in

mm

in

3.268

4.843

6.969

N/A

123.0

177.0

in

mm

in

mm

in

3.194

4.694

6.244

6.717

119.2

158.6

170.6

in

mm

in

mm

in

mm

in



Chain-Drive Systems

Unmounted Systems: Wiper Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length

eel Plate



	Size	Track Plate Length			System Length		Carriage Height		DE1		DE2		
			TPL			SL		СН					
	1	TL +	94.0	mm	TPL +	173.6	mm	23.0	mm	30.0	mm	16.0	mm
e		TL +	3.701	in	TPL +	6.835	in	0.906	in	1.181	in	0.630	in
a.	2S	TL +	129.9	mm	TPL +	227.6	mm	33.0	mm	40.0	mm	27.5	mm
L.		TL +	5.114	in	TPL +	8.960	in	1.299	in	1.575	in	1.083	in
he	21	TL +	129.9	mm	TPL +	318.1	mm	33.0	mm	40.0	mm	68.0	mm
l₹		TL +	5.114	in	TPL +	12.522	in	1.299	in	1.575	in	2.677	in
e	3	TL +	177.6	mm	TPL +	400.1	mm	43.0	mm	52.0	mm	77.4	mm
li,	Ŭ	TL +	6.992	in	TPL +	15.752	in	1.693	in	2.047	in	3.047	in
>	Δ	TL +	243.8	mm	TPL +	440.9	mm	55.0	mm	54.0	mm	75.0	mm
	+	TL +	9.599	in	TPL +	17.358	in	2.165	in	2.126	in	2.953	in

Unmounted Systems: Basic Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length





	Size	Track Plate Length			System Length			Carriage Height		DE1		DE2	
			TPL			SL		C	Н				
	1	TL +	90.0	mm	TPL +	173.6	mm	31.7	mm	30.0	mm	16.0	mm
e		TL +	3.543	in	TPL +	6.835	in	1.250	in	1.181	in	0.630	in
a	25	TL +	127.0	mm	TPL +	227.6	mm	43.0	mm	40.0	mm	27.5	mm
H	20	TL +	5.000	in	TPL +	8.960	in	1.694	in	1.575	in	1.083	in
lee	21	TL +	127.0	mm	TPL +	318.1	mm	43.0	mm	40.0	mm	68.0	mm
1	26	TL +	5.000	in	TPL +	12.522	in	1.694	in	1.575	in	2.677	in
er	2	TL +	172.0	mm	TPL +	400.1	mm	57.0	mm	52.0	mm	77.4	mm
ġ	3	TL +	6.772	in	TPL +	15.752	in	2.244	in	2.047	in	3.047	in
2	4	TL +	242.0	mm	TPL +	440.9	mm	69.0	mm	54.0	mm	75.0	mm
	4	TL +	9.528	in	TPL +	17.358	in	2.717	in	2.126	in	2.953	in

- Complete lead screw actuated linear system, ready for immediate installation
- Standard aluminum and steel support beam options available
- Two standard available wheel plate options
- Available in standard and corrosion-resistant versions
- Standard and anti backlash nuts available
- Lead accurate to 0.0006 in./in. (mm/mm)
- Standard NEMA and IEC motor mounts available

CARRIAGE ASSEMBLY LOAD CAPACITIES										
System	Axial Capa	Load city	Radial Load Capacity							
5120	N Ibs		N	lbs						
1	988	222	1166	262						
2S/2L	2449	551	2805	631						
3	6668	1499	6026	1355						
4	15682	3525	9220	2073						

LOPRO LEAD SCREW THRUST CAPACITIES									
Size	Screw Diameter	Nut Type	Dynamic Load Capacity						
	IN	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	N	lbs					
1	1 / 4	BY	196	44.0					
I	1/4	NTBY	44	9.9					
0	0.10	BY	343	77.1					
2	3/8	NTBY	89	20.0					
0	1/2	NTBY	446	100.3					
3	5/8	BY	981	220.5					
4	0/4	BY	1570	352.9					
4	3/4	VHDY	1560	350.7					

- Guide system constructed with DualVee Motion Technology[®]
- Stock lead screw lengths: up to 4000 mm. Longer lengths available - consult factory.





Note: Carriage starting positions may vary. Pictures do not necessarily represent the starting positions of all the lead screw systems, i.e. not all systems' starting positions have the carriage in intimate contact with the drive end housing as shown.



Beam Mounted Systems: Wiper Wheel Plate



	Size	Screw Dia	Nut	Track Plate Length	System Length	Tube Length TBL	Carriage Height CH	System Height SH								
		D 101	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	TPL*	SL	ALUMINUM/STEEL	ALUMINUM STEEL	ALUMINUM STEEL								
	1	1//	ΒY	TL + 95.8 mm TL + 3.771 in	TPL + 65.7 mm	TPL + 43.0 mm	63.0 mm 61.1 mm	70.5 mm 68.6. mm								
	1	1/4	NTBY	TL + 99.2 mm TL + 3.906 in	TPL + 2.588 in	TPL + 1.693 in	2.480 in 2.406 in	2.776 in 2.701 in								
Plate	2	2/0	ΒY	TL + 129.9 mm TL + 5.114 in	TPL + 91.8 mm	TPL + 59.0 mm	73.0 mm 71.1 mm	83.2 mm 81.3 mm								
heel P	۷	3/8	NTBY	TL + 146.9 mm TL + 5.785 in	TPL + 3.615 in	TPL + 2.323 in	2.874 in 2.799 in	3.276 in 3.201 in								
er WI	S	1/2	NTBY	TL + 206.6 mm TL + 8.134 in	TPL + 108.1 mm	TPL + 77.0 mm	163.0 mm 93.8 mm	172.2 mm 103.0 mm								
Wip	0	5/8	ΒY	TL + 180.4 mm TL + 7.101 in	TPL + 4.354 in	TPL + 3.031 in	6.417 in 3.693 in	6.780 in 4.055 in								
	4	3/4	3/4	3/4	3/4	3/4	3/4	3//	3/4	3/4	BY	TL + 270.0 mm TL + 10.628 in	TPL + 121.7 mm	TPL + 86.0 mm	N/A 105.8 mm	N/A 119.4 mm
	-7		VHDY	TL + 298.4 mm TL + 11.748 in	TPL + 4.792 in	TPL + 3.386 in	N/A 4.165 in	N/A 4.701 in								

* Track plate length (TPL) = track length (TL) + carriage length (CL) + nut protrusion.

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Beam-Mounted System: Basic Wheel Plate



	Size	Screw Dia.	Nut Type	Track Plate Length	System Length	Tube Length TBL	Carriage Height CH/SH		
			.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	TPL	SL	ALUMINUM/STEEL	ALUMINUM	STEEL	
	1	1/4	BY	TL + 90.0 mm TL + 3.543 in	TPL + 65.7 mm	TPL + 43.0 mm	71.8 mm	69.8. mm	
	I	17-4	NTBY	TL + 90.0 mm TL + 3.543 in	TPL + 2.588 in	TPL + 1.693 in	2.825 in	2.750 in	
neel Plate	2	2/0	ΒY	TL + 137.0 mm TL + 5.394 in	TPL + 91.8 mm	TPL + 59.0 mm	83.0 mm	81.1 mm	
	Ζ	3/8	NTBY	TL + 154.0 mm TL + 6.063 in	TPL + 3.615 in	TPL + 2.323 in	3.269 in	3.194 in	
er Wh	0	1/2	NTBY	TL + 204.5 mm TL + 8.052 in	TPL + 108.1 mm	TPL + 77.0 mm	177.0 mm	107.8 mm	
Wip	3	5/8	ΒY	TL + 180.4 mm TL + 7.101 in	TPL + 4.254 in	TPL + 3.031 in	6.968 in	4.244 in	
	1	3/4	BY	TL + 270.0 mm TL + 10.628 in	TPL + 121.7 mm	TPL + 86.0 mm	N/A	119.8 mm	
	4	0,4	VHDY	TL + 296.6 mm TL + 11.677 in	TPL + 4.792 in	TPL + 3.386 in	N/A	4.717 in	





Unmounted Systems: Wiper Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length
- System is shipped with temporary mounting plates affixing drive ends to track plate

Carriage Length) (Travel Length)



	Size	Screw Dia.	Nut Type	Track Pla Length	Track Plate Length		System Length		System Base Length			Carriage Height		System Height	
				TPL			SL			SBL		С	Н	S	H
	1	1/4	BY	TL + 95.8 TL + 3.77	mm I in	TPL +	65.7	mm	TPL +	43.0	mm	23.0	mm	30.5	mm
	1	1/4	NTBY	TL + 96.7 TL + 3.80	mm 3 in	TPL +	2.58	8 in	TPL +	1.693	3 in	0.906	in	1.201	in
late	0	2/0	ΒY	TL + 129.9 TL + 5.114	mm in	TPL +	91.8	mm	TPL +	59.0	mm	33.0	mm	43.2	mm
leel P	Z	3/0	NTBY	TL + 146.9 TL + 5.78	mm 5 in	TPL +	3.61	5 in	TPL +	2.32	3 in	1.299	in	1.701	in
er Wh	2	1/2	NTBY	TL + 195.5 TL + 7.696	mm in	TPL +	108.1	mm	TPL +	77.0	mm	43.0	mm	52.2	mm
Wipe	3	5/8	BY	TL + 180.4 TL + 7.101	mm in	TPL +	4.23	4 in	TPL +	3.03	1 in	1.693	in	2.055	5 in
	Λ	2/4	BY	TL + 270.0 TL + 10.63	mm 3 in	TPL +	121.9	mm	TPL +	86.0	mm	55.0	mm	68.6	mm
	4	5/4	VHDY	TL + 298.4 TL + 11.748	mm in	TPL +	4.79	2 in	TPL +	3.38	6 in	2.165	in	2.701	in

Unmounted Systems: Basic Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length
- System is shipped with temporary mounting plates affixing drive ends to track plate







(System Base Length)

	Size	Screw Dia.	Nut Type	Track Plate Length	System Length	System Base Length	Carriage Height/ System Height	
				TPL	SL	SBL	CH/SH	
	1	1 / 4	ΒY	TL + 90.0 mm TL + 3.543 in	TPL+ 65.7 mm	TPL + 43.0 mm	31.7 mm	
	I	1/4	NTBY	TL + 90.0 mm TL + 3.543 in	TPL+ 2.588 in	TPL + 1.693 in	1.250 in	
late	0	2/0	BY	TL + 137.0 mm TL + 5.394 in	TPL+ 91.8 mm	TPL + 59.0 mm	43.0 mm	
neel P	Z	5,0	NTBY	TL + 154.0 mm TL + 6.063 in	TPL+ 3.615 in	TPL + 2.323 in	1.694 in	
er Wh	S	1/2	NTBY	TL + 204.5 mm TL + 8.052 in	TPL+ 108.1 mm	TPL + 77.0 mm	57.0 mm	
Wip	3	5/8	BY	TL + 172.0 mm TL + 6.772 in	TPL+ 4.254 in	TPL + 3.031 in	2.244 in	
	4	B	BY	TL + 270.0 mm TL + 10.628 in	TPL+ 121.7 mm	TPL + 86.0 mm	69.0 mm	
	4	5/4	VHDY	TL + 296.6 mm TL + 11.677 in	TPL+ 4.792 in	TPL + 3.386 in	2.717 in	

Ball Screw Drive Systems



- Complete ball screw actuated linear system, ready for immediate installation
- Standard aluminum and steel support beam options available
- Two standard available wheel plate options
- Available in standard and corrosion-resistant versions
- Nut operating temperatures: 32°F - 200°F (0°C - 93°C)

- Accurate to 0.004 in./ft. (0.1 mm/300 mm)
- Standard NEMA and IEC motor mounts available
- Guide system constructed with DualVee Motion Technology[®]
- Maximum ball screw lengths: Size 2: 3,000 mm
 Size 3: 1,500 mm
 Size 4: 1,500 (for ø 16 mm)
 1,800 (for ø 20 mm)



CARRIAGE ASSEMBLY LOAD CAPACITIES										
System Size	Axial I Capa	Load city	Radial Load Capacity							
	N	lbs	N	lbs						
1	988	222	1166	262						
2S/2L	2449	551	2805	631						
3	6668	1499	6026	1355						
4	15682	3525	9220	2073						



LOPRO BALL SCREW THRUST CAPACITIES					
System Size	Screw Diameter	Maximum Length	Lead	Dynamica Load Capacity	
	mm	mm	mm	N	lbs
1	N/A	-	-	-	-
2	10	3000	2	1250	281.0
			3	2800	629.4
3	12	1500	5	2300	517.0
			10	1500	337.2
4	16	1500	5	5600	1258.9
			10	5800	1303.8
	20	1800	5	8600	1933.3


Note: Carriage starting positions may vary. Pictures do not necessarily represent the starting positions of all the ball screw systems, i.e. not all systems' starting positions have the carriage in intimate contact with the drive end housing as shown.



Beam Mounted Systems: Wiper Wheel Plate



	Size	Screw Dia.	Lead	Track Plate Length	System Length	Tube Length TBL	Carriage C	Height H	Systen	n Height SH
		mm	mm	TPL	SL	ALUMINUM/STEEL	ALUMINUM	STEEL	ALUMINUM	STEEL
		10	2	TL + 129.9 mm TL + 5.114 in	TPL + 91.8 mm	TPL + 59.0	73.0 mm	71.1 mm	83.2 mm	81.3 mm
e	2	10	3	TL + 129.9 mm TL + 5.114 in	TPL + 3.615 in	TPL + 2.323 in	2.874 in	2.799 in	3.276 in	3.201 in
I Plat	0	10	5	TL + 181.6 mm TL + 7.150 in	TPL + 108.1 mm	TPL + 77.0 mm	163.0 mm	93.8 mm	172.2 mm	103.1 mm
Whee	3	12	10	TL + 185.6 mm TL + 7.308 in	TPL + 4.254 in	TPL + 3.031 in	6.417 in	3.693 in	6.780 in	4.055 in
Viper		10	5	TL + 259.9 mm TL + 10.232 in	TPL + 121.7 mm	TPL + 86.0 mm	N/A	105.8 mm	N/A	119.4 mm
>	4	16	10	TL + 272.9 mm TL + 10.742 in						
		20	5	TL + 267.9 mm TL + 10.546 in	TPL + 4.792 in	TPL + 3.386 in	N/A	4.165 in	N/A	4.701 in

Beam-Mounted Systems: Basic Wheel Plate



	mm	mm	TPL	SL	ALUMINUM/STEEL	ALUMINUM	STEEL
0	10	2	TL + 131.9 mm TL + 5.193 in	TPL+ 91.8 mm	TPL + 59.0 mm	83.0 mm	81.1 mm
2	10	3	TL + 151.9 mm TL + 5.981 in	TPL+ 3.615 in	TPL + 2.323 in	3.269 in	3.194 in
	10	5	TL + 172.0 mm TL + 7.356 in	TPL+ 108.1 mm	TPL + 77.0 mm	177.0 mm	107.8 mm
3	12	10	TL + 190.8 mm TL + 6.772 in	TPL+ 4.254 in	TPL + 3.031 in	6.968 in	4.244 in
	16	5	TL + 258.1 mm TL + 10.160 in	TPL+ 121.7 mm	TPL + 86.0 mm	N/A	119.8 mm
4			TL + 10.711 in				
	20	5	TL + 266.0 mm TL + 10.474 in	TPL+ 4.792 in	TPL + 3.386 in	N/A	4.717 in
	2 3 4	mm 2 10 3 12 4 16 20	mm mm 2 10 2 3 3 3 3 12 5 10 10 10 4 16 5 20 5 5	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

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Ball Screw Systems

Unmounted Systems: Wiper Wheel Plate

- Designed to be mounted to a customersupplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length
- System is shipped with temporary mounting plates affixing drive ends to track plate



	Size	Screw Dia.	Lead	Track Plate Length	System Length	Tube Length	Carriage Height	System Height
		mm	mm	TPL	SL	TBL	СН	SH
			2	TL + 129.9 mm TL + 5.114 in	TPL + 91.8 mm	TPL + 59.0 mm	33.0 mm	43.2 mm
e	2	10	3	TL + 129.9 mm TL + 5.114 in	TPL + 3.615 in	TPL + 2.323 in	1.299 in	1.701 in
el Plat		10	5	TL + 181.6 mm TL + 7.150 in	TPL + 108.1 mm	TPL + 77.0 mm	43.0 mm	52.2 mm
Whee	3	12	10	TL + 185.6 mm TL + 7.308 in	TPL + 4.254 in	TPL + 3.031 in	1.693 in	2.055 in
Viper		16	5	TL + 259.9 mm TL + 10.232 in	TPL + 121.7 mm	TPL + 86.0 mm	55.0 mm	68.6 mm
>	4	10	10	TL + 272.9 mm TL + 10.742 in				
		20	5	TL + 267.9 mm TL + 10.546 in	TPL + 4.792 in	TPL + 3.386 in	2.165 in	2.701 in

Unmounted Systems: Basic Wheel Plate

- Designed to be mounted to a customer-supplied mounting surface
- System straightness and flatness is determined by mounting surface accuracy
- System is designed for continuous support along entire track plate length
- System is shipped with temporary mounting plates affixing drive ends to track plate





Screw Dia. Track Plate System Base Carriage Height/ System Length Size Lead Length Length System Height mm mm SL SBL TPL CH/SH TL +131.9 mm 2 TPL + 91.8 mm TPL + 59.0 43.0 mm mm TL + 5.193 in 2 10 TL +151.9 mm 3 TPL + 3.615 in TPL + 2.323 in 1.694 in TL + 5.980 in Wiper Wheel Plate TL +172.0 mm 5 TPL +108.1 mm TPL + 77.0 mm 57.0 mm TL + 7.354 TL +190.8 in 3 12 mm 10 TPL + 4.254 in TPL + 3.031 in 2.244 in TL + 6.772 in TL +258.1 mm 5 TL + 10.161 in TPL +121.7 mm TPL + 86.0 69.0 mm mm 16 TL +272.1 mm 4 10 TL + 10.713 in TL +266.0 2.717 in mm TPL + 4.792 in TPL + 3.386 in 20 5 TL + 10.472 in

Ordering - General Codes



Examples	1	2	3	4	5	6	7	Travel Length	Shaft Pos.	Description
1	LP	1	W	С	D	A	CR	2500 mm	L	LP1WCDACR, 2500mm ⁺ , L** LoPro Size 1, Wiper Wheel Plate Chain Drive System with Dual Drive Shaft, on an Aluminum Support Beam, Corrosion Resistant Components, 2500 mm carriage travel Shaft Position Left
2	LP	2	BL	LS	3GB	S	(blank)	24 in.	-	LP2BLLS3GBS, 24 inches [•] LoPro Size 2, Basic Wheel Plate with Track Lubricator, Lead Screw Drive System, 3/8" x 5.0mm BY NUT, on a Steel Support Beam, 24 inch carriage travel

* Length denotes carriage travel, which is used to calculate track plate length and overall system length. Refer to the appropriate system drive option section for details.

** "L" or "R" designations applicable only for belt or chain driven systems.



WHEN ORDERING SINGLE DRIVE SHAFT SYSTEMS, INDICATE DESIRED POSITION* OF DRIVE SHAFT, L OR R.

*Note:

 ${\bf L}$ indicates drive input on the left hand side as seen from the drive end ${\bf R}$ indicates drive input on the right hand side as seen from the drive end

Lead Screw Configuration Code

	Configuration Code, [XXX]	2CB	2CN	2IB	2IN				
SIZE 1	DESCRIPTION	1/4" x 2.0mm BY NUT	1/4" x 2.0mm NT BY NUT	1/4" x 10.0mm BY NUT	1/4" x 10.0mm NTBY NUT				
	Configuration Code, [XXX]	3GB	3GN	3JB	3JN	3PB	3PN		
SIZE 2	DESCRIPTION	3/8" x 5.0mm BY NUT	3/8" x 5.0mm NTBY NUT	3/8" x 12.0mm BY NUT	3/8" x 12.0mm NTBY NUT	3/8" x 25.0mm BY NUT	3/8" x 25.0mm NTBY NUT		
	Configuration Code, [XXX]	4GN	4IN	4PN	5GB	5LB		-	
SIZE 3	DESCRIPTION	1/2" x 5.0mm NTBY NUT	1/2" x 10.0mm NTBY NUT	1/2" x 25.0mm NTBY NUT	5/8" x 8.0mm BY NUT	5/8" x 16.0mm BY NUT			
	Configuration Code, [XXX]	6GB	6GV	6IB	6IV	60B	60V	6QB	6QV
SIZE 4	DESCRIPTION	3/4" x 5.0mm BY NUT	3/4" x 5.0mm VHDY NUT	3/4" x 10.0mm BY NUT	3/4" x 10.0mm VHDY NUT	3/4" x 24.0mm BY NUT	3/4" x 24.0mm VHDY NUT	3/4" x 50.0mm BY NUT	3/4" x 50.0mm VHDY NUT

Ball Screw Configuration Code

	Configuration Code, [XXX]	CCN	CEN	
SIZE 2	DESCRIPTION	10mm x 2.0mm Non Preloaded Nut	10mm x 3.0mm Non Preloaded Nut	
	Configuration Code, [XXX]	DGN	DIN	
SIZE 3	DESCRIPTION	12mm x 5.0mm FEM-E-B Mod. Flange Non Preloaded Nut	12mm x 10.0mm FEM-E-B Mod. Flange Non Preloaded Nut	
	Configuration Code, [XXX]	GGN	GIN	HGN
SIZE 4	DESCRIPTION	16mm x 5.0mm FEM-E-B Mod. Flange Non Preloaded Nut	16mm x 10.0mm FEM-E-B Mod. Flange Non Preloaded Nut	20mm x 5.0mm FEM-E-B Mod. Flange Non Preloaded Nut



Wheel Plate Options

Wiper Wheel Plates



- Wheels are captured via low profile bushings on both sides of the guide wheel for maximum system stiffness
- Wheels are completely enclosed minimizing the affect of contamination
- Offers lowest profile envelope

Basic Wheel Plates



- Available in four sizes (1, 2, 3, & 4)
- Options include lubricators and wheel covers, both of which distribute lubricant along the vee ways via oil-saturated felt inserts
- Wheel covers provide extra protection from contaminants at the wheel/track interface

Wheel Plates: Wiper-Style

- Pre-assembled carriage plate with lubricating wiper caps
- Includes four DualVee[®] guide wheels and stainless steel low profile bushings and mounting hardware
- LoPro[®] carriage assemblies come standard with sealed 52100 or 440C stainless steel, and high temperature or clean room compatible wheels



Size	Part Number	Ove Len	rall gth	Ove Wio	rall dth	Wheel Asse Hei	Plate mbly ght	Whee Hei	l Plate ght	Mounti Len	ng Hole Igth	Mounti Wi	ng Hole dth	Mounti Leng	ing Hole gth 2
		L		٧	V	A	Н	ŀ	ł	LM	IH1	WN	/IH1	LN	1H2
1		94.0	mm	78	mm	18.5	mm	16.5	mm	-	-	50.0	mm	50.0	mm
	IVITAVVPVV	3.70	in	3.07	in	0.730	in	0.650	in	-	-	1.969	in	1.969	in
2		129.8	mm	115.3	mm	26.4	mm	23.3	mm	30.0	mm	76.0	mm	76.0	mm
2	IVIZAVVPVV	5.11	in	4.54	in	1.041	in	0.916	in	1.181	in	2.992	in	2.992	in
2		177.5	mm	161.8	mm	35.6	mm	30.3	mm	38.0	mm	100.0	mm	100.0	mm
3	IVIJAVVPVV	6.99	in	6.37	in	1.403	in	1.193	in	1.496	in	3.937	in	3.937	in
4		243.8	mm	213.1	mm	45.7	mm	39.4	mm	66.0	mm	152.0	mm	152.0	mm
4	IVI4AVVPVV	9.60	in	8.39	in	1.798	in	1.553	in	2.598	in	5.984	in	5.984	in

Size	Part Number	Mountii Wid	ng Hole th 2	Mounting Hole Thread	Whee Spa Len	l Bolt cing gth	Whee Spacin	el Bolt g Width	Vee I	leight	Cou Mounti Hei	ıpler ing Hole ight	Cou Attac Feat Maxi Diar	upler hment ture - imum neter
		WIV	1H2	MBH	WE	SL	WB	SW	V	Н	CI	ИН	A	٨P
1		25.0	mm		50.8	mm	53.3	mm	9.5	mm	7.1	mm	11.0	mm
1	IVITAVVPVV	0.984	in	1014 × .7	2.000	in	2.098	in	0.374	in	0.281	in	0.433	in
2		38.0	mm		76.2	mm	80.0	mm	14.0	mm	10.7	mm	17.0	mm
2	IVIZAVVPVV	1.496	in	1016 × 1.0	3.000	in	3.150	in	0.550	in	0.422	in	0.669	in
2		50.0	mm		101.6	mm	109.2	mm	18.0	mm	14.1	mm	22.0	mm
3	IVI3AVVPVV	1.969	in	IVI8 X 1.25	4.000	in	4.300	in	0.709	in	0.556	in	0.866	in
1		66.0	mm	M10 V 1 F	152.4	mm	146.7	mm	24.0	mm	19.3	mm	32.0	mm
4	IVI4AVVPVV	2.598	in	10110 × 1.5	6.000	in	5.774	in	0.945	in	0.758	in	1.260	in

Wheel Plates: Basic

Basic Wheel Plate	Dual Vee Size	Coupler Mounting Hole Length	Coupl Mount Hole Descript	er ing tion	Co M Ho E	oupler lount ble to dge	Coupl Moui Hole Widt	ler nt e :h						
Profile		LCMH	СМН	1	E	СМН	WCM	IH						
	1	0.394 (10.0 mm)	0.090 th 0.173 Ø C'BORE	и Ø x 0.080 DP	0 (6.0	.236 0 mm)	0.55´ (14.0 m	1 nm)						
	0	0.709	0.161 thr	υØ	0	.394	0.944	4						
Standard	2	(18.0 mm)	0.290 Ø C'BORE	x 0.170 DP	(10.	0 mm)	(24.0 m	nm)						
Height	2	0.709	0.177 thr	υØ	0	.394	1.260)						
	3	(18.0 mm)	0.325 Ø C'BORE	x 0.157 DP	(10.	0 mm)	(32.0 m	nm)						
	4	0.866	0.256 th	υØ	0	.472	2.047	7						
	4	(22.0 mm)	0.430 Ø C'BORE	x 0.236 DP	(12.	0 mm)	(52.0 m	nm)						
	1	0.394	0.090 th	υØ	0	.236	0.55	1						
	'	(10.0 mm)	0.173 Ø C'BORE	x 0.080 DP	(6.0) mm)	(14.0 m	nm)						
	2	0.709	0.161 thr	υØ	0	.394	0.944	4						
Low	-	(18.0 mm)	0.290 Ø C'BORE	x 0.170 DP	(10.	0 mm)	(24.0 m	nm)						
Profile	3	0.709	0.177 thr	υØ	0	.394	1.260)						
		(18.0 mm)	0.325 Ø C'BORE	x 0.157 DP	(10.	0 mm)	(32.0 m	nm)						
	4	0.866	0.256 th	υØ	0	.472	2.047	7						
		(22.0 mm)	0.430 Ø C'BORE	x 0.236 DP	(12.	0 mm)	(52.0 m	nm)						
Basic	Dual	Port	Overall	Overa		Whee	l Plate	10/	eeol Dio	e a l Diat	haal Diata	haal Diata	a al Diata	easl Plata





Basic Wheel Plate	Dual Vee Size	Part Number 1	Overa Lengt	ıll :h	Over Widt	all th	Wheel I Assem Heig	Plate Ibly ht	Wheel I Heig	Plate ht	Wheel Heig	Vee ht	Wheel Spac Leng	Bolt e th	Wheel Spac Widt	Bolt e h	Wheel Bolt Thread
Profile			L		w		AH		н		VH		WBS	L	WBS	W	WBT
	1	BWP1_DV	90.0 3.54	mm in	80.0 3.150	mm in	24.6 0.970	mm in	8.5 0.333	mm in	18.2 0.718	mm in	50.8 2.000	mm in	53.3 2.098	mm in	M4 X 0.7
Standard	2	BWP2_DV	127.0 5.00	mm in	116.0 4.57	mm in	34.0 1.340	mm in	11.8 0.465	mm in	24.0 0.946	mm in	76.2 3.000	mm in	80.0 3.150	mm in	M6 X 1.0
Height	3	BWP3_DV	172.0 6.77	mm in	165.0 6.50	mm in	46.8 1.844	mm in	14.6 0.574	mm in	32.0 1.260	mm in	101.6 4.000	mm in	109.2 4.300	mm in	M8 X 1.25
	4	BWP4_DV	242.0 9.53	mm in	222.0 8.740	mm in	55.6 2.187	mm in	17.3 0.683	mm in	38.0 1.495	mm in	152.4 6.000	mm in	146.7 5.774	mm in	M10 X 1.5
	1	BWP1_LP	90.0 3.543	mm in	80.0 3.150	mm in	20.5 0.808	mm in	8.5 0.333	mm in	14.1 0.556	mm in	50.8 2.000	mm in	53.3 2.098	mm in	M4 X 0.7
Low	2	BWP2_LP	127.0 5.000	mm in	116.0 4.57	mm in	30.0 1.182	mm in	11.8 0.465	mm in	20.0 0.788	mm in	76.2 3.000	mm in	80.0 3.150	mm in	M6 X 1.0
Profile	3	BWP3_LP	172.0 6.772	mm in	165.0 6.50	mm in	40.8 1.608	mm in	14.6 0.574	mm in	26.0 1.024	mm in	101.6 4.000	mm in	109.2 4.300	mm in	M8 X 1.25
	4	BWP4_LP	242.0 9.53	mm in	222.0 8.74	mm in	47.5 1.872	mm in	17.3 0.683	mm in	30.0 1.180	mm in	152.4 6.000	mm in	146.7 5.774	mm in	M10 X 1.5

Basic Wheel Plate	Dual Vee Size	Part Number	Mountin Leng	g Hole th	Mountin Wid	g Hole th	Mountin Leng	g Hole th 2	Mountin Widt	g Hole h 2	Mounting Hole Thread
Profile		1.	LMF	11	wM	H1	LM	12	WM	H2	МНТ
	1	BWP1_DV	-	- -	50.0 1.969	mm in	50.0 1.969	mm in	25.0 0.984	mm in	M4 X 0.7
Standard	2	BWP2_DV	25.0 0.984	mm in	76.0 2.992	mm in	76.0 2.992	mm in	38.0 1.496	mm in	M6 X 1.0
Height	3	BWP3_DV	35.0 1.378	mm in	100.0 3.937	mm in	100.0 3.937	mm in	50.0 1.969	mm in	M8 X 1.25
	4	BWP4_DV	56.0 2.205	mm in	152.0 5.984	mm in	152.0 5.984	mm in	66.0 2.599	mm in	M10 X 1.5
	1	BWP1_LP	-	-	50.0 1.969	mm in	50.0 1.969	mm in	25.0 0.984	mm in	M4 X 0.7
Low	2	BWP2_LP	25.0 0.984	mm in	76.0 2.992	mm in	76.0 2.992	mm in	38.0 1.496	mm in	M6 X 1.0
Profile	3	BWP3_LP	35.0 1.378	mm in	100.0 3.937	mm in	100.0 3.937	mm in	50.0 1.969	mm in	M8 X 1.25
	4	BWP4_LP	56.0 2.205	mm in	152.0 5.984	mm in	152.0 5.984	mm in	66.0 2.599	mm in	M10 X 1.5

Note: Low profile carriages are for non-driven systems only.



AL	ALUMINUM BEAMS								
System Size	Material								
1									
2S	6061-T6 Aluminum Allov								
2L									
3									
4	N/A								

t	
HEIGHT	0 0
•	
	WIDTH



	STEEL BEAMS
System Size	Material
All Sizes, All	Structural Steel Tubing,
Drive Options	ASTM A500 Grade A

	Alum	inum	Steel												
Size	All Drive Co	nfigurations	Belt/Cha	ain Drive	Lead Scr	ew Drive	Ball Scre	w Drive							
	Width	Height	Width	Height	Width	Height	Width	Height							
1 N/A for	80.0 mm	40.0 mm	63.5 mm	.5 mm 38.1 mm 63.5 mm		38.1 mm N/A		N/A							
Ball Screw Drive	3.150 in	1.575 in	2.50 in	1.50 in	2.50 in	1.50 in	N/A	N/A							
2 Lead/Ball	100.0 mm	40.0 mm	N/A	N/A	76.2 mm	38.1 mm	76.2 mm	38.1 mm							
Screw	3.937 in	1.575 in	N/A	N/A	3.00 in	1.50 in	3.00 in	1.50 in							
2S	100.0 mm	40.0 mm	76.2 mm	38.1 mm	N/A	N/A	N/A	N/A							
Belt/Chain	3.937 in	1.575 in	3.00 in	1.50 in	N/A	N/A	N/A	N/A							
2L	100.0 mm	80.0 mm	76.2 mm	76.2 mm	N/A	N/A	N/A	N/A							
Belt/Chain	3.937 in	3.150 in	3.00 in	3.00 in	N/A	N/A	N/A	N/A							
2	120.0 mm	120.0 mm	127.0 mm	101.6 mm	127.0 mm	50.8 mm	127.0 mm	50.8 mm							
5	4.724 in	4.724 in	5.00 in	4.00 in	5.00 in	2.00 in	5.00 in	2.00 in							
4	N/A	N/A	152.4 mm	101.6 mm	152.4 mm	50.8 mm	152.4 mm	50.8 mm							
	N/A	N/A	6.00 in	4.00 in	6.00 in	2.00 in	6.00 in	2.00 in							

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Support Beams

Aluminum Beam Properties

Size	Beam Cross Section	Part Number	Cross- Sectional Area	Moment of Inertia X-Axis	Moment of Inertia y-Axis	LoPro T-Slot A	T-Slot B	T-Slot C	Max Length
1		LP1SBEXTLP	66.9 mm² 2.62 in²	2.776E+05 mm⁴ 0.67 in⁴	1.016E+06 mm⁴ 2.44 in⁴	40.0 mm 1.575 in	N/A	40.0 mm 1.575 in	5.6 m (18.37 ft)
2S		LP2SSBEXT	83.9 mm² 3.30 in²	3.505E+05 mm⁴ 0.84 in⁴	1.773E+06 mm⁴ 4.26 in⁴	59.0 mm 2.322 in	N/A	60.0 mm 2.362 in	5.6 m (18.37 ft)
2L		LP2LSBEXT	106.2 mm² 4.18 in²	2.137E+06 mm⁴ 5.13 in⁴	2.974E+06 mm⁴ 7.15 in⁴	59.0 mm 2.322 in	40.0 mm 1.575 in	60.0 mm 2.362 in	5.6 m (18.37 ft)
3		LP3SBEXT	202.6 mm² 8.01 in²	8.537E+06 mm⁴ 20.51 in⁴	8.490E+06 mm⁴ 20.40 in⁴	81.0 mm 3.190 in	40.0 mm 1.575 in	80.0 mm 3.150 in	5.6 m (18.37 ft)

Notes

- · Aluminum support beams are designed with industry standard cross section and t-slot (10 mm) geometry.
- Beams are compatible with BWC's MCS Aluminum frame and machine construction system as well as other industry standard offerings.
- TNuts and other accessories are also available (refer to BWC MCS's catalog for detailed accessory specifications).

Support Beams

Steel Beam Properties



Support Beams

Steel Beam Properties, continued

Size	Beam Cross Section	Part Number	Cross- Sectional Area	Moment of Inertia X-Axis	Moment of Inertia y-Axis	Max Length
	у ————————————————————————————————————	L P4BSB	116.6 mm²	4.885E+06mm⁴	9.187E+06 mm⁴	14.6 m
			4.59 in²	11.74 in4	22.07 in⁴	(48 Ft.)
4	y	LP4LSBS	68.7 mm²	7.709E+05 mm⁴	4.388E+06 mm⁴	14.6 m
		LP4SSB	2.71 in²	1.85 in4	10.54 in4	(48 Ft.)

Fit-up Adjustment Wrenches

- Eccentric adjustment mounting tools
- Includes bushing wrench and wheel bolt wrench for each wheel plate size (1, 2, 3, and 4)
- Allows for fit-up adjustment between opposing wheels by rotating eccentric bushing







Wrench	Size	Part	Wrenc	h Size	Ler	igth	Thickness			
Туре		Number	Н	w		L	ТК			
	1	1PW/BB	5.6	mm	101.3	mm	2.3	mm		
	1		0.220	in	3.99	in	0.09	in		
	2	2P\\/BB	8.7	mm	114.3	mm	3.0	mm		
Wheel	Z	21 0 0110	0.344	in	4.50	in	0.12	in		
Bolt	2	3D\\/BB	11.2	mm	127.0	mm	3.4	mm		
	5		0.440	in	5.00	in	0.14	in		
	4		12.8	mm	138.9	mm	3.4	mm		
	4	41 00110	0.503	in	5.47	in	0.14	in		
	1	1 P\\/BY	11.2	mm	101.6	mm	1.9	mm		
	1 1		0.439	in	4.00	in	0.07	in		
	2	2P\\/BY	14.3	mm	114.3	mm	2.3	mm		
Eccentric	2	21 0 011/1	0.564	in	4.50	in	0.09	in		
Bushing	2	3D\\/BX	19.1	mm	129.5	mm	3.0	mm		
	5		0.752	in	5.10	in	0.12	in		
	Δ		22.3	mm	147.3	mm	3.0	mm		
	4		0 877	in	5.80	in	0.12	in		



Motor Mounts

- Designed to adapt standard NEMA frame motors to LoPro Linear Systems
- Standard motor mounts include NEMA sizes 17, 23, 34, and 42
- Other motor faces can be accommodated; consult factory

MOTO	R MOUNTS
System Size	Material
All Sizes, All Drive Options	Low Carbon Steel

		M	OTOR MOUNT A	VAILABILITY MA	TRIX		
C !	Part		Lead/Ball		Moto	or Size	
Size I 1 N 2 N 2S N 2L I	Number	Beit/Chain	Screw	NEMA 17	NEMA 23	NEMA 34	NEMA 42
	M1PMMM17						
	M1PMMM23						
1	M1PMMLS17						
2 2S	M1PMMLS23						
2	M2PMMLS23						
26	M2PMMM23						
25	M2PMMM34						
21	M2PMMG23						
ZL	M2PMMG34						
	M3PMMG23						
	M3PMMG34						
3	M3PMMG42						
	M3PMMLS23						
	M3PMMLS34						
	M4PMMG34						
	M4PMMG42						
4	M4PMMLS34						
	M4PMMLS42						





Note: Please contact BWC for motor mounts for use with IEC motors.

	MOTOR MOUNT DIMENSIONS														
Compatibility	Part Number	0	AL	WI	NW	WI	NH	W	INL	F	н	F	W	F	т
Companionity		mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in
1 B/C TO NEMA 17	M1PMMM17	64.5	2.54	31.8	1.25	26.9	1.06	16.5	0.65	44.5	1.75	44.5	1.75	5.8	0.23
1 B/C TO NEMA 23	M1PMMM23	71.9	2.83	38.1	1.50	15.2	0.60	19.1	0.75	57.2	2.25	57.2	2.25	5.8	0.23
2 SMALL B/C TO NEMA 23	M2PMMM23	78.2	3.08	43.2	1.70	22.9	0.90	20.3	0.80	57.2	2.25	57.2	2.25	5.8	0.23
2 SMALL B/C TO NEMA 34	M2PMMM34	106.2	4.18	48.3	1.90	22.9	0.90	25.2	0.99	82.8	3.26	82.8	3.26	5.8	0.23
2 LARGE B/C TO NEMA 23	M2PMMG23	77.0	3.03	35.6	1.40	25.4	1.00	25.4	1.00	57.2	2.25	57.2	2.25	5.8	0.23
2 LARGE B/C TO NEMA 34	M2PMMG34	89.7	3.53	50.8	2.00	25.4	1.00	25.4	1.00	82.8	3.26	82.8	3.26	5.8	0.23
3 B/C TO NEMA 23	M3PMMG23	98.6	3.88	50.8	2.00	25.4	1.00	34.3	1.35	57.2	2.25	57.2	2.25	5.8	0.23
3 B/C TO NEMA 34	M3PMMG34	108.7	4.28	63.5	2.50	31.8	1.25	28.6	1.13	82.8	3.26	82.8	3.26	5.8	0.23
3 B/C TO NEMA 42	M3PMMG42	110.5	4.35	63.5	2.50	31.8	1.25	28.6	1.13	108.0	4.25	108.0	4.25	7.6	0.30
4 B/C TO NEMA 34	M4PMMG34	108.7	4.28	63.5	2.50	31.8	1.25	28.6	1.13	82.8	3.26	82.8	3.26	5.8	0.23
4 B/C TO NEMA 42	M4PMMG42	110.5	4.35	63.5	2.50	31.8	1.25	28.6	1.13	108.0	4.25	108.0	4.25	7.6	0.30
1 LS, BS TO NEMA 17	M1PMMLS17	51.8	2.04	31.8	1.25	12.7	0.50	10.1	0.40	44.5	1.75	44.5	1.75	5.8	0.23
1 LS, BS TO NEMA 23	M1PMMLS23	61.2	2.41	31.8	1.25	13.2	0.52	15.2	0.60	57.2	2.25	57.2	2.25	5.8	0.23
2 LS, BS TO NEMA 23	M2PMMLS23	68.8	2.71	38.1	1.50	15.2	0.60	16.0	0.63	57.2	2.25	57.2	2.25	5.8	0.23
3 LS, BS TO NEMA 23	M3PMMLS23	77.0	3.03	43.2	1.70	22.9	0.90	19.1	0.75	57.2	2.25	57.2	2.25	5.8	0.23
3 LS, BS TO NEMA 34	M3PMMLS34	83.3	3.28	38.1	1.50	15.2	0.60	25.4	1.00	82.8	3.26	82.8	3.26	5.8	0.23
4 LS, BS TO NEMA 34	M4PMMLS34	89.7	3.53	50.8	2.00	31.8	1.25	19.1	0.75	82.8	3.26	82.8	3.26	5.8	0.23
4 LS, BS TO NEMA 42	M4PMMLS42	91.4	3.60	50.8	2.00	31.8	1.25	19.1	0.75	108.0	4.25	108.0	4.25	7.6	0.30

	MOTOR INTERFACE FLANGE													
Compatibility	Part Number	FIV	IHH	FM	HW	FIV	IHD	F	СВ	FC	3DP	FTH		Í.
companies inty	T are realised	mm	in	mm	in	mm	in	mm	in	mm	in	mm	in	(
1 B/C TO NEMA 17	M1PMMM17	31.0	1.220	31.0	1.220	3.5	0.136	22.0	0.866	2.0	0.080	20.6	0.810	
1 B/C TO NEMA 23	M1PMMM23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	26.9	1.060	
2 SMALL B/C TO NEMA 23	M2PMMM23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	34.9	1.375	
2 SMALL B/C TO NEMA 34	M2PMMM34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	34.9	1.375	
2 LARGE B/C TO NEMA 23	M2PMMG23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	34.9	1.375	
2 LARGE B/C TO NEMA 34	M2PMMG34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	41.3	1.625	1
3 B/C TO NEMA 23	M3PMMG23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	34.9	1.370	
3 B/C TO NEMA 34	M3PMMG34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	50.8	2.000	1
3 B/C TO NEMA 42	M3PMMG42	88.9	3.500	88.9	3.500	8.6	0.339	55.5	2.186	2.0	0.080	50.8	2.000	
4 B/C TO NEMA 34	M4PMMG34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	50.8	2.000	
4 B/C TO NEMA 42	M4PMMG42	88.9	3.500	88.9	3.500	8.6	0.339	55.5	2.186	2.0	0.080	50.8	2.000	Note:
1 LS, BS TO NEMA 17	M1PMMLS17	31.0	1.220	31.0	1.220	3.5	0.136	22.0	0.866	2.0	0.080	20.6	0.810	1. "B/C" =
1 LS, BS TO NEMA 23	M1PMMLS23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	20.6	0.812	Belt/
2 LS, BS TO NEMA 23	M2PMMLS23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	26.9	1.060	Chain
3 LS, BS TO NEMA 23	M3PMMLS23	47.1	1.856	47.1	1.856	5.1	0.201	38.1	1.500	1.9	0.075	34.9	1.375	2. "LS" =
3 LS, BS TO NEMA 34	M3PMMLS34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	34.9	1.375	Screw
4 LS, BS TO NEMA 34	M4PMMLS34	69.6	2.740	69.6	2.740	5.6	0.221	73.0	2.875	1.9	0.075	50.8	2.000	3. "BS" =
4 LS, BS TO NEMA 42	M4PMMLS42	88.9	3.500	88.9	3.500	8.6	0.339	55.5	2.186	2.0	0.080	50.8	2.000	Ball Screw

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Technical Specifications

Drive Ends

Belt/Chain Systems



Lead/Ball Screw Systems

Fixed End Assembly



Simple End Assembly



DEL

MHDWR

MHW

Drive Ends: Belt/Chain Systems

- Designed for high performance, high cycling linear motion
- Incorporates high quality radial bearings with a high strength aircraft grade aluminum housing
- Keyed shaft and pulley arrangement provides rigid, accurate linear motion







	Size Part Number		Drive F	Drive End Drive End		Drive F	nd	B	оттс	M VIEW								
Size			Length		Width		Height		Sha Leng	Shaft S Length Di		Shaft Diameter		Square Key			DE2	
			DEL		DEV	V	DEH		SHF	SHFTL		ΓD	SHFTK		1			
1	LP1BDE	(BELT)	76.2	mm	50.0	mm	38.0	mm	29.7	mm	9.0	mm	3	mm	30.0	mm	16.0	mm
, '	LP1CDE	(CHAIN)	2.999	in	1.969	in	1.496	in	1.171	in	0.354	in	5		1.181	in	0.630	in
25	LP2SBDE	(BELT)	95.2	mm	72.0	mm	60.0	mm	36.6	mm	12.0	mm	4	mm	40.0	mm	27.5	mm
25	LP2SCDE	(CHAIN)	3.748	in	2.835	in	2.362	in	1.442	in	0.472	in	4	111111	1.575	in	1.083	in
21	LP2LBDE	(BELT)	141.2	mm	80.0	mm	100.0	mm	43.3	mm	15.0	mm	Б	mm	40.0	mm	68.0	mm
ZL	LP2LCDE	(CHAIN)	5.558	in	3.150	in	3.937	in	1.703	in	0.591	in	5	111111	1.575	in	2.677	in
2	LP3BDE	(BELT)	173.2	mm	102.0	mm	120.0	mm	52.4	mm	16.0	mm	5		52.0	mm	77.4	mm
3	LP3CDE	(CHAIN)	6.818	in	4.016	in	4.724	in	2.062	in	0.630	in	5	111111	2.047	in	3.046	in
4	LP4BDE	(BELT)	183.2	mm	140.0	mm	128.0	mm	51.7	mm	20.0	mm	6		54.0	mm	75.0	mm
4	LP4CDE	(CHAIN)	7.212	in	5.512	in	5.039	in	2.034	in	0.787	in	6	mm	2.126	in	2.953	in

Size	Mounting Hardware	Mounting Hole Width	Mounting Hole Edge Spacing	Mounting Hole Length	Mounting Hole Bolt Circle Diameter	Pilot Diameter	Motor Mount Mounting Hole Thread	Secondary Mounting Hole Width	Secondary Mounting Hole Length	Secondary Mounting Hole Edge Spacing	Secondary Mounting Hole Thread
	MHDWR	MHW	MHE	MHL	МНВС	PD	MHTHD	SMHW	SMHL	SMHE	SMHTHD
1	M3 x 22 mm	40.0 mm	6.0 mm	18.0 mm	42.4 mm	24.0 mm	$M4 \times 7$	42.0 mm	_	30.0 mm	$M4 \times 7$
	MIN	1.575 in	.236 in	.709 in	1.669 in	.945 in	IVI4 X .7	1.654 in	-	1.181 in	IV14 X .7
25	M5 x 30 mm	59.0 mm	10.0 mm	20.0 mm	50.9 mm	28.4 mm	MEXQ	60.0 mm		30.0 mm	MEXQ
23	MIN	2.323 in	.394 in	.787 in	2.004 in	1.102 in	1VIJ X .0	2.362 in	-	1.181 in	O. X CIVI
21	M5 x 35 mm	59.0 mm	10.0 mm	20.0 mm	67.9 mm	42.4 mm	M6 x 10	60.0 mm	54.0 mm	19.0 mm	MEVO
ZL	MIN	2.323 in	.394 in	.787 in	2.673 in	1.654 in		2.362 in	2.126 in	.748 in	O. X CIVI
2	M6 x 45 mm	81.0 mm	13.0 mm	26.0 mm	87.7 mm	47.0 mm		80.0 mm	58.0 mm	27.0 mm	
3	MIN	3.189 in	.512 in	1.024 in	3.452 in	1.850 in	IVIO X 1.20	3.150 in	2.283 in	1.063 in	IVIO X 1.20
4	M8 x 55 mm	111.0 mm	13.5 mm	27.0 mm	90.5 mm	52.4 mm	M9 v 1 25	110.0 mm	64.0 mm	27.0 mm	M9 v 1 25
4	MIN	4.375 in	.532 in	1.063 in	3.564 in	2.047 in	IVIO X 1.25	4.331 in	2.520 in	1.063 in	IVIO X 1.25

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Idler Ends: Belt/Chain Systems

- Belt and chain tensioning is easily accomplished via rotation of single, easy-to-access fastener
- High quality radial bearings and high strength aluminum housing provides smooth, accurate linear motion





						OM VIEW		_				
Size	Part Numb	er	Idler End	Length	Idler End	Width	Idler End	Height	IE1 and	I IE2	Shaft Dia	meter
			IEL		IEW	1	IEł	-			SHF	D
1	LP1BIE (BI	BELT)	97.4	mm	50.0	mm	38.0	mm	30.0	mm	16.0	mm
	LP1CIE (CH	HAIN)	3.834	in	1.969	in	1.496	in	1.181	in	0.630	in
2S	LP2SBIE (BI	BELT)	132.4	mm	72.0	mm	60.0	mm	40.0	mm	27.5	mm
	LP2SCIE (CH	HAIN)	5.212	in	2.835	in	2.362	in	1.575	in	1.083	in
2L	LP2LBIE (BI	BELT)	176.9	mm	80.0	mm	100.0	mm	40.0	mm	68.0	mm
	LP2LCIE (CH	HAIN)	6.964	in	3.150	in	3.937	in	1.575	in	2.677	in
З	LP3BIE (BI	BELT)	226.9	mm	102.0	mm	120.0	mm	52.0	mm	77.4	mm
	LP3CIE (CH	HAIN)	8.933	in	4.016	in	4.724	in	2.047	in	3.046	in
4	LP4BIE (BI	BELT)	257.7	mm	140.0	mm	128.0	mm	54.0	mm	75.0	mm
	LP4CIE (CH	HAIN)	10.146	in	5.512	in	5.039	in	2.126	in	2.953	in

Size	Mounting Hardware	Mounting Hole Width	Mounting Hole Edge Spacing	Mounting Hole Length	Hex Head Adjustment Screw	Secondary Mounting Hole Width	Secondary Mounting Hole Length	Secondary Mounting Hole Edge Spacing	Secondary Mounting Hole Thread
	MHDWR	MHW	MHE	MHL	НХ	SMHW	SMHL	SMHE	SMHTHD
1	M3 x 22 mm	40.0 mm	6.0 mm	18.0 mm	1/4 in	42.0 mm	_	30.0 mm	M4 x 7
'	MIN	1.575 in	.236 in	.709 in	.,	1.654 in		1.181 in	NI4 X .7
25	M5 x 30 mm	59.0 mm	10.0 mm	20.0 mm	1/4 in	60.0 mm		30.0 mm	M5 v 8
25	MIN	2.323 in	.394 in	.787 in	1/ - 111	2.362 in	_	1.181 in	1013 × .0
21	M5 x 35 mm	59.0 mm	10.0 mm	20.0 mm	5/16 in	60.0 mm	54.0 mm	19.0 mm	M5 v 8
ZL	MIN	2.323 in	.394 in	.787 in	0/10/11	2.362 in	2.126 in	.748 in	1013 × .0
2	M6 x 45 mm	81.0 mm	13.0 mm	26.0 mm	5/16 in	80.0 mm	58.0 mm	27.0 mm	M9 v 1 25
5	MIN	3.189 in	.512 in	1.024 in	3/10/11	3.150 in	2.283 in	1.063 in	1010 X 1.25
1	M8 x 55 mm	111.0 mm	13.5 mm	27.0 mm	3/8 in	110.0 mm	64.0 mm	27.0 mm	
4	MIN	4.375 in	.532 in	1.063 in	5,0 11	4.331 in	2.520 in	1.063 in	IVIO X 1.20

Fixed Ends: Lead/Ball Screw Systems

- Designed for high performance, high cycling linear motion
- Incorporates high quality radial bearings with a high strength aircraft grade aluminum housing
- Employs a single double-row angular contact beaming (size 1 employs two radial ball bearings).
- Shaft Key Sizes (square keys)
 Sizes 1 and 2 - n/a
 Size 3 - 4 mm, 10 mm long
 Size 4 - 5 mm, 10 mm long







Size	Part Number	Fixed End Length	Fixed End Width	Fixed End Height	Fixed End Housing Length	Shaft Diameter	А	в	с	Mounting Hardware
		FEL	FEW	FEH	FEHL	SHFTD				RF
1	LP1LSCE	52.0 mm 2.048 in	50.8 mm 2.000 in	30.5 mm 1.200 in	30.0 mm 1.181 in	5.0 mm 0.197 in	6.0 mm 0.236 in	18.0 mm 0.709 in	40.0 mm 1.575 in	M3
2	LP2LSCE	72.0 mm 2.835 in	72.4 mm 2.850 in	43.2 mm 1.700 in	40.0 mm 1.575 in	6.0 mm 0.236 in	10.0 mm 0.394 in	20.0 mm 0.787 in	59.0 mm 2.323 in	M5
3	LP3LSCE	86.9 mm 3.422 in	101.6 mm 4.000 in	52.3 mm 2.060 in	52.0 mm 2.047 in	12.0 mm 0.472 in	13.0 mm 0.511 in	26.0 mm 1.024 in	81.0 mm 3.189 in	M6
4	LP4LSCE	89.0 mm 3.502 in	139.7 mm 5.500 in	68.6 mm 2.700 in	54.0 mm 2.126 in	15.0 mm 0.591 in	13.5 mm 0.531 in	27.0 mm 1.063 in	111.0 mm 4.370 in	M8

NOTE: Contact BWC Sales for bolt circle diameter and hole size.



Idler End: Lead/Ball Screw Systems

- High strength anodized aluminum housing and high quality Conrad style radial bearing provides simple end screw support
- Offers rigid, low profile lead or ball screw support







Size	Part Number	Simple End Length	Simple End Width	Simple End Height	А	В	Mounting Hardware
		SEL	SEW	SEH			RF
1	LP1LSCE	13.0 mm 0.512 in	50.8 mm 2.000 in	22.8 mm 0.896 in	7.0 mm 0.276 in	40.0 mm 1.575 in	M3
2	LP2LSCE	19.0 mm .748 in	72.4 mm 2.850 in	32.5 mm 1.280 in	9.0 mm 0.356 in	59.0 mm 2.323 in	M5
3	LP3LSCE	25.0 mm .984 in	101.6 mm 4.000 in	42.5 mm 1.673 in	9.3 mm 0.368 in	81.0 mm 3.189 in	M6
4	LP4LSCE	32.0 mm 1.260 in	139.7 mm 5.500 in	54.5 mm 2.146 in	13.5 mm 0.531 in	111.0 mm 4.370 in	M8

Track Plate Assemblies

- Provides the lowest profile linear guidance
- Induction-hardened, single edge track is available in either carbon steel or stainless steel
- Track plate assemblies are butt joinable for long stroke requirements
- Lightweight anodized aluminum substrate





Size	Part Number	Wid	th	Overall Height		Vee Height		Vee Width		Inner V	Vidth	Inner Depth	
		w		н		AH		AV	V	ТМ	/	TD	
1	M1ATP	50.0 1.969	mm in	15.9 0.625	mm in	13.5 0.532	mm in	37.4 1.473	mm in	12.7 0.500	mm in	9.3 0.365	mm in
2	M2ATP	72.0 2.835	mm in	22.2 0.873	mm in	19.0 0.748	mm in	54.6 2.150	mm in	20.3 0.799	mm in	12.9 0.508	mm in
3	M3ATP	102.0 4.016	mm in	29.4 1.156	mm in	25.0 0.985	mm in	71.1 2.799	mm in	25.9 1.020	mm in	15.8 0.622	mm in
4	M4ATP	140.0 5.512	mm in	36.6 1.440	mm in	31.0 1.222	mm in	95.8 3.773	mm in	39.4 1.550	mm in	22.9 0.900	mm in

Size	Part Number	Moui Hole \	nting Nidth	Mounti Length	ng Hole Spacing	Mounting Hardware
	Number	MF	IW	MI	нѕ	RF- Low Head Cap Screws
		40.0	mm	76.0	mm	M3
1	M1AIP	1.575	in	2.992	in	M3
	140 ATD	59.0	mm	126.0	mm	M5
2	MZATP	2.323	in	4.961	in	M5
2		81.0	mm	152.0	mm	M6
3	IVI3AI P	3.189	in	5.984	in	M6
1		111.0	mm	178.0	mm	M8
4	IVI4ATE	4.370	in	7.008	in	M8

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*ES = End Spacing; Dimension is contingent upon Track Plate Length.

In addition to the standard line of LoPro[®] linear system products, BWC's capabilities extend beyond these standard systems and into the realm of custom engineered products. Custom engineered solutions from BWC range from slight modifications made to standard systems to complete ground-up system designs using DualVee[®] components and / or linear guides.

Value added modifications and capabilities include but are not limited to:

Multi Axis Bracketry

LOPRO[®]Linear Motion Systems

- Limit Switches
- Shock Absorption
- Special Motor Adaptation
- Special Actuators / Drive End Supports
- Foot Mounts for Steel Support Beams

- Bellows
- Special Machining
- Rack or Cable Driven Solutions
- Special Track and Wheel Plate Designs
- Pneumatic Actuation

Custom engineered products are typically designed in collaboration with the customer's design team, taking into account the major design parameters including envelope restrictions, material considerations, accuracy, repeatability, thrust requirements, duty cycle, and service life objectives. Non-recurring engineering fees may apply depending on the level of customization involved. Typical projects entail varying levels of prototype sketching, detailing, and prototype design modification as the system specifications are refined. Prior to fabrication, prototype designs are formally detailed & documented for "sign-off" approval by the customer. JIT or Kanban-type arrangements can be accommodated for custom engineered OEM requirements.





Screw driven LoPro[®] systems with custom designed wheel plates and drive ends. Units were modified so as to provide the necessary stroke length within a compact over-all length envelope. Drive ends were simplified to reduce cost and save space. Wheel plate assemblies use size 0 DualVee[®] guide wheels used with size/track plate assemblies. Systems are used in a laboratory grade biomedical analysis application to transport samples through an automated test process.



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This system is comprised of linear guidance elements built from our QuickTrak[®] product line. QuickTrak[®] employs an aluminum double edge track and a carriage assembly built with high performance polymer wheels. Polymer wheels are supported by a double row, stainless steel, radial bearing arrangement. Polymer wheel technology offers the advantages of very smooth motion, inherent corrosion resistance, and low cost.

Notes



Technical Reference



Pneumatically loaded test rig used to quantify load vs. service life in a DualVee®-based linear guidance system. Test stand is designed to assess the load / life relationship of two discrete products including the belt driven UtiliTrak® system (below) and an unactuated SW series guide (above).

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Load/Life Relationship

When considering the service life of a LoPro[®] linear motion system, one must consider two discrete calculations. First is the load / life relationship of the linear bearing system; second is the service life of the actuator and drive end supports under the applicable load / velocity profile and duty cycle.

Several factors will influence the service life of the linear bearing in a LoPro[®] system. Through research and development spanning over thirty years, BWC has devised a simple method to estimate the load/life relationship for a specific DualVee[®]-based guide mechanism under defined loading conditions. The methodology accounts for the size of the DualVee[®] bearing elements, the relative spacing between these elements, and the orientation, location, and magnitude of the load. The curve is based upon clean, well lubricated track conditions, so for applications where lubrication is prohibitive, a derating factor must be applied (see below).

It is important to note that secondary considerations such as maximum velocity, acceleration rates, duty cycle, stroke length, environmental conditions, the presence of shock and vibration, and extreme temperature ranges can all impact bearing service life to varying degrees. As such, the sizing method outlined below should be used conservatively, and be considered only a guideline for the sizing of LoPro[®] linear systems. When time and budget permits, the prototyping of a LoPro[®] linear system is recommended to confirm service life expectations.

The Load / Life Equation -Linear Guide Sizing and Selection

The load/life estimation requires a basic understanding of the principles of statics, the ability to work with free body diagrams, and the capacity to resolve externally applied forces on a carriage assembly into the radial and axial reaction forces at each guide wheel in the design.



Step 1: Calculate the resultant radial and axial loads reflected to each bearing element in the system design

All standard considerations involved in statics calculations must be accounted for, including inertial forces, gravitational forces, external forces such as tool pressure, bearing element spacing, and magnitude and direction of the payload. Any external forces that generate a reaction through the wheel / track interface need to be considered. Refer to pages 67 - 71 for established load resolution equations for popular loading conditions. If assistance is required in resolving specific loads into the resultant reaction forces at the guide wheel / track interface, contact our applications engineering staff for support. It is recommended that the Application data sheet on page 75 be submitted beforehand, with as much application information detailed as possible.

Step 2: Calculate the load factor for the most heavily loaded guide wheel in the system

$$L_F = L_A / L_{Amax} + L_R / L_{Rmax}$$

- Where $L_F =$ Load Factor
- L_A = Resultant axial load on the guide wheel
- L_{Amax} = The maximum axial working load capacity
 - L_{R} = Resultant radial load on the guide wheel
- L_{Rmax} = The maximum radial working load capacity

The most heavily loaded bearing in the system will have the highest load factor (L_F). Bearing system elements should be sized such that $L_F < 1$.

Due to the varying application load and speed parameters and environmental conditions, the appropriate adjustment factor must be applied to the maximum axial and radial working load capacities (LAmax and LRmax) as follows:

Application Conditions	Adjustment Factor
Clean, well lubricated, low shock, low vibration.	1.0 - 0.7
Moderate contaminants, medium duty cycle, medium shock, low to medium vibration, moder- ate speed.	0.7 - 0.4
Heavy contamination, high duty cycle, high accel- eration, high velocity, medium to high shock, high vibration, no lubrication	0.4 - 0.1

Oscillating motion resulting in less than one full revolution of the wheel under load can cause accelerated wear on the internal bearing elements. Testing of such systems is recommended to verify compatibility of the design with the load/life requirements of the application.

Technical Reference

Load / Life Relationship, cont.

Step 3: Apply the load factor to the load/life equation below:

Life constants and DualVee[®] guide wheel load ratings are provided in both inch and metric as tabulated below:

LoPro	Lite Co	onstant
Size	inches of travel life	kilometers of travel life
1	2.19 x 10 ⁶	55
2	3.47 x 10 ⁶	87
3	5.19 x 10 ⁶	130
4	6.84 x 10 ⁶	171



LoPro[®] linear guides are available with a wide range of guide wheel options. The table below provides load capacity data for each of the standard available LoPro guide wheel options:

	DUALVEE GUIDE WHEEL LOAD CAPACITY (Ib _f) DUALVEE GUIDE WHEEL LOAD CAPACITY (N)											
Guide Wheel	Radial Working Load Capacity	Axial Working Load Capacity	BDLA RADIA L	BSLR RADIA L	BDLR AXIAL	BSLR AXIAL	Radial Working Load Capacity	Axial Working Load Capacity	BDLA RADIAL	BSLR RADIAL	BDLR AXIAL	BSLR AXIAL
	L _{Rmax} (lbs _f)	L _{Amax} (lbs _f)	(Ibs _f)	(Ibs _f)	(Ibs _f)	(Ibs _f)	L _{Rmax} (N)	L _{Amax} (N)	(N)	(N)	(N)	(N)
	3.	3.	1.	2.	3.	2.	3.	3.	1.	2.	3.	2.
W1	134	157	490	250	245	234	595	252	2180	1110	1090	1040
W2	322	140	1057	625	535	591	1431	625	4700	2780	2380	2630
W3	691	382	2057	1135	1012	1079	3074	1701	9150	5050	4500	4800
W4	1058	899	2878	1776	1428	1675	4704	4001	12800	7900	6350	7450
WØX	59	28	236	112	119	106	265	123	1050	500	530	470
W1X	134	157	490	250	245	234	595	252	2180	1110	1090	1040
W2X	322	140	1057	625	535	591	1431	625	4700	2780	2380	2630
W3X	691	382	2057	1135	1012	1079	3074	1701	9150	5050	4500	4800
W4X	1058	899	2878	1776	1428	1675	4704	4001	12800	7900	6350	7450
W4XXL	1702	1473	4631	3215	2338	3035	7571	6552	20600	14300	10400	13500
W1SSX	134	157	490	250	245	234	595	252	2180	1110	1090	1040
W2SSX	322	140	1057	625	535	591	1431	625	4700	2780	2380	2630
W3SSX	691	382	2057	1135	1012	1079	3074	1701	9150	5050	4500	4800
W4SSX	1058	899	2878	1776	1428	1675	4704	4001	12800	7900	6350	7450
W4SSC	1702	1473	4631	3215	2338	3035	7571	6552	20600	14300	10400	13500
W1SS227	111	47	407	207	202	196	494	208	1810	920	900	870
W2SS227	267	117	877	519	445	490	1188	520	3900	2310	1980	2180
W3SS227	574	314	1709	944	832	899	2554	1399	7600	4200	3700	4000
W4SSCR	876	746	2383	1475	1185	1389	3896	3320	10600	6560	5270	6180

Notes:

- 1. Basic Dynamic Load Rating, According to AFBMA STD 9-1990. Based on industry standard bearing calculations and are for comparison purposes only. Maximum working load figures should be used for component sizing and selection.
- 2. Basic Static Load Rating, According to AFBMA STD 9-1990. Based on industry standard bearing calculations and are for comparison purposes only. Maximum working load figures should be used for component sizing and selection.
- 3. Working load capacities reflect lubricated wheel/track interface.

Notes



Governing Equations of Motion



Equations of motion are described herein to determine the axial and radial loads applied to the carriage assembly when subjected to typical load scenarios, which can then be utilized to determine "Load/Life" characteristics.

а	_	acceleration [m/s ²]
u	-	
С	=	Carriage
d	=	Horizontal distance of payload center of gravity from carriage center, [m]
F	=	Force applied by belt (belt working load) or chain (avg. tensile strength), [N]
F _{Ax}	=	Axial /Thrust Load Capacity of Dual Vee Wheel, [N]
F _{Fr}	=	Frictional force, [N] =µg(Mc+ Mp)
F _{Ra}	=	Radial Load Capacity of Dual Vee Wheel, [N]
g	=	Gravitational Acceleration = 9.81 m/s ²
h	=	Vertical distance of payload center of gravity from carriage center. [m]
Мр	=	Payload Mass, [kg]
n	=	Carriage Wheel Track (distance between track vees), [m]
р	=	Payload
R_{Ax}	=	Wheel Axial Reaction Force, [N]
R _{Ra}	=	Wheel Radial Reaction Force, [N]
μ	=	Coefficient of Friction, $[N/N] = .015$
Wp	=	Payload Weight, [N]
WALC	=	Wheel Axial Load Capacity
WRLC	=	Wheel Radial Load Capacity
x	=	Carriage Wheel Base, [m]
Т _Р	=	Torque applied to carriage induced by payload.



Governing Equations of Motion



Load Scenario 3











Governing Equations of Motion, cont.




Actuator Sizing and Selection

LoPro[®] systems are available with the following standard actuator options:

- Lead Screw
- Ball Screw
- Belt and Pulley
- Chain and Sprocket

The actuator in a linear motion system functions to provide thrust to the carriage assembly in the direction of motion. The carriage is restricted from movement in the other 5 degrees of freedom by the DualVee®-based linear guide. The actuator drives the carriage and supports reaction forces as dictated by the application. Information regarding sizing and selection of LoPro® actuator technology is provided below.

Belt Drive System Characteristics

- High speed capacity
- Moderate thrust capacity
- Simple design; easy maintenance
- Smooth operation over wide range of speed
- High duty cycle capability
- Repeatable to +/- 0.004" (+/-0.1 mm)
- Accurate to 0.008"/foot (0.2 mm / 300 mm)
- Easily backdrivable
- Low noise
- High efficiency (90%)
- Subject to belt stretch or wear affecting positional accuracy
- Low shock load capacity

Sizing

The maximum load on the belt drive in a LoPro[®] linear system should be restricted to 80% of the belt's working load capacity. See page 16 for belt performance data. Actual service life of the belt and its respective drive ends are affected by the specific application duty cycle, velocity profile, and thrust loading parameters to which it is subjected. As such, sizing should be done conservatively to assure service life expectations are met.

Chain Driven Systems:

Characteristics

- Low to moderate speed capacity
- High thrust capacity
- Simple design; easy maintenance
- Operates well in harsh environments
- Excellent resistance to heavy shock loads
- Inherently elastic; tends to absorb vibration
- High duty cycle capability
- Repeatable to +/- 0.008" (+/-0.2 mm)
- Accurate to 0.015" / foot (0.4mm / 300 mm)
- High efficiency (80%)
- Easily backdrivable
- High noise
- Subject to chain stretch or wear affecting positional accuracy

Sizing

Average tensile strengths of LoPro[®] standard chain is published on page 22 in the specifications section. Sizing of a chain driven LoPro[®] system should be such that the maximum tension exerted on the chain should not exceed 80% of the rated working load capacity. Actual service life of the chain and its respective drive ends are affected by the specific application duty cycle, velocity profile, and thrust loading parameters to which it is subjected. As such, sizing should be done conservatively to assure service life expectations are met.

Lead Screw Driven Systems

Characteristics

- Not easily backdrivable
- Low efficiency / sliding friction (30 50%)
- Low duty cycle (60% maximum)
- Low cost
- Quiet operation
- Repeatable to 0.0005" (0.01 mm)
- Accurate to 0.006 in / in (mm / mm)
- Wear is proportional to usage (unpredictable service life)
- Low speed operation
- Medium shock load capacity
- Smooth operation

Sizing

Lead screw systems should be sized such that the maximum axial load on the screw stays within 80% of the dynamic load capacity of the screw assembly. Dynamic load capacities are published on page 28 in the specifications section.

Ball Screw Systems

Characteristics

- Easily backdrivable
- High noise
- Moderate resistance to shock loading
- Smooth operation
- Moderate to high speed capacity
- High efficiency (90%)
- Repeatable to 0.0005" (0.01 mm)
- Accurate to 0.004"/foot (0.1mm / 300 mm)
- Predictable service life
- Maintains positional accuracy over screw service life
- High duty cycle capability

Sizing

Ball screw systems should be sized such that the maximum axial load on the screw stays within 80% of the dynamic load capacity of the screw assembly. Dynamic load capacities for ball screw assemblies are published on page 34 in the specifications section. Critical speed of the lead screw must also be considered. See critical speed chart below to verify ball screw velocity limitations.

Accuracy / Repeatability



Running parallelism end view of an unsupported LoPro[®] linear guidance system

The accuracy of a LoPro[®] linear system is dependent upon the mounting surface preparation and the technique used to align the track. LoPro[®] systems can achieve straightness and flatness characteristics to within 0.004" / foot (0.1 mm / 300 mm) when mounting surfaces are adequately prepared. Straight line accuracy of beam mounted LoPro[®] systems are subject to the industry standard straightness and twist tolerances associated with extruded or hot formed sections. As such, highest straight line precision can be achieved by bolting an unsupported LoPro[®] system to a carefully prepared flat mounting surface. Use of a machined reference edge will help maximize system straightness.

Point-to-point accuracy of a LoPro® linear system is dictated by the accuracy of the actuator. Screw driven systems are most accurate at 0.006 in / in (mm / mm). Belt driven systems are slightly less accurate and chain even less so. In terms of repeatability, screw driven systems are most repeatable at 0.0005". Repeatability in belt and chain drive systems ranges from 0.004" to 0.020" (0.10mm to 0.25 mm). Higher accuracy actuators can be integrated on request.

Preload / Fitup Adjustment

Wheel plate assemblies are built with two fixed position wheels mounted opposite two eccentrically mounted wheels. The stationary bushings determine the alignment of the system. Whenever possible, wheels should be configured so that the load is predominantly radial. Radial loading of the DualVee[®] guide wheel optimizes load distribution through the bearing elements, minimizing friction, and maximizing smoothness. That's not to say that LoPro® systems cannot be loaded in any other way. LoPro[®] linear systems can be loaded axially, or in any of the moment orientations as well. It's just good engineering practice to orient the system to accept loads radially, whenever the application allows for it.



LoPro[®] guide assembly with force and moment load vectors drawn in. Linear guide performance in a LoPro[®] system is optimized when loads are primarily radial.

Correct adjustment of the wheel to track fit-up will ensure optimum performance and long life from your LoPro[®] linear motion system.

DualVee[®] guide wheels are affixed to their respective wheel plates with either a concentric or eccentric bushing and a wheel bolt. The eccentric components are identified by a hexagonal shoulder, which is rotated by a thin profile, open end, wrench. The rotation of the eccentric bushing varies the force with which the wheel is pushed into contact with the track. The ideal adjustment of the eccentric bushings will eliminate free play of the carriage, while not over pre-loading the wheel bearings. The suggested procedure for this adjustment is as follows:



Fitup adjustment being made to a wiper wheel plate in a belt driven LoPro[®] linear motion system.

- Check that the concentric mounted wheels are tightly affixed to the carriage plate.
- Loosen the eccentric mounted wheels just enough to permit rotation of the mounting bushings with an open-end wrench on the hex.
- 3) Position the carriage plate on the track.
- 4) Rotate the hex with the wrench until the wheels contact the track.
- 5) Hold the guide wheel between your fingers, and move the wheel plate along the track. Adjust the hex with the wrench until the wheels will just barely skid on the track. Tighten down the wheel bolt, (or nut) to maintain this adjustment.
- 6) Repeat this procedure for all of the eccentric mounted wheels.
- The carriage should ride smoothly and uniformly over the entire length of the track. Further adjust the wheels until this condition is met.

<u>Lubrication</u>

Lubrication is the key to maximizing service life in any rolling contact linear bearing design. Internally, DualVee[®] guide wheels are lubricated for life with an extreme pressure, corrosion resistant grease. As such, the main consideration with regards to lubrication is the wheel / track interface. Typically, a light machine oil or an extreme pressure grease does well to minimize wear, stick slip, and corrosion.

LoPro[®] systems are available with two standard wheel plate designs. The wiper wheel plate comes complete with lubricating wiper caps (lubricators consist of an oil saturated felt). The basic wheel plate is available with either wheel covers or lubricators. Both options include lubrication via oil saturated felt.

Lubrication will maximize the load capacity of an individual bearing element. As such, for any specific loading condition, the presence of lubrication on the guide ways will significantly increase the service life over a non-lubricated configuration under the same loads.

Lubrication will also increase the maximum linear velocity that a guide wheel – based bearing arrangement can travel. In high cycling applications where high speed or acceleration rates are present, lubrication of the wheel / track interface is strongly recommended.

Track Splicing Considerations

The aluminum track plate in a LoPro[®] guide is fabricated in 10 foot lengths. DualVee[®] track, on the other hand, is fabricated in 20 foot lengths. The fact that LoPro[®] systems can be fabricated with long lengths demands that DualVee[®] track must be spliced somewhere. Standard track splicing procedure for systems in excess of 20 feet calls for the joints on parallel tracks to be staggered for greater accuracy and smoothness. Long length systems requiring track splicing are engineered, fabricated, assembled, and quality checked, prior to disassembly, packaging, and shipment. Systems are supplied with clearly marked, pre-matched joints making installation easy.

Contaminated Environments / Wear Resistance

Since the circumference of the wheel is greater at the major diameter than at the minor diameter, there is a constant wiping action on the track surface. This wiping action gives DualVee® - based guidance systems a self cleaning effect. As such, DualVee[®] guide wheels are employed in a wide variety of harsh environments, including the presence of metal chips, fibers, slurries, etc. It is important to note that such environments will often limit service life of the LoPro® guidance system to some extent. Since environments vary from application to application, it is recommended that a LoPro® system be prototyped before employing on a large scale, particularly in a harsh environment where service life could be unpredictable.



Application Data Sheet

Company:			
Contact:			
Address:			
City:	State:	Zip Code:	
Phone:	Fax:	e-mail:	
System Orientation:	horizontal	□ vertical	
Load:	🗆 lbs		
Mass Size (I x w x h):	🗆 in	🗆 m	
Stroke Length:	🗆 in	🗆 m	
Velocity:	🗆 in/s	□ m/s	
Accel/Decel:	□ in/s ²	\square m/s ²	
Linear Accuracy:	□ in/ft	🗖 mm/m	
Repeatability:	□ in	🗆 mm	
Duty Cycle:	□ in/day	□ m/day	
Environment:	□ factory □ foo	od grade 🛛 clean room 🗖 other	
Temperature:	 □ °F	□°C	
Additional Forces:			
Additional Requirements: Expected Volume:	Date Needed:		
	System Si	etch	
Constraint <td></td> <td></td> <td></td>			

BWC[®] Solutions

DualVee® Components and Linear Guides — built with DualVee Motion Technology*

GV3 Linear Guidance and Transmission System

SL2 Stainless Steel Based Slide System

HDS Heavy Duty Slide System

UtiliTrak[®] Linear Motion Guide – built with DualVee Motion Technology[®]

LoPro[®] Linear Motion System — built with DualVee Motion Technology

DLS Driven Linear System

HDLS Heavy Duty Driven Linear System

RTS Ring and Track System / DTS Driven Track System

MCS Aluminum Frame and Machine Construction System



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