

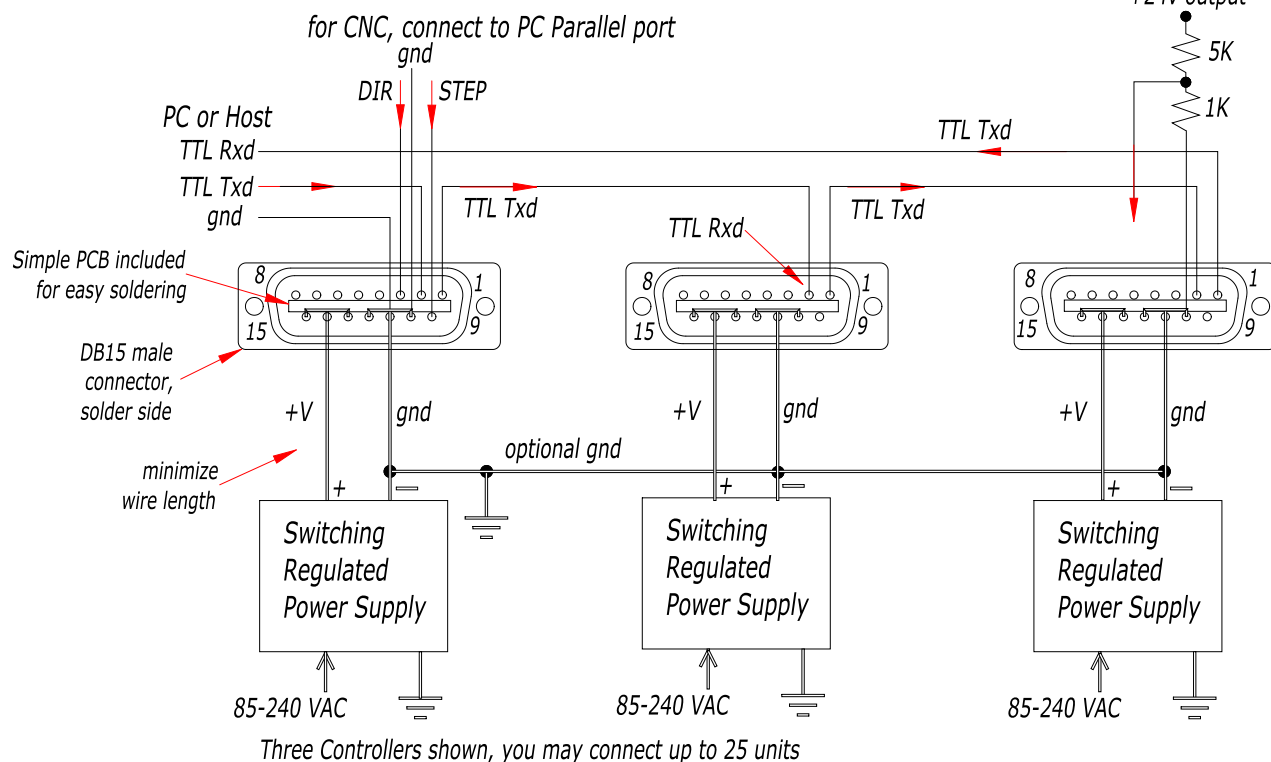
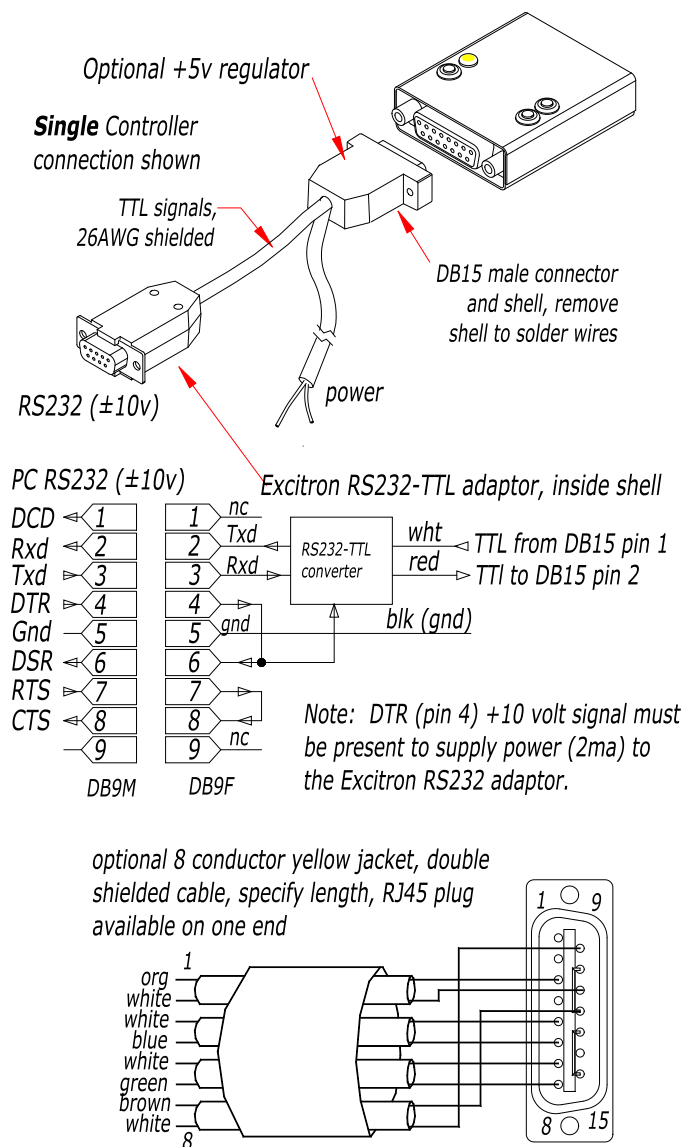
Various connections are shown here. Excitron Controllers have a DB15 or 8 or 10 pin header connectors. Other serial port interfaces such as USB and RS485 are available. See the CNC DB25 Diagram for step/dir Driver Mode.

Simple Serial Bus provides a daisy chain "network" to connect multiple Controllers. The PC is the Master and each FTFc15 must be set to a slave address. You must first set the address for each Controller **before** connecting this daisy chain. The transmit pin of each Controller is tied to the Receive pin of the next Controller. See the Excitron Controller User's Manual for protocol details. In case you forget the slave address, pushing Sw1 & Sw2 manual switches (if available) will cause the slave address to be displayed. Then type '@' to stop the message.

Note for DB15 type Controllers! all signals are TTL (+5v). Maximum allowable voltage is +5.5, minimum is -0.5. Do not connect RS232 ($\pm 10v$) signals directly to TTL. For interface to RS232 PCs, use FTFw-RS232-TTL Adaptor, which translates the $\pm 10v$ to +5v logic. The power ground provides the signal ground for the serial port ground. Serial communications may fail unless your PC is grounded. USB and RS232 Controllers have built-in circuitry for direct connection to the appropriate PC port.

The +5v regulator option gives you up to 30ma for externally powering devices, and additional noise immunity on the Controller input pins. This regulator option is assembled inside the DB15 male connector.

You may connect PLC +24 volt outputs to the Controller input pins with a resistor ladder as shown:



10A-TTL and 100A-TTL Controllers are provided with a 18" heavy duty jacketed 18 AWG 2 conductor power cable; 12" length when ordered with our 24 volt 72W encapsulated power supply. White is +V; black is ground. Heavy currents may require additional wires for good grounding. Cut this cable to the shortest reasonable length; this reduces electrical noise spikes and possible missed motor steps. Smaller motor/controllers are provided with 18" long with red +V and black ground wires. All controllers supplied with matching connectors. If the power supply and/or RS232-TTL adaptor is ordered with your controller, then all wires are soldered and tested for you.

EXCITRON

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Controller Connections

www.excitron.com 100% 1/1 Rev A

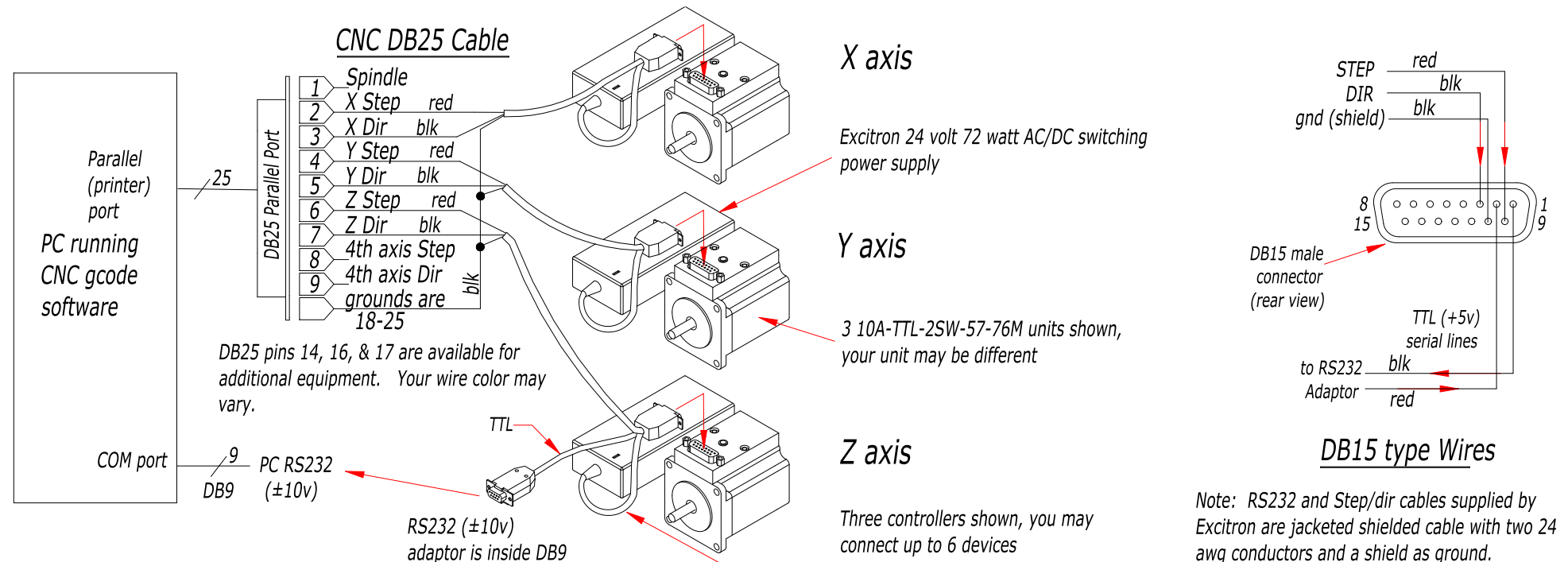
CNC DB25 Cable:

This cable provides an easy connection for the PC parallel port CNC step/dir pins. Up to 6 axis can be connected, depending on your CNC program. All PC CNC programs output **step** and **direction** signals to the PC parallel DB25 connector, and the Controller accepts **step** and **direction** when in Driver Mode. You may use a DB25 extension cable (25 stranded wires, shielded) between your PC and the CNC DB25 cable. Other equipment may be connected by soldering wires to the DB25 socket pins.

Power Supply Cable:

Best configuration is shown--AC/DC power supply close to the Controller, to reduce electrical noise. Then only the inexpensive AC power cord flexes during movement.

IMPORTANT! DO NOT run AC cables near any DC or signal cables!



CNC Setup:

1. Simply plug each motor/controller into the appropriate DB15 male connector, and plug the DB25 connector into your PC's Printer Port (DB25).
2. Run your PC CNC software program, and configure the printer port outputs to match the step and direction signals to the particular parallel port pin. The most logical pin configuration is shown here. If your program has Enable outputs, ignore them for use with the motor/controllers. Also change the CNC program configuration for the: number of motor steps per inch (or mm); maximum velocity; acceleration; and possibly other values.

Serial Port Setup:

1. If you want to change the Controller's full/half step, brake, or torque (these are not changed by your CNC program), then run Hyperterminal or any serial program, which uses the PC serial COM port connected to the Controller, if it has an RS232-TTL Adapter.
2. Type '@' to put the Controller into Command Mode, change full/half step, brake, or torque, then save your changes to Motion Profile #01 using the 'U' 01 command. Then set for Driver Mode by typing 'c' then 'd'. When in Driver Mode, the Controller will echo serial characters, but will not respond to them, except the '@' which stops Driver Mode and puts it back into Command Mode.
3. See Controller Connections for additional information.

Note: RS232 and Step/dir cables supplied by Excitron are jacketed shielded cable with two 24 awg conductors and a shield as ground.

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CNC DB25 Diagram