

OPERATOR'S MANUAL

MODEL 1877

96 CHANNEL FASTBUS TDC

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(ECO 1300)

CAUTION

Cooling

It is imperative that the module 1877 TDC be well cooled. Be sure fans move sufficient air to maintain exhaust air temperature at less than 50° C.

Installation

"Hot" insertion (insertion with crate power turned on) of modules is supported in accordance with the FASTBUS specification.

Specifications

The information contained in this manual is subject to change without notice. The reference for product specification is the Technical Data Sheet effective at the time of purchase.

Electrostatic Sensitivity

While measures have been taken to protect the MTD133 ASIC from electrostatic damage, it is still imperative to follow anti static procedures when handling this CMOS device. Removal of the MTD133 from its socket will void the product warranty.

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1. General Information

1.1 Purpose

This manual is intended to provide instruction regarding the setup and operation of the LeCroy Model 1877 Time to Digital Converter. In addition, it describes the converter's theory of operation and presents information regarding its function and application.

1.2 Unpacking and Inspection

It is recommended that the shipment be thoroughly inspected immediately upon delivery. All material in the container should be checked against the enclosed Packing List and shortages reported promptly. If the shipment is damaged in any way, please notify the Customer Service Department or the local field service office. If the damage is due to mishandling during shipment, you may be requested to assist in contacting the carrier in filing a damage claim.

1.3 Warranty

LeCroy warrants its instrument products to operate within specifications under normal use and service for a period of one year from the date of shipment. Component products, replacement parts, and repairs are warrantied for 90 days. This warranty extends only to the original purchaser. Software is thoroughly tested, but is supplied "as is" with no warranty of any kind covering detailed performance. Accessory products not manufactured by LeCroy are covered by the original equipment manufacturers' warranty only.

In exercising this warranty, LeCroy will repair or, at its option, replace any product returned to the Customer Service Department or an authorized service facility within the warranty period, provided that the warrantor's examination discloses that the product is defective due to workmanship or materials and has not been caused by misuse, neglect, accident or abnormal conditions or operations.

The purchaser is responsible for the transportation and insurance charges arising from the return of products to the servicing facility. LeCroy will return all in-warranty products with transportation prepaid.

This warranty is in lieu of all other warranties, express or implied, including but not limited to any implied warranty of merchantability, fitness, or adequacy for any particular purpose or use. LeCroy shall not be liable for any special, incidental, or consequential damages, whether in contract, or otherwise.

1.4 Product Assistance

Answers to questions concerning installation, calibration, and use of LeCroy equipment are available from the Customer Service Department, 700 Chestnut Ridge Road, Chestnut Ridge, New York, 10977-6499, (914) 578-6030, or your local field service office.

1.5 Maintenance Agreements

LeCroy offers a selection of customer support services. For example, Maintenance Agreements provide extended warranty that allows the customer to budget maintenance costs after the initial warranty has expired. Other services such as installation, training, on-site repair, and addition of engineering improvements are available through specific Supplemental Support Agreements. Please contact the Customer Service Department or the local field service office for details.

1.6 Documentation Discrepancies

LeCroy is committed to providing state-of-the-art instrumentation and is continually refining and improving the performance of its products. While physical modifications can be implemented quite rapidly, the corrected documentation frequently requires more time to produce. Consequently, this manual may not agree in every detail with the accompanying product and the schematics in the Service Documentation. There may be small discrepancies in the values of components for the purposes of pulse shape, timing, offset, etc., and, occasionally, minor logic changes. Where any such inconsistencies exist, please be assured that the unit is correct and incorporates the most up-to-date circuitry.

1.7 Software Licensing Agreement

Software products are licensed for a single machine. Under this license you may:

- Copy the software for backup or modification purposes in support of your use of the software on a single machine.
- Modify the software and/or merge it into another program for your use on a single machine.
- Transfer the software and the license to another party if the other party accepts the terms of this agreement and you relinquish all copies, whether in printed or machine readable form, including all modified or merged versions.

1.8 Service Procedure

Products requiring maintenance should be returned to the Customer Service Department or authorized service facility. If under warranty, LeCroy will repair or replace the product at no charge. The purchaser is only responsible for the transportation charges arising from return of the goods to the service facility. For all LeCroy products in need of repair after the warranty period, the customer must provide a Purchase Order Number before any inoperative equipment can be repaired or replaced. The customer will be billed for the parts and labor for the repair as well as for shipping. All products returned for repair should be identified by the model and serial numbers and include a description of the defect or failure, name and phone number of the user. In the case of products returned, a Return Authorization Number is required and may be obtained by contacting the Customer Service Department in your area.

2. Product Description

2.1 Introduction

The LeCroy Model 1877 provides 96 channels of either Common Start or Common Stop multi-hit Time to Digital Conversion designed for elementary particle or nuclear physics experiments. All input time signals to be measured, "hits", are received via differential ECL (dECL) front panel inputs. Each channel exhibits 500 psec LSB and can store up to 16 hits within a 32.768 usec range. The time measurement is performed using the MTD133, a full custom ASIC developed by LeCroy Corporation.

2.2 General Description

The 1877 Time to Digital Converters offer all the flexibility of the 1870 Series Pipeline Time to Digital Converters with a 500 psec least count and can store up to 16 hits per channel within a 32.768 usec full scale range. Time data relative to the common input is stored in a LIFO within the MTD133 until it is transferred to the 1877's buffer memory. The MTD133's internal LIFO depth is programmable from 0 to 16 hits. Additionally, the full scale range of the MTD133 may be programmed from 0 to 32.768 usec.

Each 1877 has 96 channels of front panel hit inputs and a Common input. All inputs are differential ECL (dECL) and are terminated by a balanced 110 ohm impedance matching network. The 1877 can operate in either Common Start or Common Stop mode. In Common Start mode, the common input receives a start pulse and the individual channels can register up to 16 subsequent hits during a programmable Common Start Timeout window. In Common Stop mode, the 96 front panel inputs register individual channel hits and the common inputs latches a stop pulse. Each channel can be programmed to detect leading and/or trailing edges (hits) and can store up to 16 hits. Selected edges can be detected with as little as 20 nsec separating them. If more than 16 hits occur per channel, only the last 16 hits are retained. If multiple common input pulses are received, only the first is registered.

Operation of the 1877 can be divided into four phases: programming, acquisition, buffering and readout. Once the control/status registers have been programmed the module is in acquisition mode and ready to latch hits. In Common Start mode, the acquisition phase begins when the module latches a start and ends after a user programmable common start timeout. No hits will be recorded after the programmed hit window expires. A front panel dECL input is also provided to allow the use of an external timeout if desired. The maximum acquisition time, however, is internally restricted to 32.768 usec regardless of the application of an external timeout. Immediately following the acquisition phase, the time data is transferred to an eight event circular buffer, awaiting readout to Fastbus. Readout of the event just buffered can occur as quickly as 500 nsec after the end of buffering. The module automatically returns to acquisition mode once all the time data for a particular event has been safely buffered. Readout of events previously stored in the buffer memory may occur simultaneously with acquisition or buffering without any performance penalty.

In both Common Start and Common Stop modes, a programmable fast clear window begins immediately following the end of acquisition. During the fast clear window (FCW), a user can safely clear an event (e.g. based on a experiment trigger decision) and return to acquisition mode, thus saving the time necessary for buffering and reading out the event. The FCW can range from 800 nsec to 400 usec.

The data for each event stored in the multi-event circular buffer is preceded by a header word identifying the address (geographic or logical), the buffer number, and the word count for the event. A parity bit is set to give an even number of bits for the word. The timing measurements of the 1877 are stored as 32 bit words. The least significant 16 bit word is the time measurement data. The most significant 16 bit word contains the channel number, phase (leading or trailing), even parity, buffer number (modulo 4), and the geographic address.

The front panel hit inputs are also converted to TTL levels and provided directly to the auxiliary connector as trigger outputs. Unlike the 1876, these trigger outputs are not pair-wise OR'ed and there is no provision for programmable trigger widths.

The functionality of the 1877 can be tested using either an internal tester or a front panel dECL test input. The internal tester can be programmed to produce 1, 2, 4 or 8 pulses separated by 125, 250, 500, or 1000 nsec, respectively. Either leading, trailing, or both edges of the pulses are selectable for detection, creating up to 16 internal hits per channel. Testing can be performed in either Common Start or Common Stop modes.

Like the earlier LeCroy models 1878 & 1879 TDCs, provisions have been made to accommodate auxiliary card functions. A 12 bit bi-directional bus, four address lines and three control lines are connected to the Fastbus auxiliary connector for read and write operations on the auxiliary card. The 1877 also has the facility to allow auxiliary cards to assert the TDC's T-pin in response to a specific broadcast code. Pinout at the auxiliary connector is compatible with the earlier models.

2.3 Specifications

Please refer to the model 1877 technical data sheet for a complete summary of all relevant specifications.

2.4 Front Panel

The LeCroy Module 1877 TDC front panel provides connectors for system integration and LEDs to indicate the module status and assist system debugging. Cables necessary for proper installation can be purchased from LeCroy. See Section 3.2 for more information regarding cabling.

2.4.1 Displays

Two colored LEDs reside on the front panel of the 1877 to indicate the status of operations. A brief description of each is listed below: The LED illumination is stretched to a minimum of 10 msec to aid in viewing.

- **Slave Addressed LED:** As per the Fastbus specification, this yellow LED is lit whenever the TDC module is attached to the Fastbus as a slave.
- **Common Hit LED:** This green LED is illuminated whenever the TDC registers a common hit (start or stop). The common hit may be received via the front panel input marked COM, a FASTBUS command, or it may be created by the module's internal tester. See Section 2.11 for more information regarding the internal tester.

2.4.2 Inputs

All front-panel inputs to the 1877 are differential ECL compatible with the ECLine standard. The "+" input is quiescently at least 200 mV more negative than the "-" input. Each pair of differential inputs is terminated with an effective 112 ohms.

All hit inputs are received via six 34 pin connectors. A 3M connector type 3414-6034 will mate with the TDC header and provide strain relief. Pin 33 is connected to circuit ground, and pin 34 is connected to chassis ground. The circuit ground and the chassis ground are connected to each other on the printed circuit board through 100 ohms. The hit inputs are numbered from top to bottom in ascending order. Four control inputs are differentially received via an 8 pin header located at the bottom of the front panel.

The control signals can be connected by single pair headers AMP part number 5-87456-2 or they can all be connected simultaneously by a 8 position connector AMP part number 87456-2. A brief description of each input follows below:

- **COM** : A dECL input which receives the common input pulse. Any pulse, whether it be a start or a stop, received via the COM input is global to all 96 channels. In Common Start mode the pulse acts as a global start for every channel, and in Common Stop mode it acts as a global stop for every channel. Front panel input of this signal is selected by setting CSR1<1> to 0. This signal may be daisy chained on the front panel if the two jumpers connecting the 112 ohm input termination are removed from all except the last module in the chain.
- **CLR** : A dECL input used to issue fast clears to the module. A clear pulse can be issued at anytime inside the Fast Clear Window or when buffering is not in progress, provided it is at least 40 nsec wide. When a clear is issued, the data of a just measured, unbuffered, event is cleared and the module returns to acquisition mode 250 nsec after the trailing edge of the pulse. There is no output signal coinciding with the module's return to the ready state. The control and status registers are not affected by a clear. Front panel sourcing of this signal is always enabled. This signal may be daisy chained on the front panel if the two jumpers connecting the 112 ohm input termination are removed from all except the last module in the chain.
- **TIME** : A dECL input used to receive the Common Start Timeout pulse. When operating in Common Start mode, it is necessary to define a period of time when the TDC will register hits. The beginning of this period starts with receipt of the Common Start. The end of this time occurs when the module receives the timeout pulse. Front panel input of this signal is selected by setting CSR1<7:4> to 0. This signal may be daisy chained on the front panel if the two jumpers connecting the 112 ohm input termination are removed from all except the last module in the chain. This signal can also be provided by an on board programmable timer. If the front panel source for this signal is selected but does not arrive, the module will still time out after 32 usec.
- **IN** : All 96 dECL inputs are used to receive individual channel hits. In Common Start mode the stop pulses are received via the connectors marked IN, and in Common Stop mode the start pulses are received.

2.4.3 Outputs

The one front panel output from the 1877 is differential ECL. The "+" output should be quiescently at least 200 mV more negative than the "-" output. This output is terminated with 112 ohms to -2 V.

- **BIP** : Buffering in Progress (BIP) is a single dECL signal provided to aid in readout. While BIP is true, the current event's data is being buffered and the data from this event is not ready for readout via FASTBUS. BIP will also become true when all buffers are full and no further events can be accepted. In the event of a fast clear, BIP will go false within 75 nsec of the rising edge of the fast clear pulse. Of course, events buffered may be readout via FASTBUS at any time.

2.5 General Operation

The operation of the 1877 can be divided into four unique phases. The first phase includes all the setup necessary before the 1877 TDC can successfully be used. This includes installation of the module and programming the control registers. The module will not latch hits until the control registers have been programmed. Once all the setup is complete, the module is in acquisition mode and ready to accept hits. The module remains in acquisition mode until either a Common Start Timeout or a Common Stop occurs, depending on the acquisition mode programmed.

Following acquisition mode, the module buffers the data into a multiple event data buffer. It can take a maximum of 78 usec for an event to be buffered, depending on the number of hits in the event. While the data is being buffered, the Buffering In Progress (BIP) signal is true. The user can begin the final phase, readout, 500 nsec after the buffering has finished. However, previously buffered events can be readout while the most current event is being buffered, with a penalty in buffering speed.

2.5.1 Setup

As per the Fastbus specification, the 1877 may be inserted in the Fastbus crate with the power either on or off. No special precautions are required when attaching the front panel connectors. If it is desired to daisy chain the COM or CLR signals, the jumpers connecting the terminations for these signals must be removed on all except the last unit in the daisy chain. At a minimum, CSR1 must be programmed to establish a working condition in the 1877.

1. **CSR0:** CSR 0 must be programmed as for desired addressing mode and Multi-Block configuration.
2. **CSR1:** CSR 1 contains most of the configuration bits for the module. Acquisition mode, edge selection, and Common Start Timeout (if Common Start operation is chosen) must be set for the desired operational modes. *This register powers up to 0x00000000 and must be programmed to enable leading and/or trailing edge detection.*
3. **CSR3 :** CSR 3 <31:16> must be written to the desired value if logical addressing is being used.
4. **CSR7 :** This register must be configured if it is desired to use class N broadcasts.
5. **CSR18 :** This register controls the full scale time measurement and LIFO depth (number of hits each channel will register) of the MDT133. After power up or a master reset this register defaults to full scale and maximum LIFO depth.

After the CSR registers are programmed, the unit is ready to acquire data.

2.6 Control and Status Registers

Twenty three Control and Status Register (CSR) locations are possible. Seven registers reside on the 1877 TDC module itself and are always implemented within the module. Sixteen additional locations are reserved for an Auxiliary Functions Card (AFC) are supported by the Fastbus interface to the auxiliary connector. These 16 registers exist only to the extent they are implemented on the AFC.

2.6.1 Control and Status Register 0

When CSR 0 is read, the 1877 presents 103C_h on the Address/Data bus lines 16-31 as its manufacturer's identification. CSR0 is the default register when a primary address to control space is issued. See Figure 2-1 and Figure 2-2 for individual bit definitions.

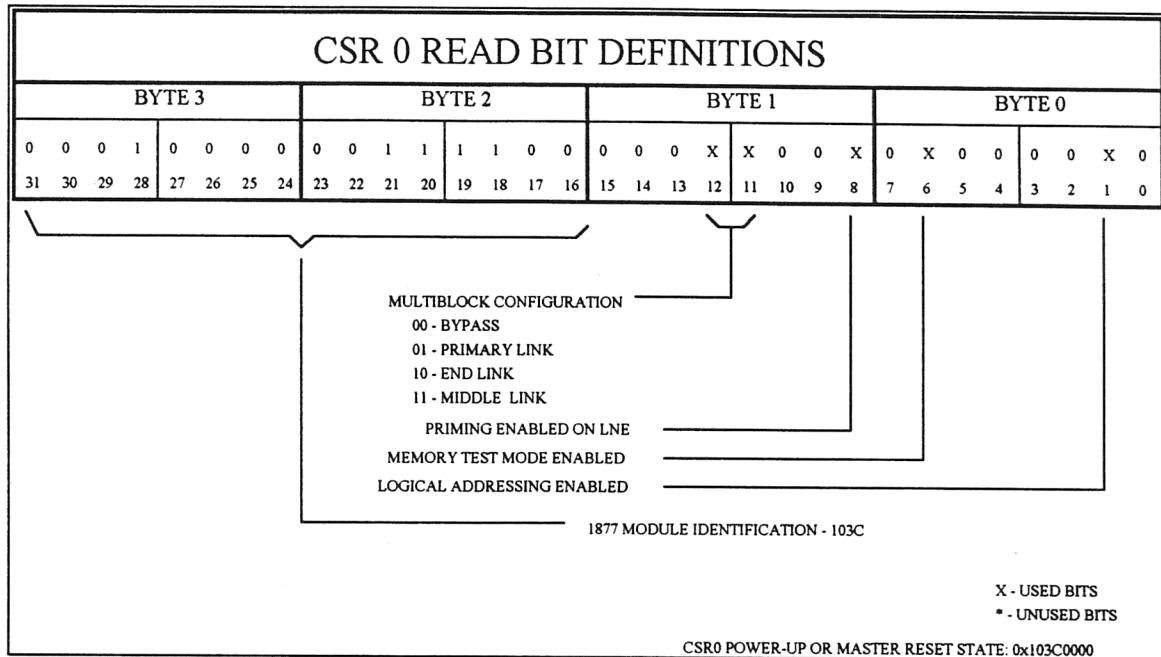


Figure 2-1 CSR 0 Read Bit Definition

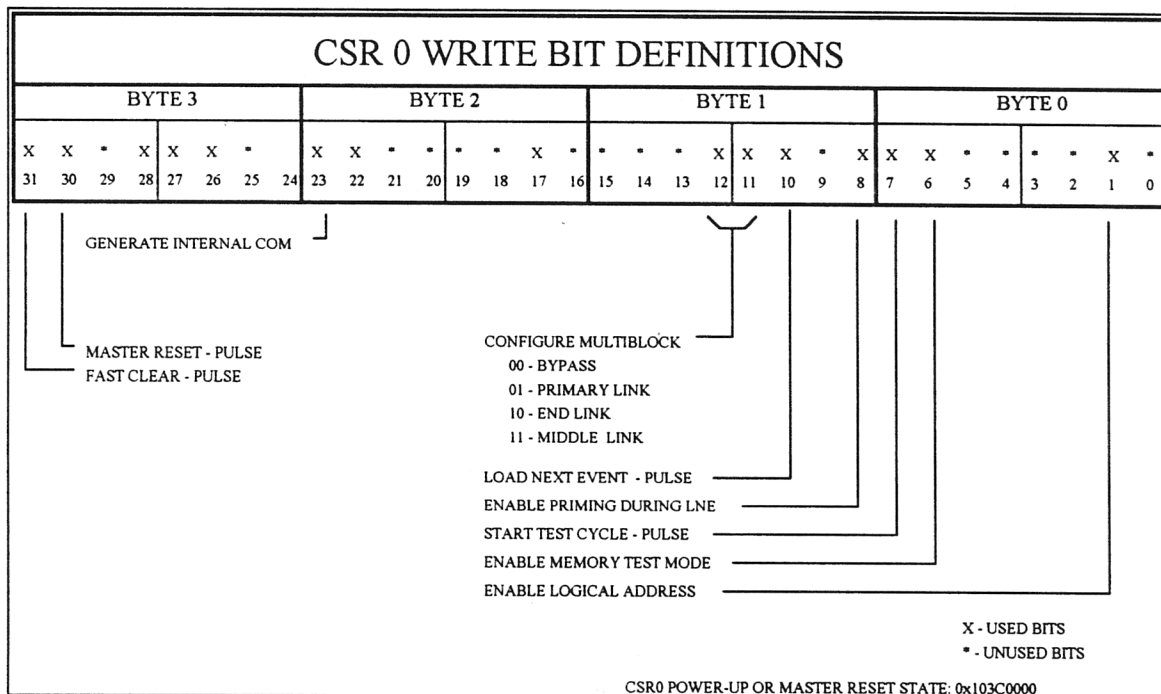


Figure 2-2 CSR 0 Write Bit Definition

Latched Bits:

- **Logical Address Enable:** Bit 1 must be set for the unit to respond to logical addressing.
- **Enable Priming on Load Next Event:** When bit 8 is set, the module primes its internal data pipeline during a Load Next Event command. This option is provided to improve block transfer

startup times and Multi-Block token passing times. Priming on LNE *must* be enabled when the module is participating in a MDT (Multi-Block) scan. Failure to do so will result in the module responding to the transfer with SS=3, the MDT error response. Enabling Priming on LNE when in Memory Test Mode must be done with great care since the priming operation results in the data space NTA being advanced. Also CSR5 (only visible while in Memory Test Mode) is decremented during priming. *It must, therefore, be understood that the use of Priming on LNE with Memory Test Mode enabled results in a non-compliant Fastbus mode.*

- **Memory Test Mode Enable:** If Bit 6 is set, the memory in data space may be accessed by specifying an NTA in data space corresponding to the memory location desired. This feature may be used to facilitate testing of the memory. In normal operation, this bit should be 0. See Section 4.3.2.2 for further discussion of Memory Test Mode (MTM).
- **Multi-Module Data Transfer (Multi-Block) Configuration:** Bits 11 and 12 configure the module for MDT operation as described in Appendix N to the Fastbus Specification. Also see Section 4.4.3 for further discussion of the Multi Block implementation specific to the 1877. Priming on LNE (CSR0<8>) *must* be enabled when the module is participating in a MDT (Multi-Block) scan. Failure to do so will result in the module responding to the transfer with SS=3, the MDT error response

Pulsed Bits:

- **Fast Clear :** Writing Bit 31 will produce a clear signal equivalent to a front panel clear or TR0 clear.
- **Master Reset :** A write to Bit 30 will reset all CSR 's to their power up condition.
- **Load Next Event :** This input advances the buffer page pointer by 1 and loads CSR5 with the word count (the contents of the first memory location of the next page of memory) for that event. This facilitates a block read of the event. Note: CSR5 is only visible to Fastbus while in Memory Test Mode.
- **Test Cycle :** A write to Bit 7 initiates a burst of pulses from the internal tester.
- **Internal Com :** Writing Bit 23 is equivalent to a pulse on the front panel Com (or TR6 input). This method of generating a Com signal is always enabled.

Note: As per the FASTBUS specification, CSR0<29:22> are clears for corresponding user defined bits CSR0<13:6>.

2.6.2 Control and Status Register 1

The information necessary to define such user-programmable functions as the acquisition mode, the edge detection, the fast clear window, the internal tester's operation and the trigger mode are contained within CSR 1. See Figure 2-3 for individual bit definitions.

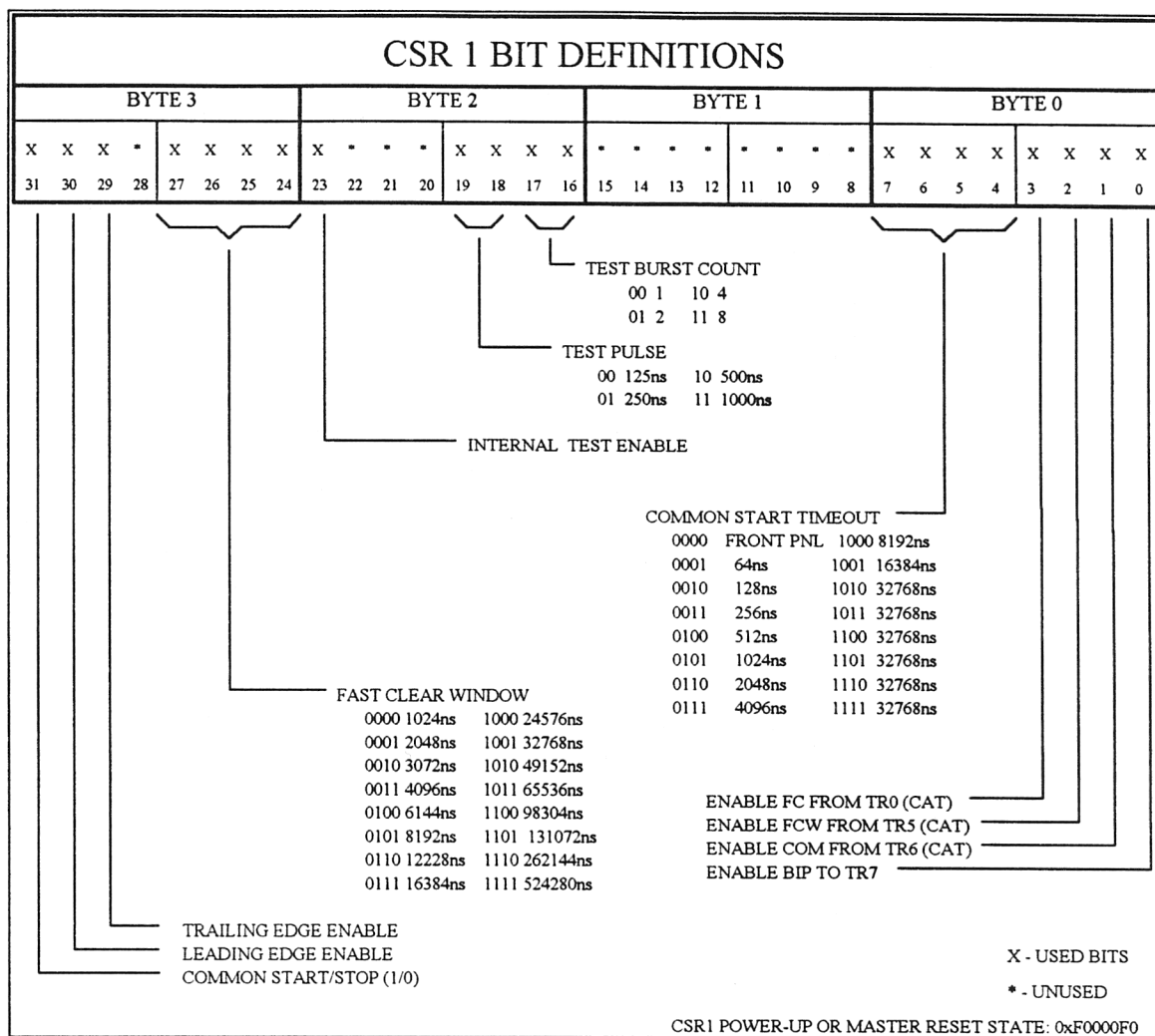


Figure 2-3 CSR1 Bit Definition

- **Acquisition Mode** : Bit 31 determines whether the TDC will operate in Common Start or Common Stop mode. When a one is written the board operates in Common Start mode, and when a zero is written the board operates in Common Stop mode. When read, the status of the bit is presented.
- **Leading Edge Enable** : Bit 30 determines whether the TDC will register the rising (low-to-high transitions) edges of incoming hits. Hits may be received from either the front panel IN connectors or the on-board tester. When a one is written the board will detect rising edges, and when a zero is written the board will not detect rising edges. When read, the status of the bit is presented.
- **Trailing Edge Enable** : Bit 29 determines whether the TDC will register the trailing (high-to-low transitions) edges of incoming hits. Hits may be received from either the front panel IN connectors or the on-board tester. When a one is written the board will detect trailing edges, and when a zero is written the board will not detect trailing edges. When read, the status of the bit is presented.

- **Fast Clear Window** : Bits 24-27 determine the length of time the on-board timer permits the user to issue a fast clear to the module after the end of acquisition. The fast clear window begins immediately following a stop pulse in Common Stop mode and immediately following a Common Start Timeout in Common Start mode. Note, this is independent of a Fast Clear Window supplied from the 1810 CAT module; the two sources are in effect OR'ed together. Once the fast clear window has ended, the current event can no longer be cleared from the multi-event buffer. When read, the status of the bits is presented.
- **Internal Test Enable** : Bit 23 enables operation of the internal tester. When read, the status of the bit is presented.
- **Test Pulse Width** : Bits 18 and 19 determine the width of the on-board tester's hit pulses. The width can be programmed to be 125, 250, 500, or 1000 nsec when a 0, 1, 2 or 3 are written respectively. When read, the status of the bits is presented.
- **Tester Burst Count** : Bits 16 and 17 determine the number of pulses the on-board tester will generate. The tester can be programmed to create 1, 2, 4 or 8 pulses when a 0, 1, 2 or 3 are written respectively. When read, the status of the bits is presented.
- **Common Start Timeout** : Bits 4-7 determine the measurement full scale in Common Start mode. These bits define the period of time during which the TDC will detect hits. It is initiated by a start pulse and ended a variable time later by the timeout. The timeout can be programmed to arrive as quickly as 64 nsec after the start pulse or as long as 32,768 nsec after the start pulse. The Common Start Timeout is only meaningful in Common Start mode. When read, the status of the bits is presented.
- **Enable Fast Clear from TR0** : Setting Bit 3 permits receipt of a fast clear from TR0. The front panel source of fast clear remains enabled.
- **Enable FCW from TR5** : Setting Bit 2 permits a fast clear window to be supplied from TR5.
- **Enable COM from TR6 / TR3** : If Bit 1 is set to 1, either TR6 or TR3 is enabled as the source for the COM signal, and the front panel COM is disabled. If the 1877 is in Common Stop mode, the TR6 is the source. If in Common Start mode, TR3 is the source.
- **Enable BIP to TR7** : Setting Bit 0 outputs the Buffering in Progress signal to TR7. This should not be set if a model 1810 CAT is in the same crate.

2.6.3 Control and Status Register 3

As per Fastbus specification, CSR 3 is used to store the desired logical address for the unit. CSR3<31:16> contain the logical address. This register powers up to 0 but is not disturbed by a master reset, CSR0<30>.

2.6.4 Control and Status Register 5

CSR 5 is implemented as an 11 bit read/write register used to control the number of words transferred during a block transfer. During a FASTBUS readout, it is decremented after each transfer. CSR5 is automatically loaded with the word count for the next event to be read out after a Load Next Event command has been issued. Bits 0 through 10 only are meaningful. Bits <31:11> will read back as 0. CSR5 is set to 0x00000000 by a Master Reset.

NOTE: CSR 5 is only accessible from Fastbus when the module is in Memory Test Mode.

CSR 7 is used to specify the broadcast classes to which an 1877 will respond. It is implemented as an 4 bit read/write register. Bits 3 through 0 correspond to broadcast classes 3 through 0 respectively. If bit N is set, the 1877 will be selected by a broadcast to class N devices. CSR7 is not affected by Master Reset.

CSR 16 is implemented as a 16 bit read-write register used to indicate and control the location of the read and the write buffer addresses. CSR 16 <15:8> indicate the next buffer to be readout to Fastbus, and CSR 16 <7:0> indicate the next buffer to be filled. Master Reset and Power-up reset CSR16 to 0x00000700, reflecting an empty condition. Unused bit always read back as zero.



CSR 18 controls the full scale time measurement of the MTD133 as well as the LIFO depth. Full scale can be programmed from 0 to 32.768 usec in steps of 8 nsec.



- **MTD133 Full Scale Time Measurement:** Bits 4 - 15 control the MDT133 time measurement full scale. Only time measurements below the programmed value will be registered in the MTD133's internal LIFO.
- **MTD133 LIFO Depth Control:** Bits 0 - 3 control the MTD133's internal LIFO depth which may be set between 1 data word (measured time value) and 16 data words.

Note: CSR18 must be programmed for 32768 usec if module is to be used in Common Start mode.

2.7 FASTBUS Operations

2.7.1 FASTBUS Address cycle

The 1877 TDC responds to geographical, logical and broadcast addressing.

2.7.1.1 Logical Addressing

CSR3<31:16 > contain the logical address to which the 1877 will respond in both CSR space and Data space.

2.7.1.2 Geographic Addressing

The model 1877 responds to geographical addressing in both CSR space and data space.

2.7.1.3 Broadcast Addressing

The following is a list of Broadcast operations responded to by the 1877. The case numbers are from the IEEE 960-1989 Fastbus specification, Table 4.3.2. Example address use G=0 and L=1 for broadcasts on the local FASTBUS segment only.

- **Case 1:** General Broadcast: 0x00000001. All devices respond to subsequent data cycles.
- **Case 2:** Class N Broadcast: 0x00000005. Only devices of class N respond to subsequent data cycles.
- **Case 3:** Sparse Data Scan: 0x00000009: Devices respond by asserting T-Pin during following read cycle if data present.
- **Case 3a:** Sparse Data Scan: 0x00000019. Devices respond by asserting T-Pin if they contain no data or are available for use.
- **Case 4:** 0x0000000D. Devices respond by asserting T-Pin during following read cycle.
- **Case 8-B:** 0x000000BD. Devices respond by asserting T-Pin during following read cycle if the auxiliary card is asserting PCT.
- **Case 8-C:** 0x000000CD. Unique 1877 Sparse Data Scan: 1877 TDCs respond by asserting T-Pin during following read cycle if unsuppressed data is present in the next buffer.

CSR7<3:0 > controls the classes of class N broadcast to which the 1877 will respond in both Data and CSR spaces.

Important note: In some rare cases, the module will not be able to respond to a broadcast primary address cycle within the 500nsec minimum Master/ANC Logic handshake time. In these circumstances, the

module will assert the Fastbus WAIT signal for the period of time required by the slave to properly decode the broadcast.

2.8 Data Space

Data memory in the 1877 TDC is organized in a 16K word circular buffer with eight 2K word pages. Data resulting from an event is stored in one of the eight 2048 word buffers. Each event buffer contains enough addresses to hold the maximum data resulting from a single event (1537 words). An event is defined as the occurrence of a Common Start or Stop.

In the power-up or reset state, Memory Test Mode is disabled, and the 1877 data space consists (from the FASTBUS point of view) of only DSR0; writes to the Data Space NTA have no effect. CSR16 controls the buffer which is currently accessible to Fastbus (read buffer) as well as the buffer which will be used to store the next event readout of the MTD133's (write buffer). At power-up or when a master reset is issued, the next event buffer to be read will be 7, and the next event buffer to be filled will be 0. Once an event occurs and is buffered the write buffer number is automatically incremented. CSR16 is a read-write register which can be used to control the position of the read and write buffers. Under normal operating circumstances, CSR16<10:8> is modified by the Load Next Event command and CSR16<2:0> is modified by the MTD133 readout circuitry. The user should, in general, not need to manipulate CSR16 directly except to re-read and event.

When Memory Test Mode is enabled, any location within the 16K data space is directly accessible via FASTBUS. At any particular time, there are 2048 (one complete buffer) secondary addresses (DSR's) available in data space. The buffer currently accessible can be modified by the Load Next Event command or by writing CSR16 directly.

CSR5<10:0> controls the number of words transferred in a block read. During normal data acquisition, a Load Next Event both advances the read buffer to the next event and loads CSR5<10:0> with the correct word count for the event contained in the next buffer. This can, of course, be done for an entire crate of 1877s at once using a broadcast command. The maximum number of words transferred is limited to one full buffer. Though CSR5 is always maintained in the 1877, it is only visible to Fastbus when Memory Test Mode is enabled.

When the read pointer is one less than the write pointer (modulo 8) the buffers are considered empty. When the read pointer and the write pointer are equal, the buffers are considered full. The condition "not empty" is used for the Sparse Data Scan. The condition "full" is used to extend Buffering in Progress (BIP) until the buffers are not full.

2.8.1 Header Word Format

The first word (zeroth address) of each buffer contains a header word for the event data which follows and is normally the first word readout during a block transfer. This header word contains the word count for that event as well as parity, phase, buffer number, and geographic or logical address of the module. The word count is automatically loaded into CSR5 when a Load Next Event command is issued. After each FASTBUS block transfer data cycle, the word count register is decremented. The parity bit is high or low so as to make the total number of bits in the header word even.

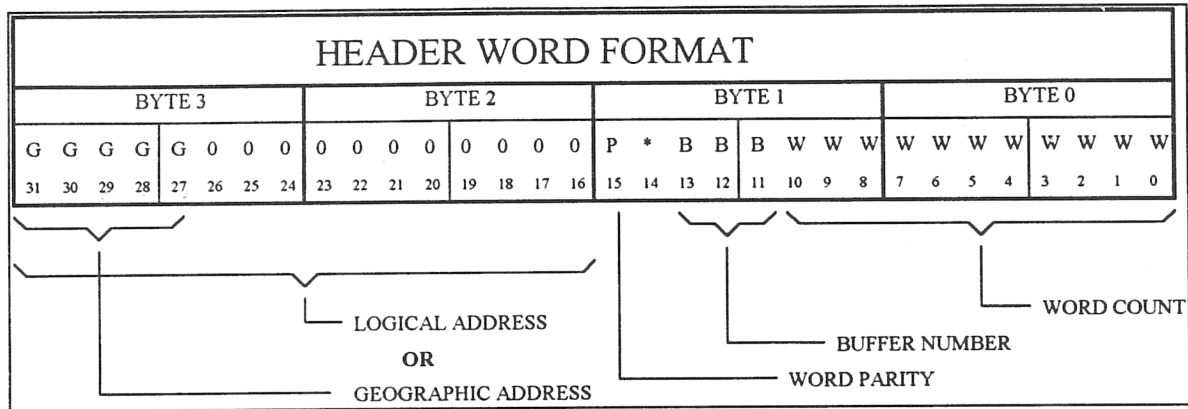


Figure 2-6 1877 Header Word

2.8.2 Data Word Format

The 1877 time data is read out as a 32 bit data word. The 16 least significant bits are the time data, the next bit is the hit phase (denoting leading or trailing edge), and the next 7 bits are the channel identification. The most significant byte contains the geographic address, parity, and the buffer number (modulo 4). The hit phase is one for a leading edge hit and zero for a trailing edge hit. Here again the parity bit is high or low so as to make the total number of bits in the word even.

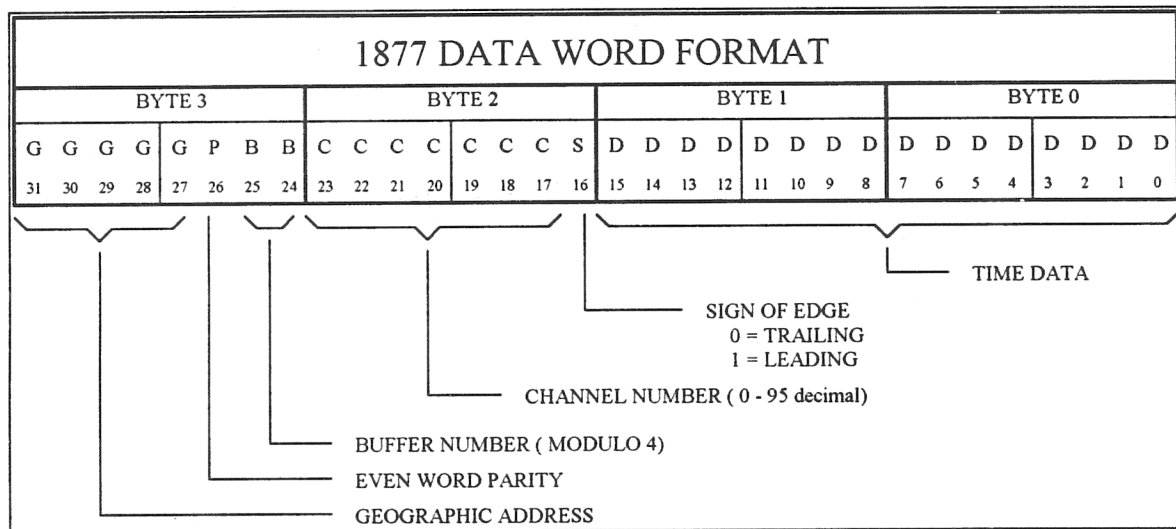


Figure 2-7 1877 Data Word

2.9 Readout

2.9.1 Single Read from Data Space

Reading of the data stored in the multi-event buffer can be done using random read cycles. However, first the correct number of words to read must be ascertained. Assuming Load Next Event has been used to select the desired event to read, the first location of this buffer, the header word, must be read to find out how many words are in the event. Bits <10:0> of the header word contain the word count for the event. This word count is the number of data words plus 1 for the header word itself. With this information the correct number of words for the event can be read by repeated reads to DSR0.

2.9.2 Block Transfer Read from Data Space

Block transfers are the preferred way to read data from the 1877, and this is facilitated by the Load Next Event function, CSR 0<10>. A write to CSR 0<10>, Load Next Event, increments the read pointer by 1 and loads CSR 5 with the word count for that event. This can of course be done for an entire crate at one time using a broadcast. A subsequent block read will transfer data until automatic decrementing of CSR 5 reaches 0, the end of the event's data. The header word for the event is the first word transferred. SS = 2 indicates the end of the block transfer.

2.10 FASTBUS Write to Data Memory

Although not pertinent to data acquisition, it is possible to write to the data memory via Fastbus providing that Memory Test Mode has been enabled. This may be desired for testing. For this purpose, the data memory appears as a 16384 x 32 bit word RAM with the upper three bits of the address being CSR 16<10:8> and the lower 11bits being the Data Space NTA. Data may be written into this RAM using random, or broadcast modes. Block writes to data space are not supported. Since the 1877 event manager is not managing this loading, however, the parity checking, channel identification, and geographic address identification normally present in the data are not present when read back.

2.11 Tester

An on board tester is provided for easy verification of the unit's functionality. When CSR0<7> is written with the internal tester enabled, a test cycle of square wave pulses is initiated. The number of pulses generated can be 1, 2, 4, or 8 as programmed by CSR1<17:16>. The width of the pulses is controlled by CSR1<19:18>. By enabling both leading and trailing edge detection (CSR1<30:29> = 1), and setting the tester to 8 pulses, it is possible to generate 16 measurements on 96 channels.

Since the clock generating the test pulses is asynchronous to the acquisition clock, the tester pulse measurements will have a non-zero standard deviation, typically less than one count. This is, however, usually larger than that attainable using a high quality external source.

2.12 Fast Clears

A fast clear can be applied any time during the fast clear window. This will cause the event just recorded in the front end not to be buffered. The write pointer for the buffer will not be incremented. The buffering situation will be as though the cleared event never took place. This action requires 250 nsec. from the falling edge of the fast clear pulse before the module is ready to accept another event. Fast clears can be applied either from the front panel input, by writing CSR 0<31>, which can of course be done using a broadcast write, or via a model 1810 CAT (TR0). The application of a Fast Clear during the Fast Clear Window will terminate the Fast Clear Window.

2.13 Allocation of Restricted Use Lines

Using CSR1, the 1877 can be enabled to accept Common, Fast Clear Window, and Fast Clear inputs on the TR lines. These lines have been allocated to be compatible with the LeCroy model 1810 Calibration and Timing (1810 CAT) module facilitating distribution of these signals throughout a crate. The assignments are:

TR0 - Fast Clear

TR3 - Test Pulse

TR4 - Auxiliary Card Strobe

TR5 - Fast Clear Window

TR6 - Common

The Fast Clear Window corresponds to the 1810 CAT MPI signal, which can be either programmed internal to the 1810 or supplied via the 1810 front panel. The Common signal corresponds to the 1810 CAT input signal marked TDC Stop. The Test Pulse input corresponds to the 1810 CAT Test Pulse output.

When testing with the 1810 CAT it should be understood that the 1810 was designed for a Common Stop TDC, the LeCroy model 1879. The pulse width of the signal output on TR3 and the delay of the signal output on TR6 can be programmed. The pulse width of the TR6 signal can not be programmed and is nominally 225 nsec. When using the 1877 in Common Stop mode operation is straightforward. The signal on TR6 is used as the Common Stop and the signal on TR3 is used to generate test hits to the channel inputs of the 1877.

With the 1877 set for Common Start mode, the signal from TR6 is used to generate test hits for the channels, and TR3 is used for the Common Start. This is because the 1810 CAT can not change the time ordering of the pulses output on TR3 and TR6; TR3 occurs before TR6. The user must take care in programming the 1810 CAT so that both edges of the TR6 pulse are detectable in Common Start mode. There is also a difference in propagation delays for the two signals on the 1877 of about 15 nsec. This results in a small discrepancy between the time programmed into the 1810 CAT DSR1 and what is actually measured in the 1877. Pulse width measurements should still be accurate.

In both Common Start and Common Stop modes the signal from the 1810 CAT used to generate hits to the channels is always enabled. So if the 1810 CAT is used when acquiring real data in any way that might cause a test cycle, the test pulse from the 1810 CAT must be disabled. This is done in CSR1 of the 1810 CAT.

Additionally the BIP output signal from the 1877 can be enabled to TR7 so that all 1877 TDCs in a crate could be wire OR'ed to produce a crate wide BIP. This practice is, however, incompatible with the use of TR7 by the 1810 CAT. The 1810 uses TR7 to distribute a reference timing signal to 1879 TDC modules. If a 1810 CAT is in the crate, the 1877 CSR1<0> must be set to 0.

2.14 Interface to Auxiliary Functions Card

In order to allow the user to generate fast trigger signals, the 1877 provides 96 trigger pulses to the Fastbus auxiliary connector. These trigger pulses are simply the front panel hit inputs converted to TTL logic levels.

In addition to the TTL trigger pulses, a 12-bit wide bi-directional bus, four address lines and three control lines are also connected to the Fastbus Auxiliary connector. This allows the user to perform read and write operations on the auxiliary functions card (AFC). The AFC is accessed via secondary addresses to control space from 0xC0000000 and 0xC000000F.

The Auxiliary Functions connector also has the facility to allow the AFC to assert the TDC's T-pin in response to a BD_H broadcast read. The AFC need only drive the PCT line low to assert the T-pin.

2.15 Example Code

/* The following are examples of some possible general purpose 1877 subroutines. This code has been compiled but never executed. It is intended only to illustrate the methods. */

```
/* Include these header files for C applications. */
#include <stdlib.h>
/* Program Parameters */
#define ARRAY_SIZE 1536 /* 12 ics * 8 channels * 8 hits * 2 phases=1536 */
#define NO_OF_CHAN 96
#define SLOT 0x00000000BL
```

/* FASTBUS Prototypes; Primitive FASTBUS Action Routines */

```
int fb_cycle_pa_csr(unsigned long slot);
int fb_cycle_pa_data(unsigned long slot);
int fb_cycle_write_word(unsigned long data);
int fb_cycle_read_block(int max_words, unsigned long data[]);
int fb_cycle_read_word(unsigned long * data);
int fb_read_length();
```

/* Prototypes */

```
void master_reset(unsigned long slot);
void setup(unsigned long slot);
unsigned long test_for_buffer();
void skip_event();
int read_event( unsigned long data[], unsigned long slot);
void sort_n_sum( long summed_data[]);
```

/* Routines */

/* The routine 'master_reset' clears the 1877, all is set to the power up state except for the logical address (csr 3h) and broadcast classes (csr 7h). */

```
void master_reset( unsigned long slot )
{
    fb_cycle_pa_csr(slot);
    fb_cycle_write_word(0x40000000L);
    return;
}
```

/* The routine 'setup' selects a particular operating mode for the 1877. */

```
void setup( unsigned long slot)
{
    fb_cycle_pa_csr(slot);
```

/* Enable Common Hits (Presently Common Hits are always enabled and this bit has no effect) */

```
    fb_cycle_write_sa(0x00000000L);
    fb_cycle_write_word(0x00000004L);
```

/* Select Common Start, Rising Edge Detection, Falling Edge Detection, 16 us Fast Clear window, and maximum Common Start Timeout 32 us */

```
    fb_cycle_write_sa(0x00000001L);
    fb_cycle_write_word(0xe70000f0L);
```

```
    return;
```

```
}
```

/* The 'skip_event' routine advances the 1877 buffer pointers on all boards in the crate with a broadcast of the 'Load Next Event' feature. This bit in CSR 0h sets the NTA and word count register (csr 5h) to read the next event. Note the Data Space NTA must not be directly modified for this feature to work properly. Also note that the Secondary Address cycle to Control Space is not required as the 1877 resets the CSR NTA at disconnect */

```
void skip_event() {
```

```
    fb_cycle_pa_csr_multi(0x00000003L); /* General Broadcast */
    fb_cycle_write_word(0x00000400L); /* load next event */
    fb_cycle_disconnect();
```

```
}
```

/* The 'read_event' routine advances the 1877 buffer pointers on all boards with the 'skip_event' defined above. The word count for the block transfer is returned. */

```
int read_event( unsigned long data[], unsigned long slot) {
```

```
    skip_event();
```

```
    fb_cycle_pa_data(slot);
```

```

fb_cycle_read_block(ARRAY_SIZE, data);
fb_cycle_disconnect();

return(fb_read_length()/4);
}

/* The routine 'test_for_buffer' uses FASTBUS broadcasts to poll for full buffers in the 1877. This is a T-pin scan. */

unsigned long test_for_buffer() {

    unsigned long i;
    fb_cycle_csr_multi(0x0000000BL); /* Sparse Data Scan */
    fb_cycle_read_word(&i);
    fb_cycle_disconnect();

    return(i);
}

/* The procedure 'sort_n_sum' processes the data from one 1877 buffer. It is assumed that the 1877 generates exactly the
same number of hits for every event and the sum for each hit is computed. This routine would function for the test modes of
the 1877 to compute the mean of the test pulses. */

int channel_number( unsigned long data )
{ return((data & 0x00FE0000) >> 17); }

int tdc_counts( unsigned long data)
{ return(data & 0x0000FFFF); }

void sort_n_sum( long summed_data[96][16],
                unsigned long *raw_data, int word_count)
{
    int current_channel, current_edge, last_channel, i;

    i = current_edge = last_channel = 0;

    /* Process all the words in the block */
    for (i=0; i word_count; i++) {

        /* Process only data words; Header words have channel = 127 */
        current_channel = channel_number(raw_data[i]);
        if ( (current_channel <= 95) && (current_channel >= 0) ) {

            /* if the channel number has changed, reset edge counter */
            if(current_channel != last_channel) {
                current_edge = 0;
                last_channel = current_channel;
            }

            /* update sums */
            summed_data[current_channel][current_edge] +=
                tdc_counts( raw_data[i]);
            current_edge++;
        }
    }
}

/* The main routine waits for external triggers and processes each event. If the triggers observe the Buffer In Progress (BIP)
hold off signal, a buffer overrun is avoided. */

void main()
{
    long data[ARRAY_SIZE];
    long summed_data[96][16];
    int word_count;
    fb_cycle_disconnect();
    master_reset( SLOT );
    setup( SLOT );
    while ( 1 ) {
        while (test_for_buffer() == 0x0L) {}
    }
}

```



```
word_count = read_event( data, SLOT);  
sort_n_sum( summed_data, data, word_count );  
}  
}
```


3. Installation

3.1 General Installation

The LeCroy Model 1877 Time to Digital Converter is intended for use within a FASTBUS crate with the following voltage sources properly connected to the backplane: +5.0 V, -5.2 V, -2.0 V, +15.0 V, and -15.0 V. The crate should be an ECL implementation. If an Aux. card is to be used, e.g. for trigger outputs, the Fastbus crate must include a 195 pin/connector auxiliary backplane. Each crate must be controlled by a crate master such as a LeCroy Model 1821 SM/I. Its purpose is to execute standard FASTBUS cycles for control of the module and transfer of data. A processor interface of some sort is necessary to communicate with the crate. A LeCroy Model 1821/DEC interface card with either a DEC DR11-W Unibus or a MDB DRV11-2 Qbus parallel I/O board can be used with the DEC computer line. A less expensive way of getting started, useful for a small number of crates, is to use an IMB PC/AT or compatible with a LeCroy Model 1691A Interface Card. The 1691A plugs into a slot in the PC and it is connected via a 34 conductor multiwire cable to the front panel of an 1821 SM /I.

The software package LeCroy Interactive FASTBUS Tool kit (LIFT) is now available for the LeCroy Model 1691A/IBM PC system providing the user with a substantial package of software to exercise and test FASTBUS modules using a LeCroy Model 1821 SM /I. LIFT also includes an extensive library which the user may employ in the development of user specific data acquisition software.

Either with the power on or off, the 1877 is inserted into one of the slots of the FASTBUS crate. The edge connector of the module should mate with the bus connector with modest pressure. Note the slot number of the module, as it will later be used for addressing.

3.2 Cables

The use of twisted-pair cables generally results in lower cabling costs and typically higher density and is usually adequate for digital signals. Thus the 1877 was designed to accept 34 conductor ribbon cable. If using twisted-pairs, care should be taken to install high quality, shielded cables to minimize the effects of noise and crosstalk. Many of such cables can be purchased from LeCroy Corporation. In particular, there are two types of 34 conductor multiwire cables available, one for short connections using flat cable and the second for long connections using twisted and flat ribbon cable.

The model numbers of such cables are as follows:

STC-DC /34/L - flat multiwire cable for short interconnections

LTC-DC /34-L or DC2 /34-L - twisted-pair multiwire cable for long interconnection.

STP-DC /02-L - single twisted-pair cable, 3 ft maximum length

NOTE that L is the length in feet that must be specified by the user.

All inputs are differential ECL and terminated by 112 ohms. The terminations are SIP components and may be easily replaced to accommodate other characteristic impedances.

4. Theory of Operation

4.1 General Description of Buffer Architecture

The buffer memory on the 1877 is a 16K word SRAM structure with a word width of 32 bits. The memory is constructed out of eight 8K x 8, 12ns SRAM. Access to the buffer memory from the module's front end (i.e. MTD readout) and from Fastbus is completely interleaved, resulting in a synchronous dual-ported memory.

Readout of events from the MTD's into the buffer memory can occur at a maximum rate of 20MHz while readout of the buffer memory to Fastbus via Block transfers can proceed at a rate up to 10MHz. It is important to note that front end/Fastbus access to the memory is synchronous and interleaved 2:1. This means that the maximum transfer rate to Fastbus will always be exactly half of the front-end readout rate which is itself half of the 40MHz system timebase. Additionally, since the Fastbus interfacing circuits are operating from the same clock as the memory control circuits, DK and AK response times are also a function of the 40MHz timebase.

Figure 4-1 shows a simplified block diagram of the 1877 data paths. Event data is readout of the MTD's through a pipeline at 20MHz into the buffer memory. The pipeline stage is required to achieve proper synchronism with the memory as well as compute the data word parity. Events are readout to Fastbus through a two stage pipeline at up to 10MHz, depending on the speed of the Master. The Fastbus readout pipeline stages are required to maintain the maximum transfer rate to the asynchronous Fastbus. The addresses for front-end and Fastbus access are multiplexed at a rate of 40MHz.

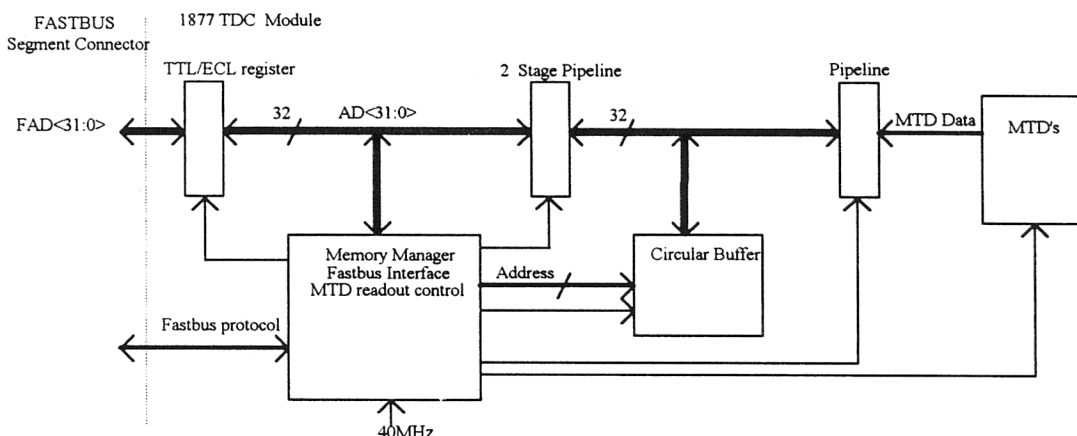


Figure 4-1 Simplified 1877 Interface/Buffer Block Diagram

4.1.1 Multi-Event Buffer Memory Organization

The 16K memory is logically partitioned into pages, each representing a separate event buffer. For the 1877, there are eight 2K pages or buffers. Since there are a maximum of 1536 data words per event, each page of memory can hold one complete event.

4.1.2 Buffer Memory Pointers

The eight individual buffers are logically organized as a circular buffer structure. Two pointers are maintained into the circular buffer memory - MTD Write Pointer (MWP) and Fastbus Read Pointer (FRP). Each pointer is really made up of two separate pointers: a page pointer - Read Page (RP) and Write Page (WP) - and an address pointer within a that page - Read Page Address (RPA) and Write Page

Address (WPA). See Figure 4-2. How the buffer pointers are controlled depends on the operational mode of the module.

Fastbus Read Pointer (FRP): The Read Page (RP) can be manipulated directly by writing to CSR 16. RP may also be effected through the use of the Load Next Event (LNE) command which prepares the module for Fastbus readout. A LNE command would have the effect of incrementing RP so that the FRP is advanced to the next buffer in the circular structure. In the default mode of the module, the Read Page Address (RPA) is not accessible to the user. In Memory Test Mode, however, the RPA becomes the Data Space Next Transfer Address and may also serve as a write pointer to Data Space. See section 4.3.2.2 for discussion of Memory Test Mode.

MTD Write Pointer (MWP): The Write Page (WP) can be manipulated directly by the user by writing to CSR 16. Otherwise, WP is maintained by the front-end MTD readout circuits. The Write Page Address (WPA) is maintained solely by the front-end MTD readout circuits and is not accessible to the user in any way.

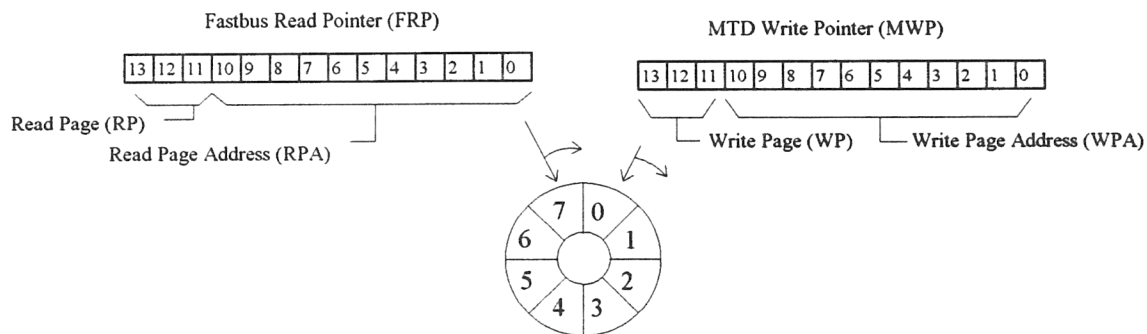


Figure 4-2 1877 Circular Buffer

4.1.3 Buffer Full/Empty Conditions

Upon power up of the module or Master Reset via Fastbus command, the MTD Write Pointer is pointing to the beginning of buffer zero and the Fastbus Read Pointer is pointing to the beginning of buffer seven. See Figure 4-2. This relative positioning of the pointers, that is the read pointer one buffer behind the write pointer, defines the Empty Condition. Conversely, the Full Condition is defined at the case where the write pointer is one buffer behind the read pointer. The Full and Empty conditions as described apply before a LNE is issued: i.e. if a single event is in the buffer and a LNE is issued, the Empty condition would be true even though an event is now ready for readout.

As events are readout of the MTD's into the circular buffer, the WP is incremented to point to the next available buffer. Similarly, as events are prepared for readout via Fastbus using the Load Next Event (LNE) command, RP is incremented to point to the next event which will be read out of the circular buffer. For example, after one event has been completely buffered (after power-up or reset) WP would be at buffer one and WPA would be zero. RP would be at buffer seven and RPA would be zero. A subsequent Load Next Event would prepare the module for Fastbus readout of that event by incrementing RP to buffer zero. See section 4.4.1 for further discussion of Load Next Event.

4.2 Acquisition and Buffering

4.2.1 Readout of MTD's

Readout of event time data from the MTD's begins either upon receipt of a common hit (in common stop mode) or at the end of the common start timeout period (in common start mode). During the time that the module is buffering event data, the signal Buffering In Progress (BIP) is asserted. Data words are written

into the buffer currently pointed to by WP starting at the location pointed to by WPA. If the module receives a Fast Clear during its programmed Fast Clear Window, the event just buffered (or being buffered) is discarded - WP is not incremented and WPA is cleared.

4.2.2 Organization of Data in Events

As data words are written to memory, the WPA is incremented until all data words have been readout of the MTD's. BIP is then deasserted and a header word (which is the complete buffer address of the last data word) is written into Write Page Address zero, the first memory location of the page. In this manner, all events, once completely buffered, consist of a header word in the first memory location of a given buffer (page) followed by the data words for that event. Further, since the header word contains the absolute memory location one beyond the last data word for that event, it reflects both the buffer number (within the circular buffer structure) and the complete word count for that event including the header word itself. If an event occurs which has no data words - a null event - a header word with a word count of one is still written and the MTD Write Pointer is advanced to the beginning of the next buffer.

4.3 Fastbus Access to Module

4.3.1 Control and Status Registers

Several Control and Status Registers (CSR's) control the configuration and operation of the 1877. The following is a list of the CSR's contained in the 1877 and a brief description of their function(s):

CSR0, CSR1 - primary control and configuration registers. These registers contain the configuration bits for all operational modes of the 1877. Additionally, CSR0 contains pulsed bits which initiate operations specific to the module such as Master Reset, Load Next Event, internal test cycles, etc.

CSR3 - Logical Address

CSR5 - Block transfer word count register. CSR5 controls the number of words which will be transferred during a block transfer. A SS=2 response is generated by the module when CSR5 has decremented to zero during a block transfer. This register is read/write and may be loaded with an arbitrary value up to 7FFh (one full buffer). CSR5 is loaded automatically with the word count for the next event when the module is prepared for readout of an event using a LNE command.

CSR7 - Controls Class-N broadcast response

CSR16 - Buffer Status register. CSR16 contains the Read Page (RP) and Write Page (WP) of the Fastbus Read Pointer and the MTD Write Pointer, respectively. This register, therefore, indicates to which buffer, in the circular buffer structure, each of the pointers is pointing. CSR16 is read/write and can be used to directly manipulate the positions of the read and write pointers within the circular buffer. In the 1876/1881, CSR16 is read-only and cannot be used to directly control the positions of the pointers.

CSR18 - MTD configuration register. CSR18 holds the full scale time measurement and internal MTD LIFO depth.

4.3.2 Secondary Addressing in Data Space

Data is readout of the module via Fastbus by first accessing the module through a primary address cycle to Data Space and then performing subsequent read data cycles. In the default operational mode, secondary addressing in Data Space is not relevant. A second operational mode, Memory Test Mode, is provided which supports secondary addresses in Data Space and allows direct access to any buffer memory location within the 16K Data Space.

4.3.2.1 Default Addressing Mode

The default addressing mode, which does not support secondary addressing in Data Space, is primarily useful if the Fastbus readout method is a block transfer. In this mode, writes to the Data Space NTA is acknowledged but ignored. There is, in effect, only one location in Data Space, DSR0.

For block transfers in this mode, each individual buffer appears similar to a FIFO. For example, assume that the module has been prepared for readout (i.e. a Load Next Event command had been previously issued.). The first data word transferred during a block read is the event header word. This header contains the geographic (or logical) address, parity, and the absolute address (in the 16K word circular buffer memory) of the last valid data word of the event being readout. The absolute address contains the buffer number, RP (also available in CSR16) and the word count including the header word, RPA for the last data word written to memory. Subsequent transfers produce the event data words in a similar manner to a FIFO until all valid data words in the event have been transferred and the module generates SS=2.

The RPA is incremented after each read to point the next word in the buffer during the block transfer. Random reads from Data Space must be used with care since the location of RPA (not visible to Fastbus) is not known except under very specific circumstances. Random reads will increment the RPA and thus can be used to readout the module in a way similar to a FIFO however no indication will be given when the end last valid data word has been readout. The number of words to readout by this method must be ascertained from the header word.

In the default readout mode, re-reads of a particular buffer are not directly supported since it is difficult to be certain, after the event has initially readout via block transfer, what the value of RPA is. Re-read of a buffer may be accomplished indirectly by manipulating RP via CSR16 and issuing a Load Next Event command. See Section 4.4 - Mechanisms for Fastbus Readout.

4.3.2.2 Memory Test Mode (MTM)

Memory Test Mode (MTM) is an operational mode selectable via CSR0 which supports secondary addressing in Data Space. In this mode, the RPA portion of the Fastbus Read Pointer is accessible as the Data Space Next Transfer Address (NTA). Additionally, CSR5, the block transfer word count register, is accessible to Fastbus as an 11bit read/write register.

In MTM, the 1877 buffers must be thought of as a paged memory, circular buffer scheme, *not a FIFO*. Random read or write data cycles may operate on any location addressable by the current RPA. By manipulating RP (via CSR16) and NTA, any location in the 16K Data Space can be addressed for reads or writes. This mode facilitates memory testing but may also serve as a very useful operating mode, depending on the specific user application. As per the Fastbus specification, RPA and therefore NTA is only incremented during block reads. Block writes are not supported in the 1877.

Block transfers are controlled in exactly the same way as with the default mode except that RPA is now accessible as the Data Space NTA and may be set by the user. In all cases, CSR5 controls the number of words transferred during a block transfer and RPA controls the address within the buffer where the transfer will begin. RPA (and therefore NTA) is incremented with each word transferred during a block transfer. If $CSR5 > (2048 - RPA)$, then RPA will wrap around back to the beginning of the page.

In contrast to MTM in the 1876, the 1877 NTA appears as only 11 bits so there is no need for the user to keep track of the Read Page to avoid accidentally changing the page to which the Fastbus Read Pointer is pointing. This allows existing user software that always writes the secondary address before beginning a transfer to operate without modification.

Though not recommended, it is possible to operate the module in Memory Test Mode with Priming on LNE enabled. The user must be aware that the priming operation causes the RPA to be incremented and

CSR5 to be decremented as the pipeline is filled. When in MTM, the RPA is visible to FASTBUS as the Data Space NTA and is affected in a way not compliant with the FASTBUS specification.

4.4 Mechanisms for Fastbus Readout

To avoid possible corruption of an event that has not yet been readout, only seven consecutive events may be buffered before the circular buffer becomes FULL. When this condition exists, the MTD Read Pointer must be advanced, either by issuing an LNE or manipulating CSR16 before additional events can be buffered. Several broadcast operations are implemented to monitor the 1877 buffering status.

Sparse Data Scan (case 3, code 0x09): Assert Tpin on following read cycle if one or more events are buffered and available for readout

Device Available Scan (case 3a, code 0x19): Assert Tpin on following read cycle if the circular buffer is Empty.

1877 Unique Sparse Data Scan (case 8-c, code 0xCD): Assert Tpin if CSR5 = 1. This scan only has meaning after a Load Next Event command has been executed. It is used to determine if the event just loaded has unsuppressed data words. Note: all buffered events will have at least a header word. Also, although CSR5 is only accessible to Fastbus in Memory Test Mode, it is always maintained internally to control the number of words transferred during a block transfer.

4.4.1 Load Next Event

The Load Next Event (LNE) command is provided to prepare the module for readout after one or more events has been completely buffered. Assuming there is at least one event in the buffer, a LNE command advances the Read Page (RP) to the next buffer (the buffer to be readout), clears the Read Page Address (RPA), and copies the word count found in the header (of the event to be readout) to CSR5. A LNE issued when no events are available to readout is ignored since this would result in either an old event being loaded or CSR5 loaded with a meaningless value.

In order to reduce the time required by the module to begin a block transfer, LNE can also prime the two stage readout pipeline - see Figure 4-1. The priming during LNE is enabled by setting bit CSR0<8>. In the module's default data space addressing mode, this action is transparent to the user. In MTM however, the result of this action is to increment the data space NTA twice prior the first data transfer. Priming of the readout pipeline does not prevent access to any of the 1877's internal registers.

4.4.2 Block Transfers from Data Space

The normal method of reading event data out of the buffer memory is Fastbus Block Transfer. In the default data space addressing mode of the unit, block transfers (in combination with the Load Next Event command) is the recommended method to access event data.

In all cases, Fastbus block reads are controlled by CSR5 and the Read Page Address (RPA). RPA may or may not be visible to the user as the Data Space NTA depending on the operational mode of the module. Also, CSR5 is only visible to FASTBUS when in MTM. CSR5 is decremented with each block read transfer until CSR5 = 0, resulting in SS = 2.

A typical implementation for a crate full of TDCs might be as follows:

- Determine if data is available for readout. This determination would be made based on either Sparse Data Scans or trigger information.

- Issue a broadcast LNE to prepare all TDCs in the crate for readout. If readout of a particular event is not required, additional LNE's can be issued to effectively skip an event in the buffer (providing additional events are available to readout)
- Address each module in data space and perform a block read.

Re-reads of a particular buffer are possible but not directly supported. In order to re-read a buffer when *not* in MTM, the Read Page (RP) must be set to the buffer preceding the buffer to be re-loaded by writing to CSR16. A LNE must then be issued to reload CSR5 and reset the Read Page Address (RPA).

In Memory Test Mode, the user has complete control over the data space NTA as well as the block transfer word count (CSR5) and Read Page pointer (CSR16). Re-reads can be accomplished as with non-MTM. Additionally, the user can re-read any buffer by setting RP to the buffer to be read, fetching the word count for that event from the first location in that buffer (using a random read from Data Space), and loading CSR5 directly with the block transfer word count.

4.4.3 Multi-Module Data Transfers (Multi-Block)

The 1877 fully supports the Multi-Module Data Transfer (MDT-1) specification. The modules participating on the Multi-Block scan must be in adjacent slots with the left most module (highest slot number) programmed as the Primary Link and the right most (lowest slot number) programmed as the End Link. The modules between the Primary and End (if any) must be programmed as either Bypass (default) or Middle Links. It is permissible for non-participating modules to be within the Multi-Block array as long as their Fastbus daisy chain lines are appropriately connected to pass the Multi-Block token through.

Assuming a group on 1877 modules has been configured for a MDT scan as per the specification, it must first be established that all modules involved in the scan have data available. This could be done, for example, through a broadcast LNE. The scan is initiated by addressing the primary link and beginning a Fastbus block read. The scan proceeds with each module participating, in turn, in the block read until the end link completes its transfer and issues SS=2.

It is important to realize that if all data words in an event are suppressed (a null event), a header word is still written into the buffer for that event. Thus, a module participating in a Multi-Block scan which has a null event loaded for readout will still transfer the header word during its portion of the transfer.

Important Note: All modules participating in a MDT scan must have

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PART NUMBER	DESCRIPTION REMARK	QTY PER
190662560	RESISTOR NETWORK 56 OHMS RN26-RN97	72
205910256	IC 256K SERIAL PROM 17256 U61	1
229020055	TRANS VOLT SUPPR P6KE6.8 CR4 CR5	2
229020145	TRANS VOLT SUPPR P6KE18 CR2 CR3	2
256432212	DIODE LED (YEL) TIL212-1 CR49	1
256532232	DIODE LED (GRN) TIL232-1 CR1 CR50 CR51	3
300050001	CHOKE FERRITE SINGLE LEAD L4 L5 L8-L10	5
309040080	CRYSTAL OSCILLATOR 80 MHZ XTAL1	1
309090250	CRYSTAL OSCILLATOR 250MHZ XTAL2	1
400311008	SOCKET IC SOLD TAIL DIP-8 U61 U207	2
403119234	HDR DBL ROW RT ANGL 34 J19-J24	6
403181002	HDR SINGL ROW STRAIGHT 2 J7-J18	12
405812002	SOCKET STRIP SOLDR 20 POS RN26-RN97	24
433220001	FUSE PICO II 125V 10 AMP F3 F4	2
433220003	FUSE PICO II 125V .5 AMP F1 F2	2
433221007	FUSE PICO II 125V 7 AMP F5	1
454112009	HDR STRAIGHT SOLDER TAIL/MALE 9 J5	1
454310003	HDR SOLD TAIL/MALE 3 J3	1
454311006	HDR SOLD TAIL/WW 6 J26-J28	3
454370002	SHUNT 2 POS	7
454713008	HDR SOLD TAIL/MALE 8 J25	1
454720130	HDR SOLD TAIL/FEM 130 P1 P2	2
468099008	TEST POINT W/GLASS INSULATOR TP1 TP4 TP7 TP8 TP14 TP16 TP20 TP24 TP25 TP27-TP32	15
500460005	MOUNTING KIT FOR TO-220	1
524440020	STANDOFF SWAGED 4-40X.360	2
540303002	SIDE COVER FASTBUS (LEFT)	1
540305001	MOUNTING BLOCK FASTBUS #1	1
540307030	STIFFENER FOR 1876 FASTBUS	2

PART NUMBER	DESCRIPTION REMARK	QTY PER
555083374	THUMB NUT (CUSTOM) .374 DIA	2
559440004	SCREW 4-40 SLOTTED 1/4"	21
560440012	SCREW PHILIPS 4-40X3/4	2
567440004	SCREW FLAT PHIL 4-40X1/4	1
568440004	SCREW FLAT PHIL 4-40X1/4	10
597000100	SHIPPING CARTON (FASTBUS PAD)	1
701876002	STIFFENER FOR 1876	1
711877000	PC BD PREASS'Y 1877	1
721877001	FRONT PANEL 1877	1
MTD133A	IC MULTIHIT TDC MTD133A	12
	U122 U123 U125 U126	
	U128 U129 U133 U134	
	U136 U137 U139 U140	
SM185457202	RES VARI CERMET 2 K	1
	R235	
SM190342221	RES NETWORK 220 OHMS	1
	RN10	
SM190342560	RES NETWORK 56 OHMS	1
	RN98	
SM190361222	RES NETWORK 2.2K	2
	RN1 RN6	
SM190362101	RES NETWORK 2% 100 OHMS	18
	RN2 RN8 RN9	
	RN12-RN25 RN99	
SM190362103	RES NETWORK 10 K	4
	RN3 RN4 RN7 RN11	
SM200160101	IC OR-NOR GATE 10H101	1
	U118	
SM200167104	IC 2-IN AND GATE 10H104	2
	U71 U108	
SM200167131	IC M-S TYP D FLOP 10H131	2
	U1 U117	
SM200170020	IC QUAD OR GATE 74F02D	1
	U58	
SM200172000	IC 2-INPUT NAND 74F00	1
	U24	
SM200172008	IC AND GATE 74F08	1
	U65	
SM200172074	IC D-TYP FLOP 74F74	4
	U16 U57 U68 U206	
SM200172574	IC OCTAL D FLIP FLOP 74F574	4
	U40 U42 U44 U83	
SM200178008	IC 2-INPUT AND HCT08	2
	U8 U26	
SM200267136	IC HEX COUNTER 10H136	1
	U9	
SM200272161	IC 4-BIT SYNCHR COUNTER 74F161	5
	U4 U7 U12 U19 U20	
SM200274221	IC MONOST MULTIVIBR LS221	2
	U141 U142	
SM200276020	IC 14-STAGE RIPPLE COUNTER 74HC4020	1
	U5	

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PART NUMBER	DESCRIPTION REMARK	QTY PER
SM200278040	IC COUNTER HCT4040 U6	1
SM200471843	IC 9-BIT BUS INT LATCH 74F843 U79 U81 U87 U90 U97 U102 U112	7
SM200472280	IC PARITY GEN/CHEK 74F280 U38 U56 U59 U60	4
SM201177377	IC OCTAL FLIP FLOP 74F377 U46 U48 U50 U52	4
SM204042015	IC LINE RECEIVER 10114 U145-U148 U151 U152 U155-U158 U161 U162 U165-U168 U171 U172 U175-U178 U181 U182 U185-U188 U191 U192 U195-U198 U201 U202 U204 U205	38
SM205229256	IC 32KX8 STATIC RAM U29 U31 U33 U35	4
SM205620574	IC FAST CMOS OCTAL D 74FCT574 U80 U88 U103 U113	4
SM205720016	IC PAL 16L8D DO NOT INCLUDE ON KIT. SEND TO THE PROGRAMMING CENTER FOR PROGRAMMING. U36	1
SM205721166	IC PAL 16R6 U208 DO NOT INCLUDE ON KIT. SEND TO THE PROGRAMMING CENTER FOR PROGRAMMING.	1
SM205728020	IC PAL 20L8 DO NOT INCLUDE IN KIT. SEND TO THE PROGRAMMING CENTER FOR PROGRAMMING. U13 U14	2
SM205728210	IC PALC22V10-25 DO NOT INCLUDE ON KIT. SEND TO THE PROGRAMMING CENTER FOR PROGRAMMING. U10 U11 U15	3
SM205784008	IC LOGIC CELL ARRAY 4008 U66 DO NOT SEND LOOSE, THIS DEVICE MUST BE HANDLED WITH CARE AND KEPT IN ITS	1

PART NUMBER	DESCRIPTION REMARK	QTY PER
SM205784008	IC LOGIC CELL ARRAY 4008 PROTECTIVE PACKAGE.	1
SM206367605	IC HEX ECL TO TTL REGISTER U45 U54 U55 U62	4
SM206670574	IC 8-BIT REGISTER 74FCT2574 U21 U22 U23	3
SM206886640	IC OCTAL BUS TRANSCEIVER 74LS640 U63 U64	2
SM207160111	IC CLOCK DRIVER 10E111 U121 U132	2
SM207170541	IC BUFFER/LINE DRIVER FCT2541 U37 U39 U41 U43 U47 U49 U51 U53 U76 U84	10
SM207178244	IC LINE DRIVER F244 U3 U82 U89 U96 U104 U105 U114-U116	9
SM207179244	IC BUFFER/LINE DRIV HCT244 U91 U92 U98 U99 U106	5
SM207285541	IC OCTAL ECL-TO-TTL TRANSLATOR U70 U73 U74 U77 U85 U100 U110	7
SM207360124	IC TRANSLATOR MC10124 U25 U27 U107	3
SM207360125	IC TRANSLATOR MC10125 U69 U143 U144 U149 U150 U153 U154 U159 U160 U163 U164 U169 U170 U173 U174 U179 U180 U183 U184 U189 U190 U193 U194 U199 U200 U75 U93	27
SM207367125	IC TRANSLATOR 10H125 U2 U109	2
SM207385543	IC OCTAL TTL TO ECL TRANSLATOR U67 U95	2
SM207385578	IC OCTAL TTL TO ECL TRANSLATOR U78 U86 U101 U111	4
SM207461116	IC ECL QUINT DIFF LINE REC 10E116 U17 U119	2
SM207960158	IC 2-IN MPX 10H158 U94	1
SM208271696	IC MICRO P SUPRVSR ADM696 U72	1
SM208470353	IC DUAL OP AMP LF353 U18 U120 U124 U127 U130 U131 U135 U138 U203	9
SM236030099	DIODE SO-PKG BAV99 CR37-CR48	12
SM240215231	DIODE 5.1V ZENER CR7-CR10 CR12-CR15 CR17-CR36 CR53	29

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PART NUMBER	DESCRIPTION REMARK	QTY PER
SM253032810	DIODE SCHOTTKY 2810	4
	CR6 CR11 CR16 CR52	
SM280140034	TRANSISTOR POWER MOSFET IRF9Z34S	1
	Q1	
SM300095151	INDUCTOR WOUND 150NH	3
	L1-L3	
SM300095271	INDUCTOR WOUND 270 NH	2
	L6 L7	
SM400100020	SOCKET SMT TO SMT 20-PIN	1
	U36	
SM400100028	SOCKET SMT TO SMT 28-PIN	5
	U10 U11 U13 U14 U15	
SM400100068	SOCKET SMT TO SMT 68-PIN	12
	U122 U123 U125 U126	
	U128 U129 U133 U134	
	U136 U137 U139 U140	
SM653181256	RES THICK FILM 1% 37.4 OHMS	7
	R240-R246	
SM653181268	RES THICK FILM 1% 49.9 OHMS	43
	R1 R2 R4-R9 R15	
	R18 R34 R35 R36	
	R93 R94 R101 R102	
	R116 R117 R119 R120	
	R126 R127 R129 R130	
	R142 R143 R146 R147	
	R152 R153 R167 R168	
	R170 R171 R179 R180	
	R182 R183 R189 R190	
	R213 R214	
SM653181297	RES THICK FILM 1% 100 OHMS	44
	R3 R10 R19 R20	
	R95 R96 R115 R118	
	R125 R128 R131 R132	
	R139 R144 R166 R169	
	R172 R173 R178 R181	
	R188 R191-R200	
	R202-R212 R215 R237	
SM653181314	RES THICK FILM 1% 150 OHMS	4
	R21 R23 R30 R31	
SM653181330	RES THICK FILM 1% 221 OHMS	7
	R22 R24 R25 R29	
	R219 R220 R249	
SM653181338	RES THICK FILM 1% 267 OHMS	31
	R11 R103-R114	
	R154-R165 R227 R228	
	R231-R234	
SM653181393	RES THICK FILM 1% 1.00 K	20
	R16 R17 R26 R27	
	R28 R32 R98 R99	
	R122 R123 R134 R135	
	R148 R151 R175 R176	
	R185 R186 R248 R304	

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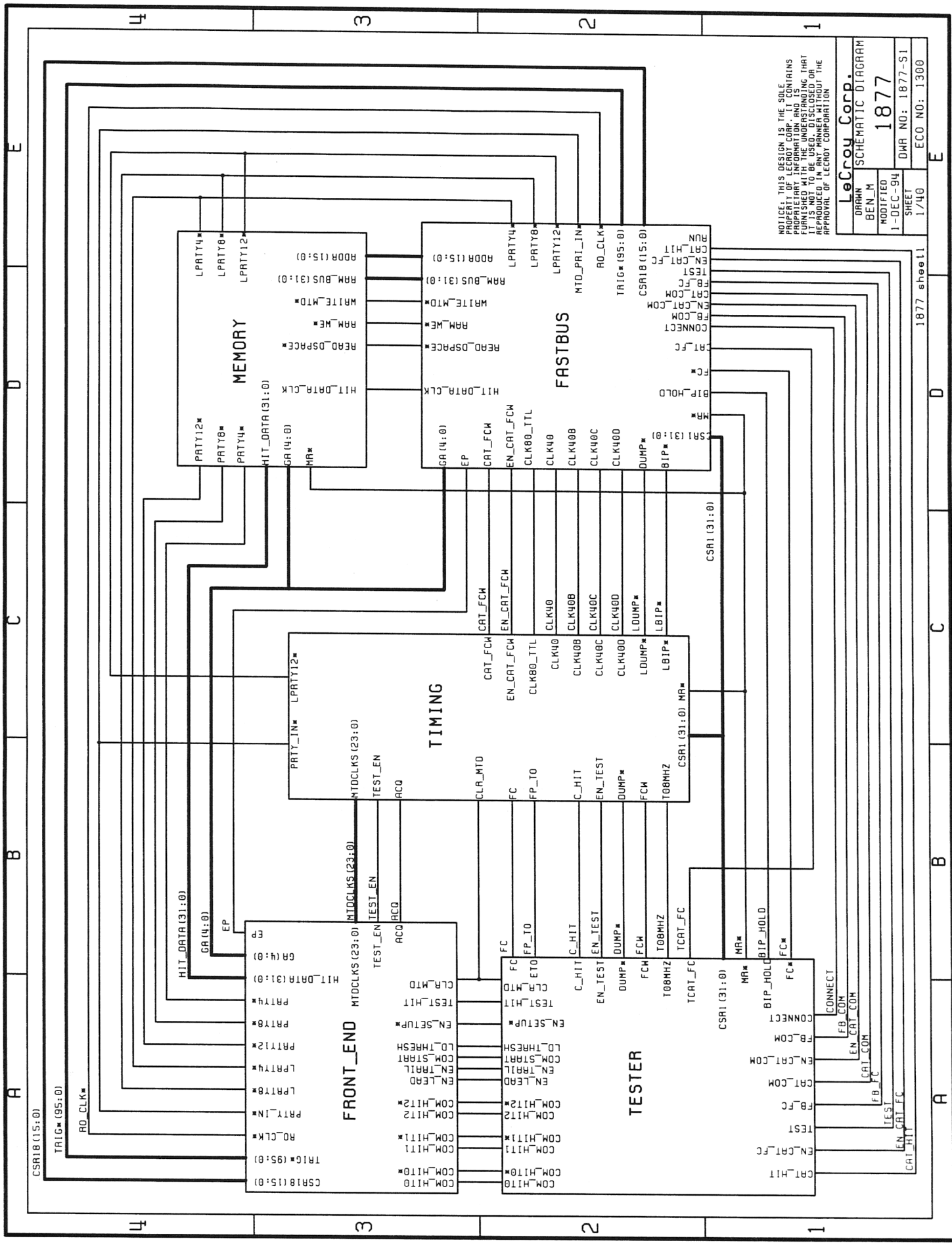
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SM653181422	RES THICK FILM 1% 2.00 K R14 R33 R140 R141 R216 R222 R225	7
SM653181443	RES THICK FILM 1% 3.32 K R12 R37-R40 R45-R48 R53-R56 R61-R64 R69-R72 R77-R80 R85-R88 R230 R223	31
SM653181458	RES THICK FILM 1% 4.75 K R97 R100 R121 R124 R133 R136 R149 R150 R174 R177 R184 R187 R224 R236	14
SM653181481	RES THICK FILM 1% 8.25 K R221 R318	2
SM653181489	RES THICK FILM 1% 10.0 K R145 R238 R239 R247 R306-R317 R320	17
SM653181518	RES THICK FILM 1% 20.0 K R13 R41-R44 R49-R52 R57-R60 R65- R68 R73-R76 R81-R84 R89-R92 R137 R138 R226 R229 R319	34
SM653181614	RES THICK FILM 1% 200 K R217 R218	2
SM661207102	CAP CERA CHIP 20% .001 UF C31 C135-C137 C150 C151 C155-C157 C547 C558-C610 C612 C622	65
SM661207103	CAP CERA CHIP 20% .01 UF C6 C206-C217 C280-C291 C342 C439 C441 C442 C444 C448-C543	126
SM661207104	CAP CERA CHIP 20% .1 UF C1-C5 C7-C23 C25 C26 C28 C29 C30 C32-C40 C46-C96 C98 C99 C100 C103 C106-C134 C138-C149 C152 C153 C154 C158-C197 C199 C201-C205 C218-C231 C234-C251 C254-C270 C272 C274-C279 C292-C302 C305-C323 C326-C341 C343-C348 C351 C353-C438 C440	397

PART NUMBER	DESCRIPTION REMARK	QTY PER
SM661207104	CAP CERA CHIP 20% .1 UF C443 C445-C447 C545 C546 C550-C557 C611 C620 C621 C623-C625	397
SM661255056	CAP CERA CHIP 5.6 PF C27 C198 C200 C232 C233 C252 C253 C271 C273 C303 C304 C324 C325 C24	14
SM661255220	CAP CERA CHIP 5% 22 PF C43 C45 C544	3
SM661255390	CAP CERA CHIP 5% 39 PF C102 C105 C349	3
SM661506684	CAP CERA CHIP 10% .68 UF C350 C352	2

End of report. 325 Details encountered.

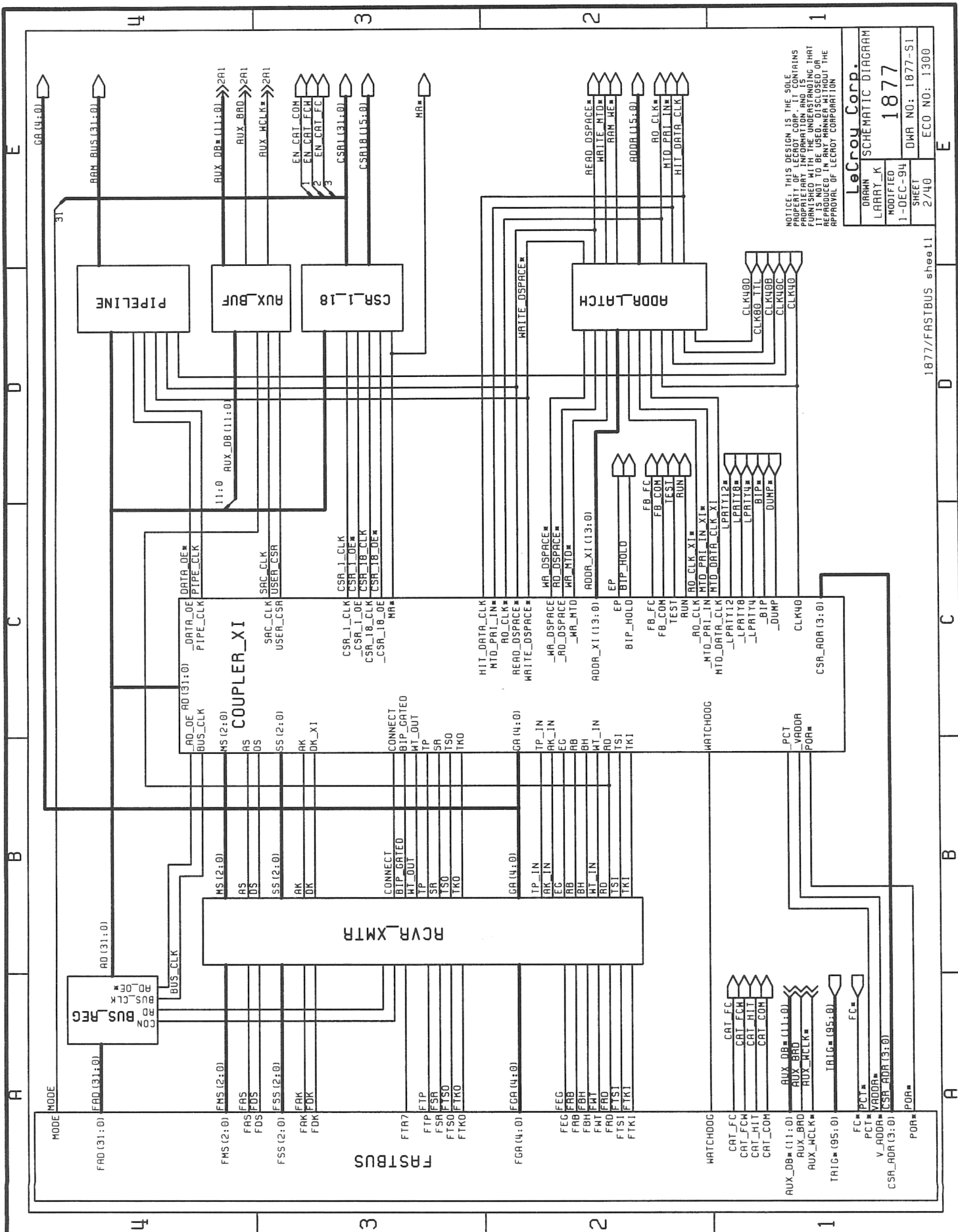
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3 1877/fastbus/addr_latch sheet1
4 1877/fastbus/aux_buf sheet1
5 1877/fastbus/bus_register sheet1
6 1877/fastbus/coupler_xi sheet1
7 1877/fastbus/csr_1_18 sheet1
8 1877/fastbus/fastbus sheet1
9 1877/fastbus/fastbus sheet2
10 1877/fastbus/fastbus sheet3
11 1877/fastbus/fastbus sheet4
12 1877/fastbus/fastbus sheet5
13 1877/fastbus/pipeline sheet1
14 1877/fastbus/rcvr_xmtr sheet1
15 1877/front_end sheet1
16 1877/front_end sheet2
17 1877/front_end sheet3
18 1877/front_end sheet4
19 1877/front_end sheet5
20 1877/front_end sheet6
21 1877/front_end sheet7
22 1877/front_end sheet8
23 1877/front_end/fe_int_0 sheet1
24 1877/front_end/fe_int_1 sheet1
25 1877/front_end/fe_int_10 sheet1
26 1877/front_end/fe_int_11 sheet1
27 1877/front_end/fe_int_2 sheet1
28 1877/front_end/fe_int_3 sheet1
29 1877/front_end/fe_int_4 sheet1
30 1877/front_end/fe_int_5 sheet1
31 1877/front_end/fe_int_6 sheet1
32 1877/front_end/fe_int_7 sheet1
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38 1877/tester sheet1
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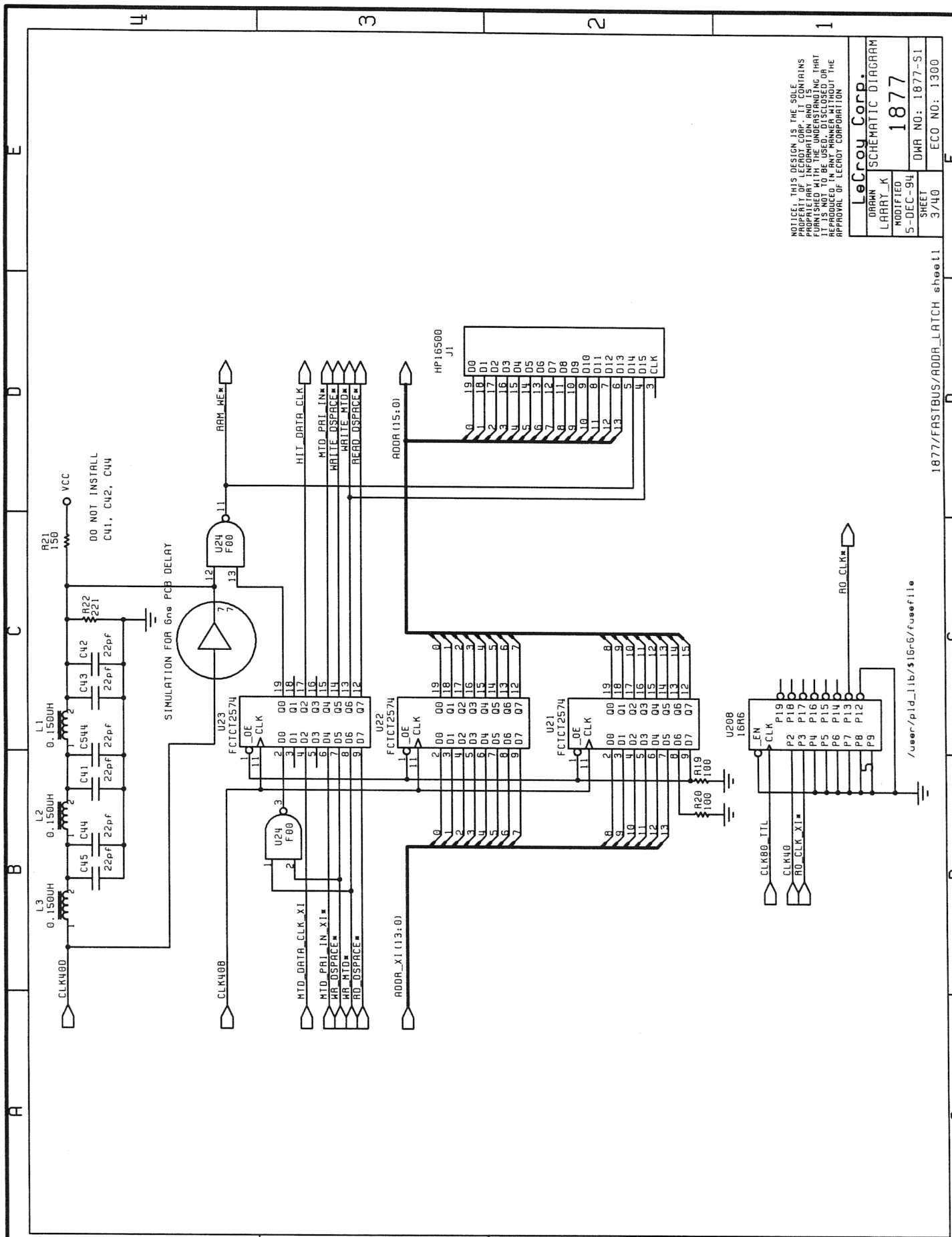
LeCroy Corp.	
DRAWN	SCHEMATIC DIAGRAM
BEN_M	1877
MODIFIED	1-DEC-94
SHEET	DWR NO: 1877-S1
1/40	ECO NO: 1300

1877 sheet1



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LeCroy Corp.			
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SHEET	2/40	DWR NO: 1877-S1	
		ECO NO: 1300	



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LeCroy Corp.	
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S-DEC-94	DWR NO: 1877-S1
SHEET	3/40
ECO NO:	1300



AWN	SCHEMATIC DIAGRAM
BY K	

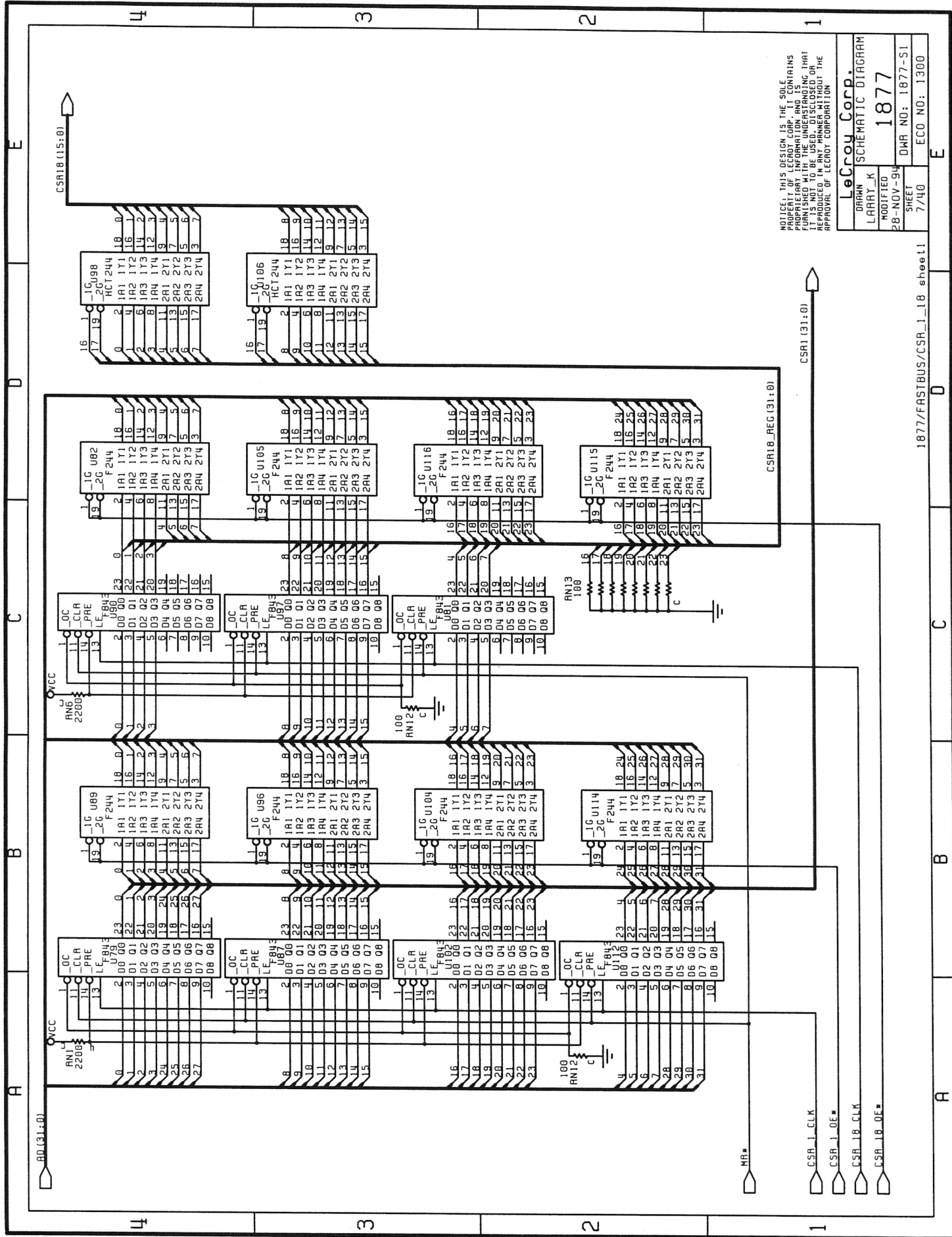
DWR NO: 1877-S1

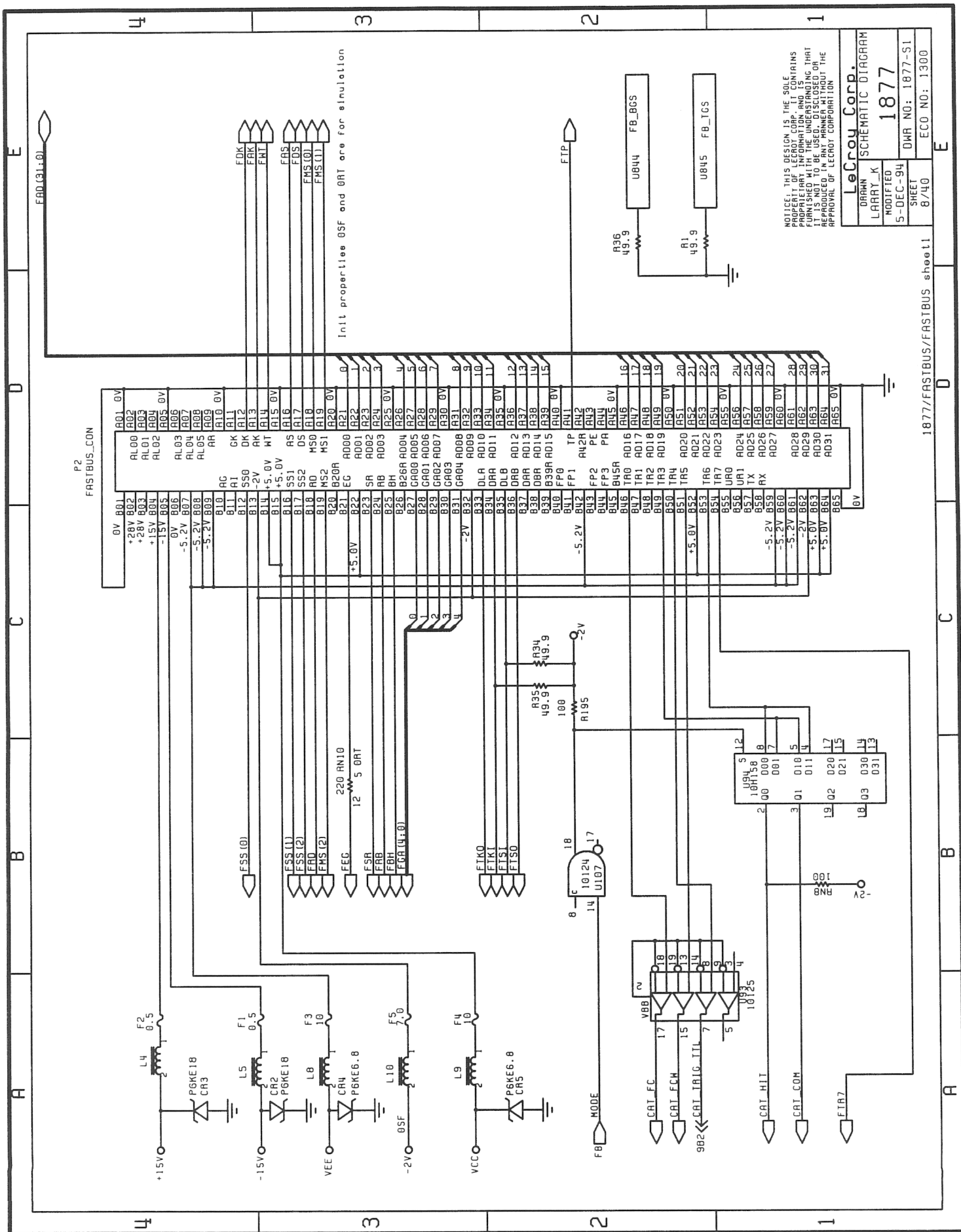
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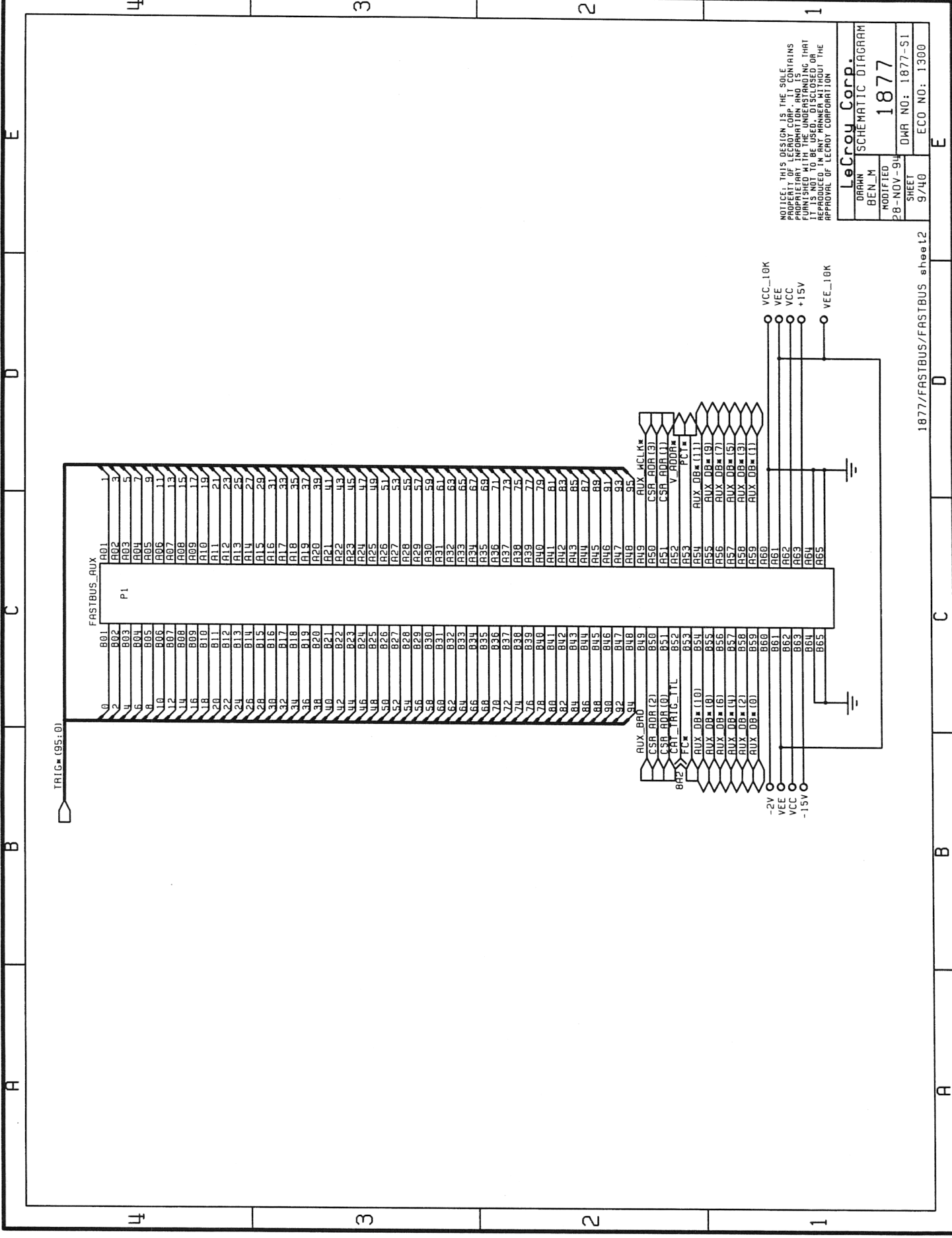
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1877/FASTBUS/AUX_BUF sheet1



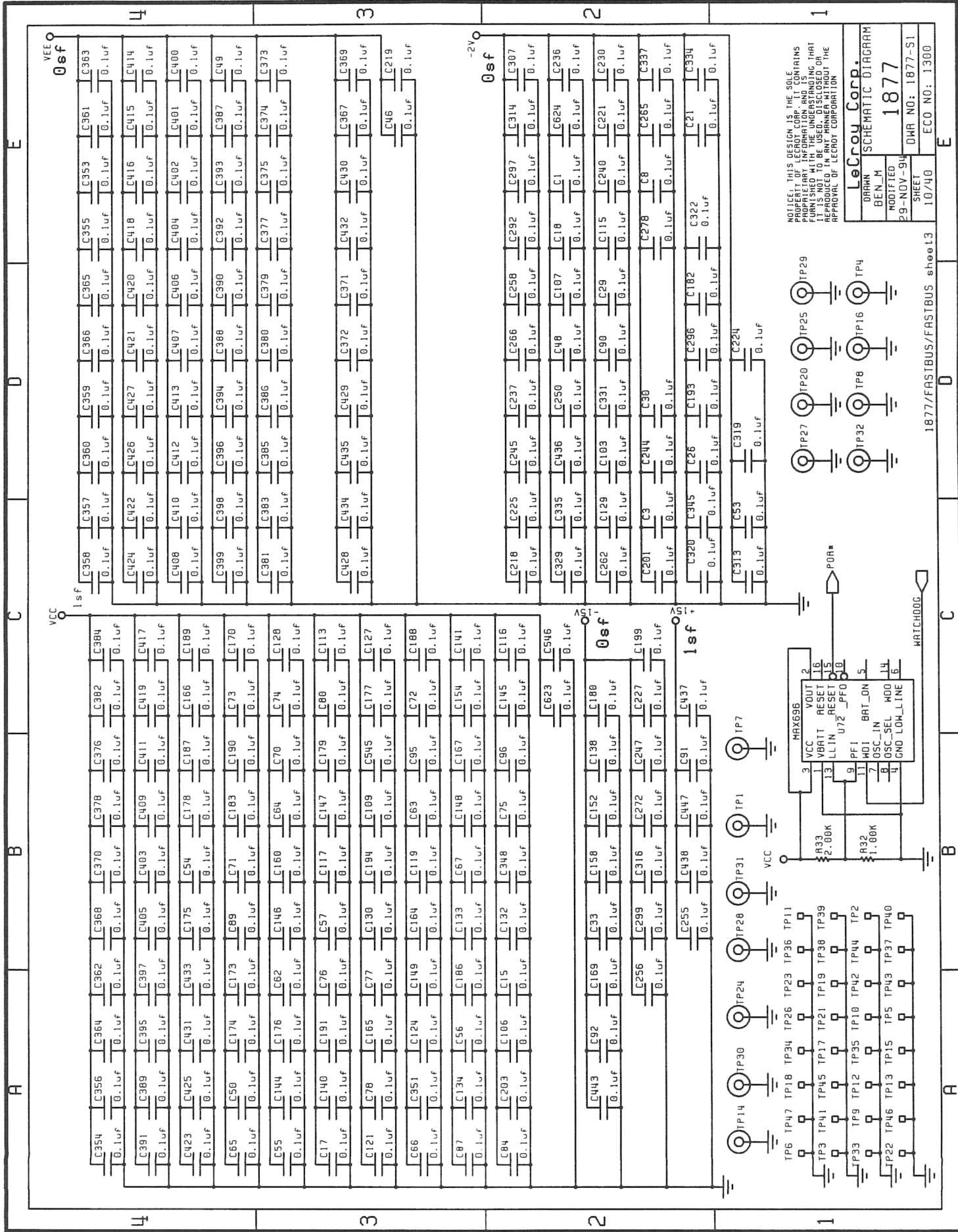






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LeCroy Corp.	
DRWN	BEN M
MODIFIED	1877
28-NOV-94	DWR NO: 1877-S1
SHEET	9/40
ECO NO:	1300



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LeCroy Corp.	
DRAWN	SCHEMATIC DIAGRAM
BEN_M	1877
MODIFIED	
29-NOV-94	
SHEET	
DWR NO: 1877-S1	
ECO NO: 1300	

1877/FABSBUS/FASTBUS sheet13

WATCHDOG

VCC

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TP147

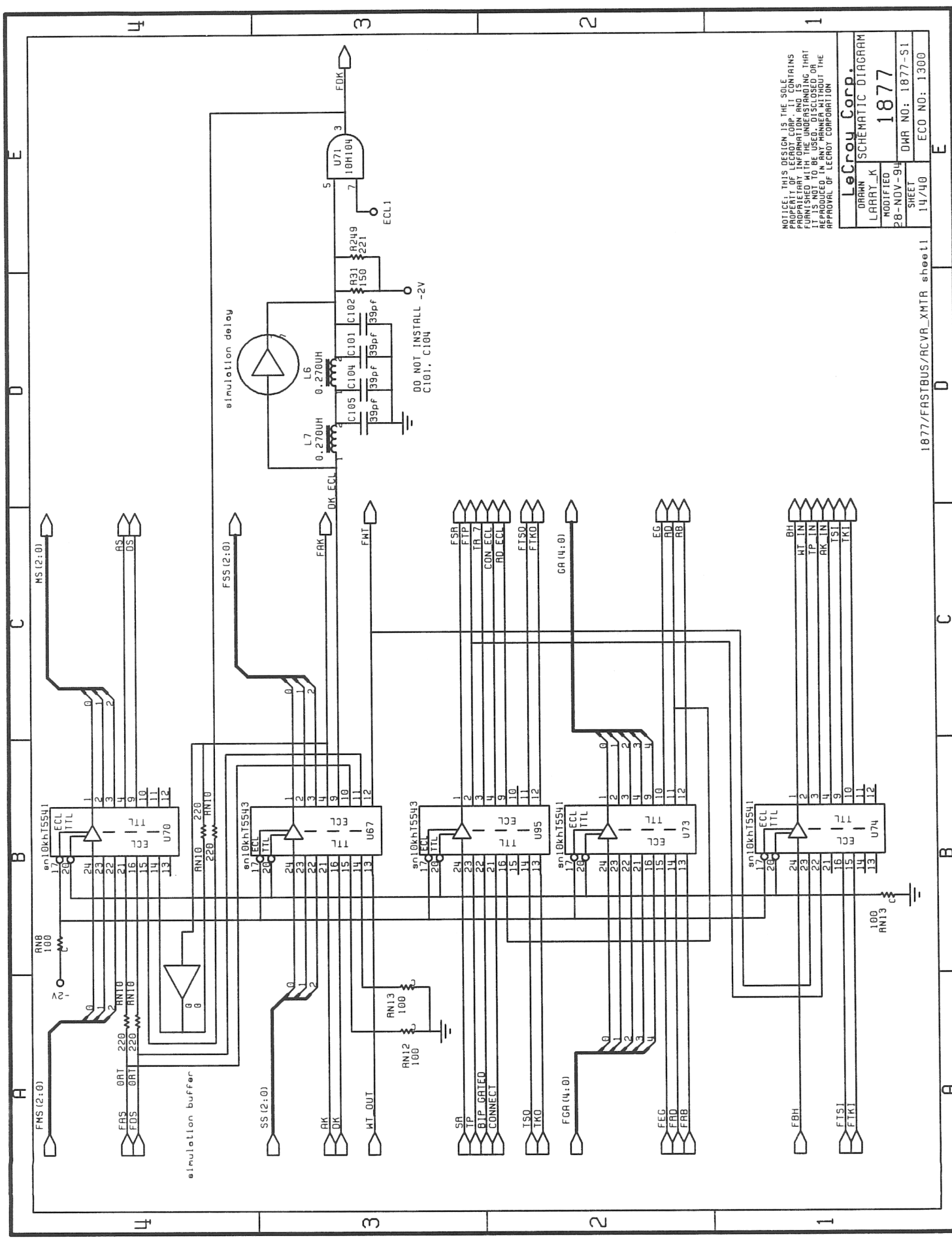
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TP151

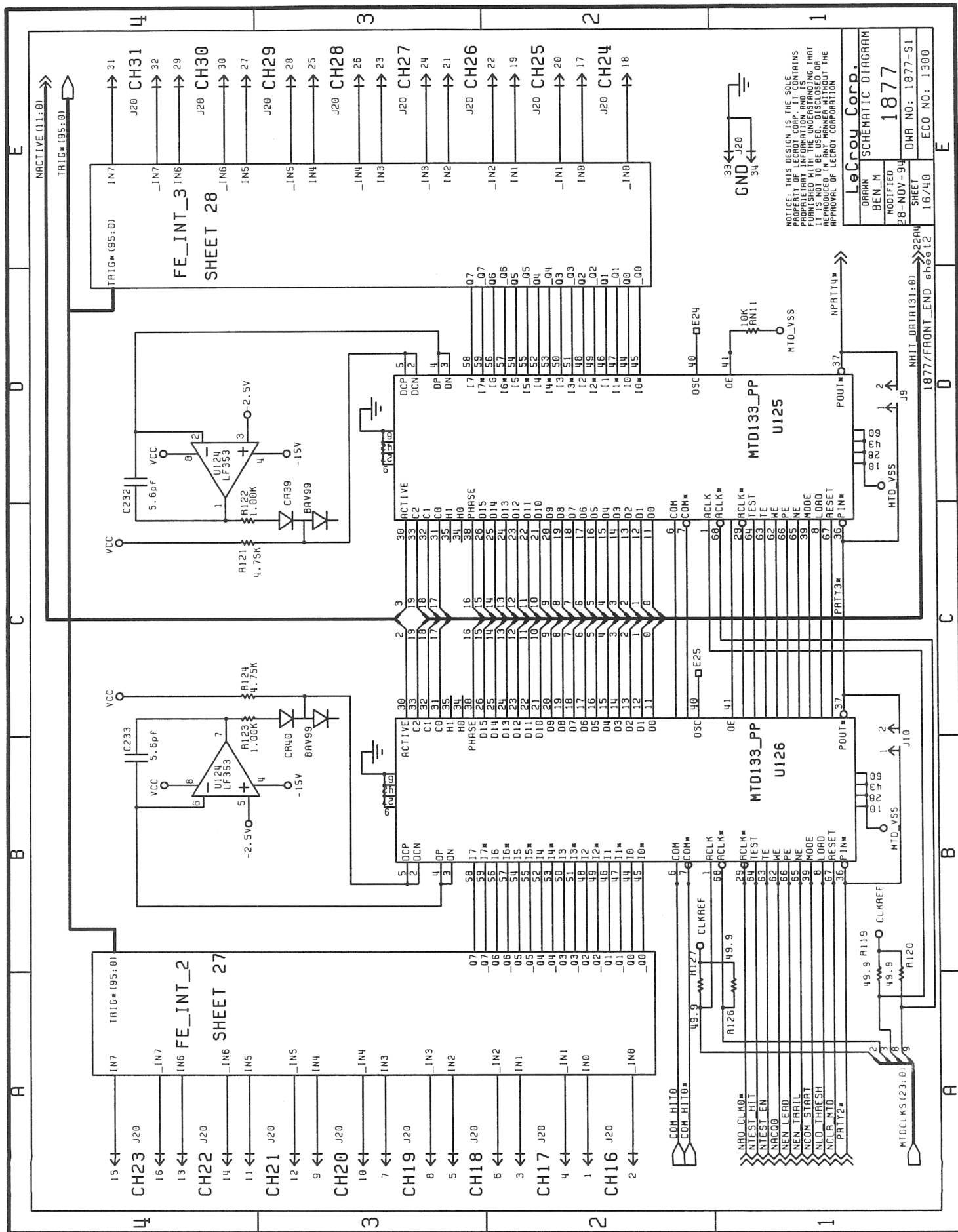
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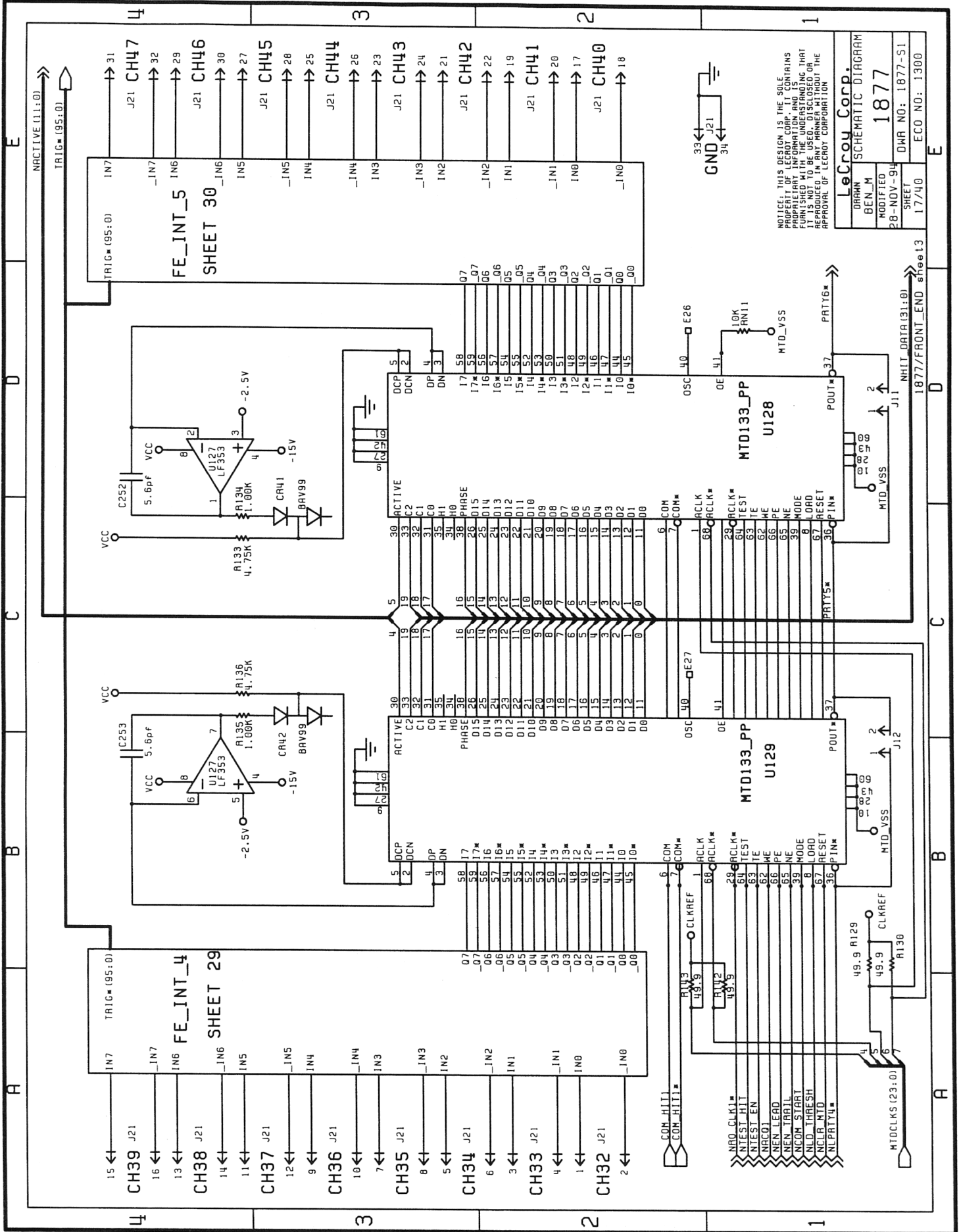


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LeCroy Corp.	
DRAWN	LARRY_K
MODIFIED	1877
DATE	14/40
ECO NO:	1300

1877/FASTBUS/RCVR_XMTR sheet 1

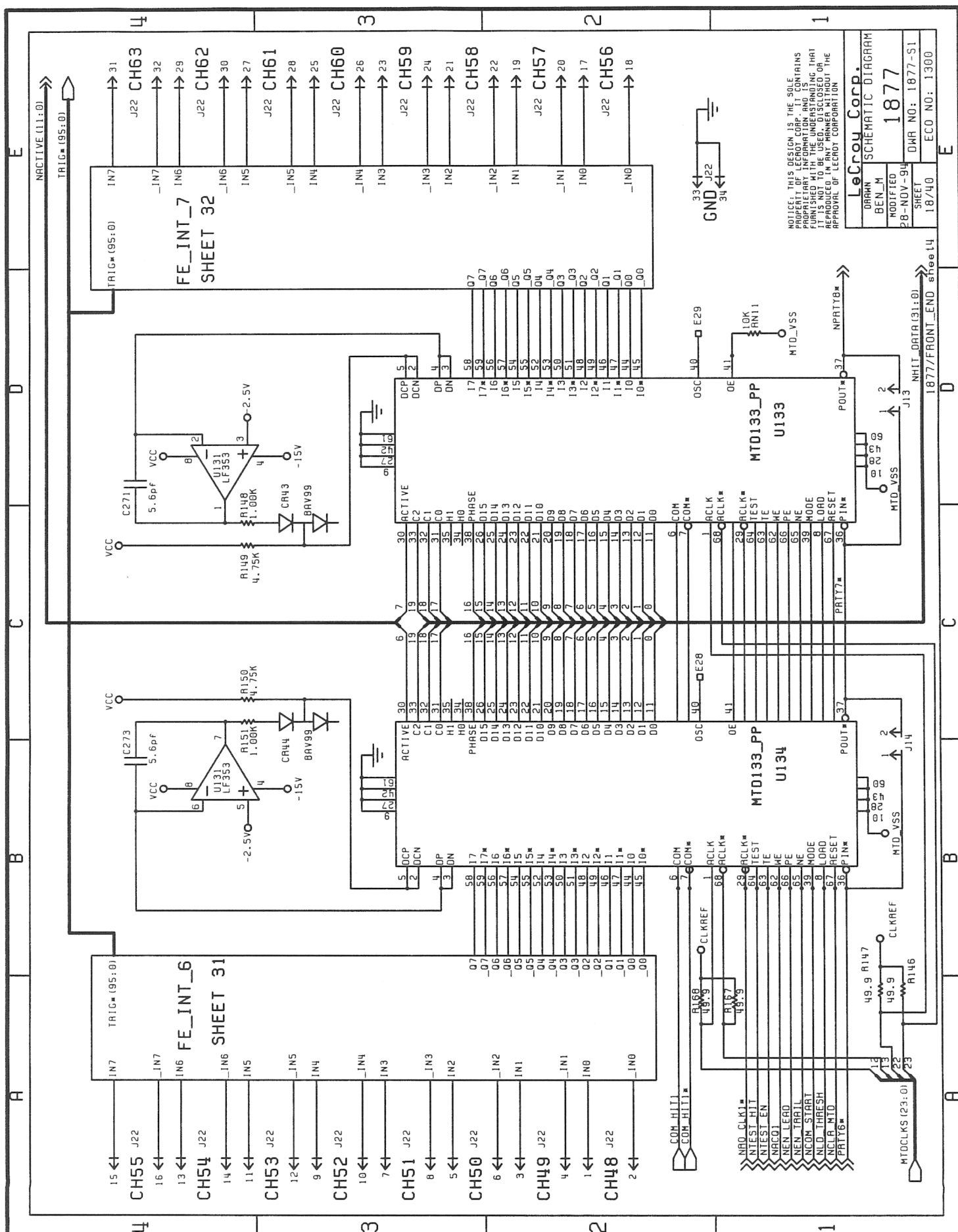




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LeCroy Corp.			
DRAWN	BEN M	SHEET	1877
MODIFIED	28-NOV-94	DWG NO:	1877-S1
DATE	1/7/00	ECO NO:	1300

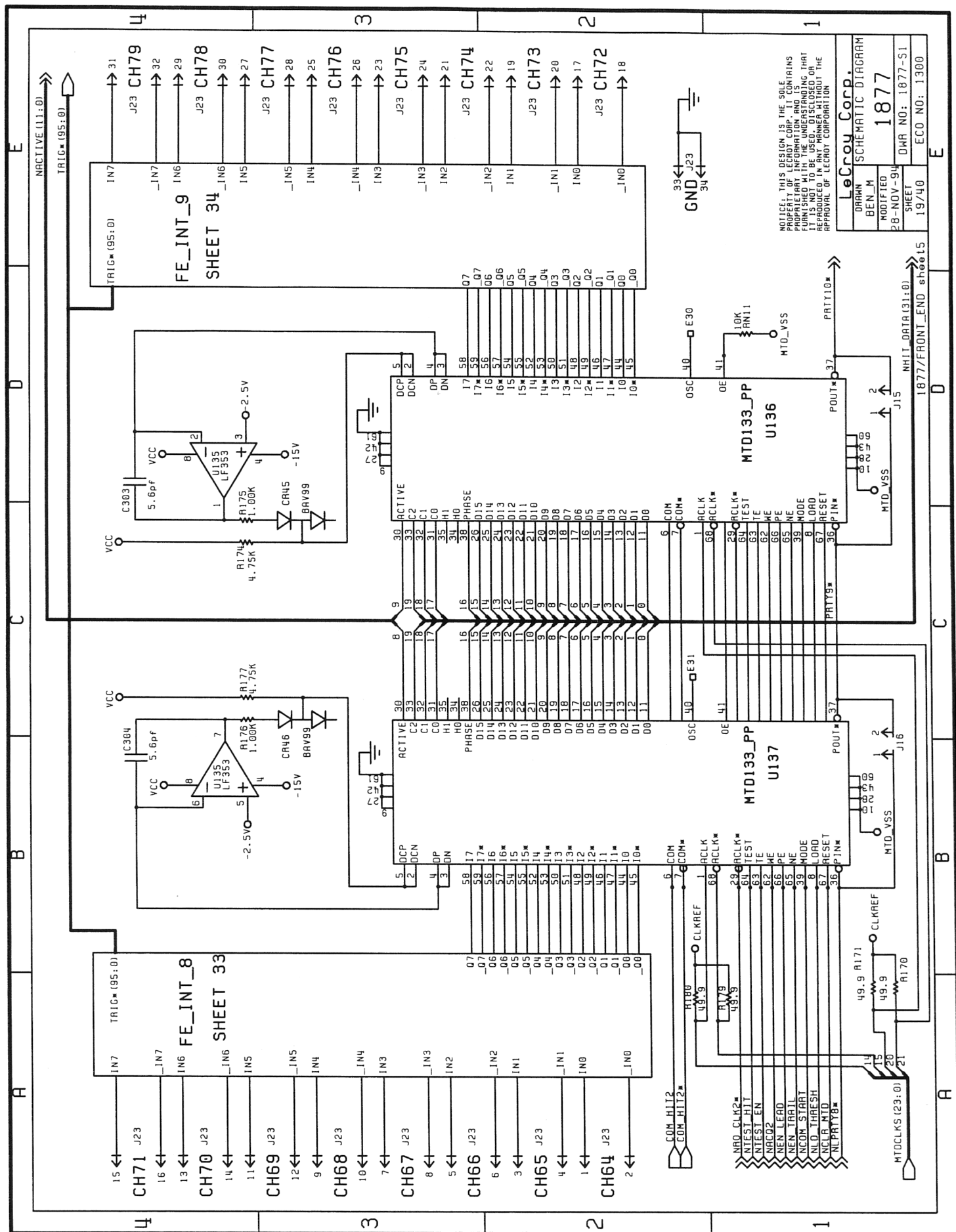
1877/Front_End sheet 13

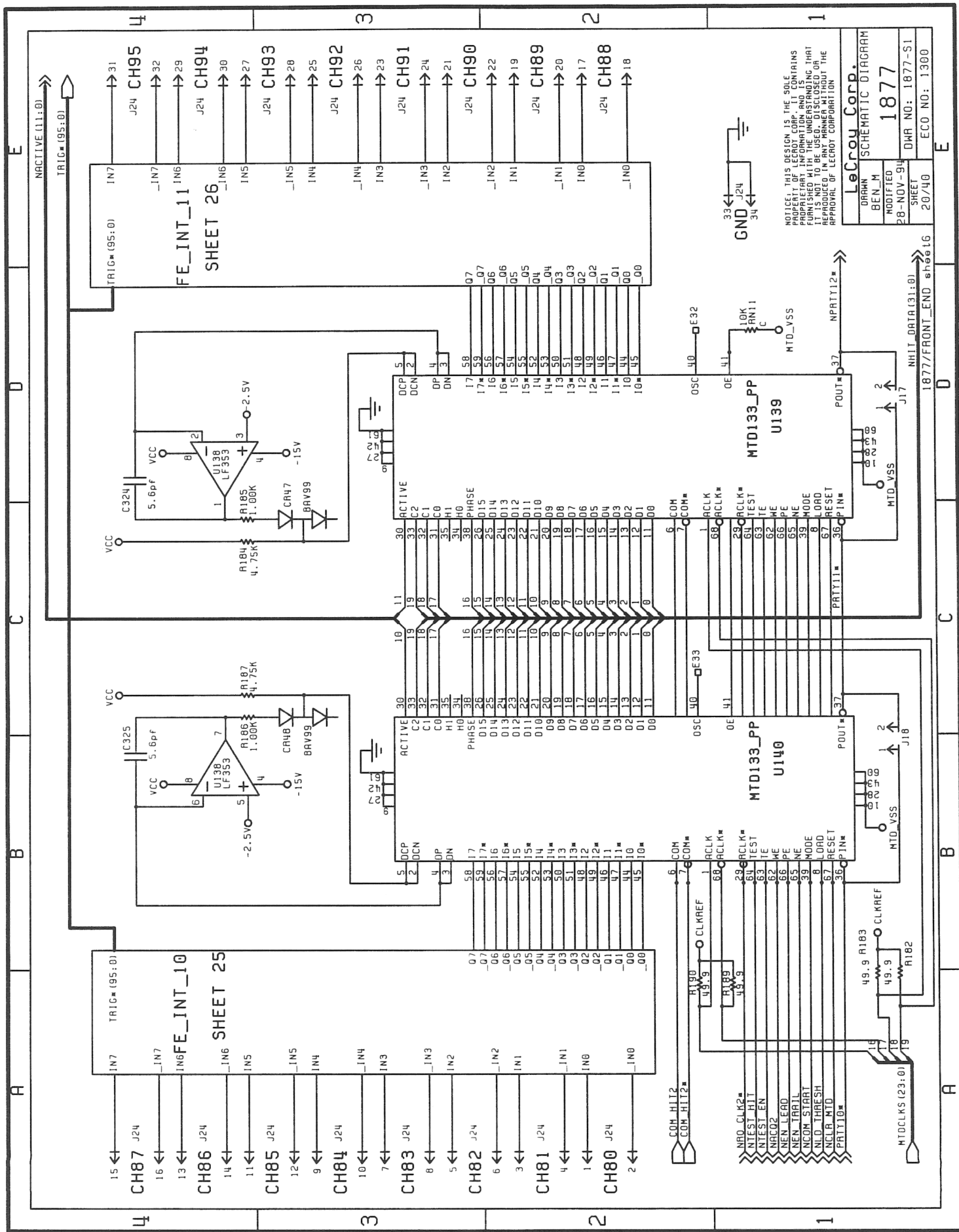


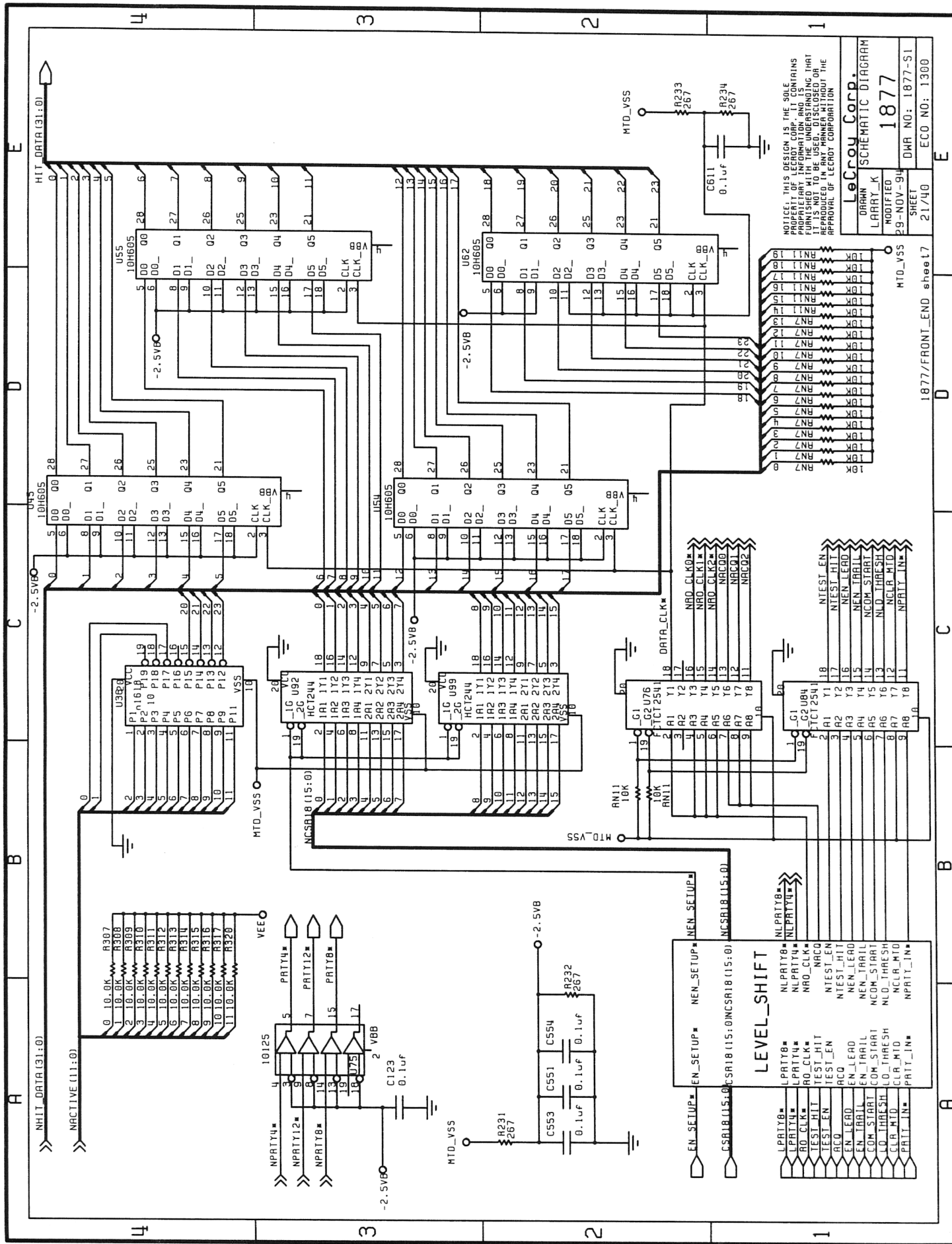
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LeCroy Corp.	
DRAWN	BEN_M
MODIFIED	28-NOV-94
SHEET	18/40
1877	
DWA NO: 1877-S1	
ECO NO: 1300	

1877/Front_End sheet 4



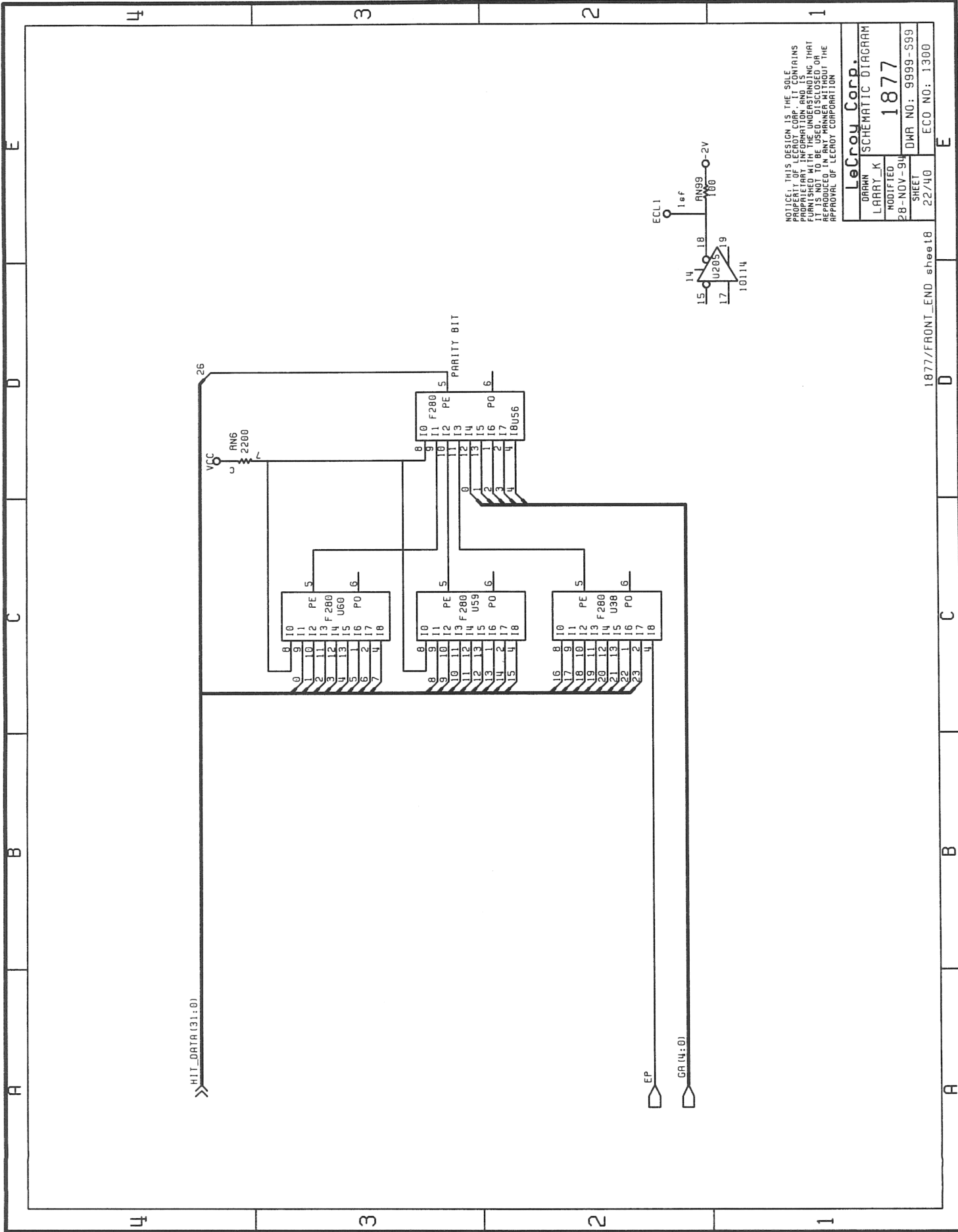




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LeCroy Corp.
SCHEMATIC DIAGRAM
1877
MODIFIED 29-NOV-94
DWR NO: 1877-S1
ECO NO: 1300

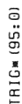
1877/Front_END sheet 7



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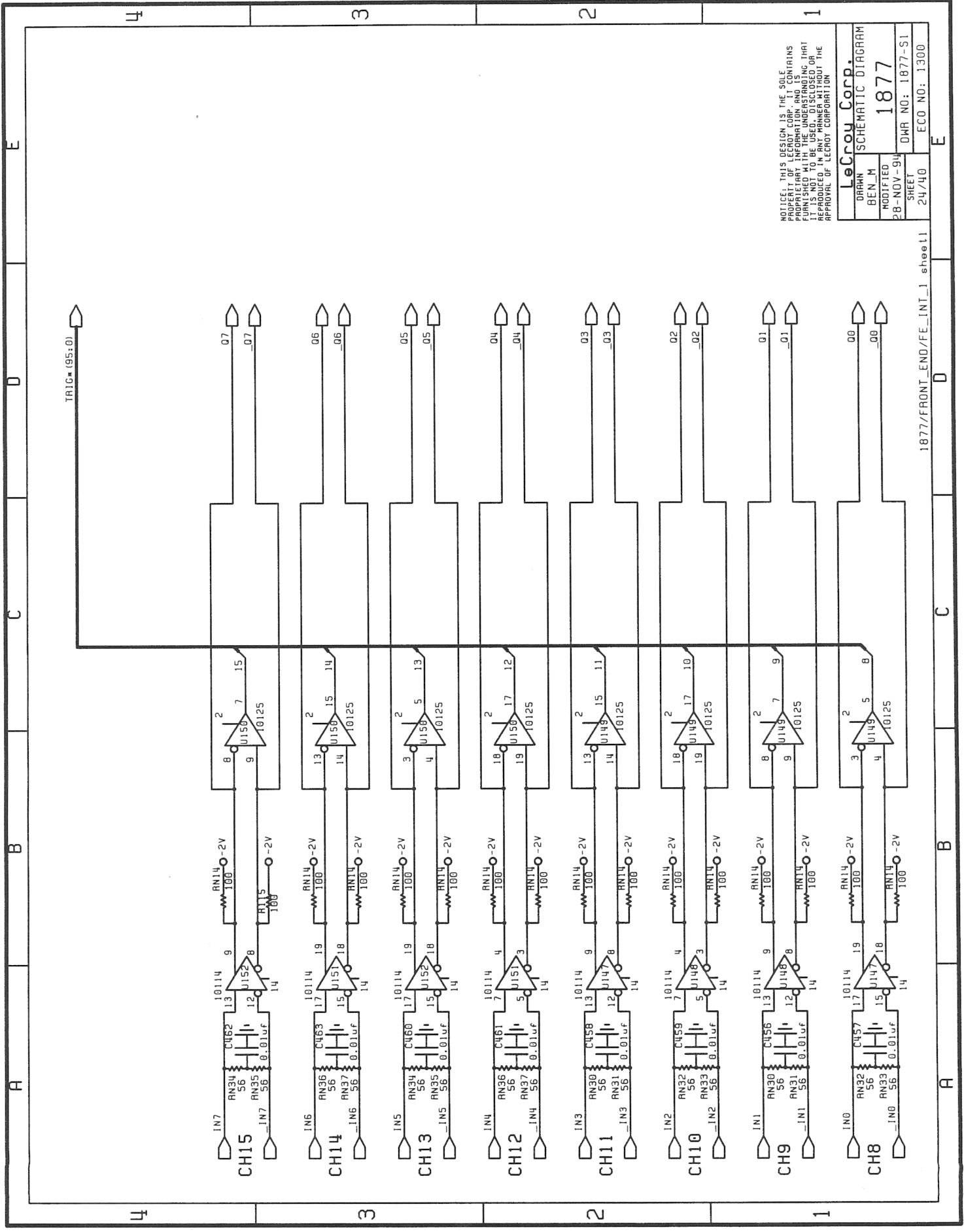
LeCroy Corp.	
DRAWN	LARRY_K
MODIFIED	1877
28-NOV-94	DWR NO: 9999-S99
SHEET	ECO NO: 1300

1877/Front_End sheet8



LeCroy Corp.		SCHEMATIC DIAGRAM	
DRAWN BEN_M	1877		DWR NO: 1877-S1
MODIFIED 28-NOV-94			ECO NO: 1300
SHEET 23/24			

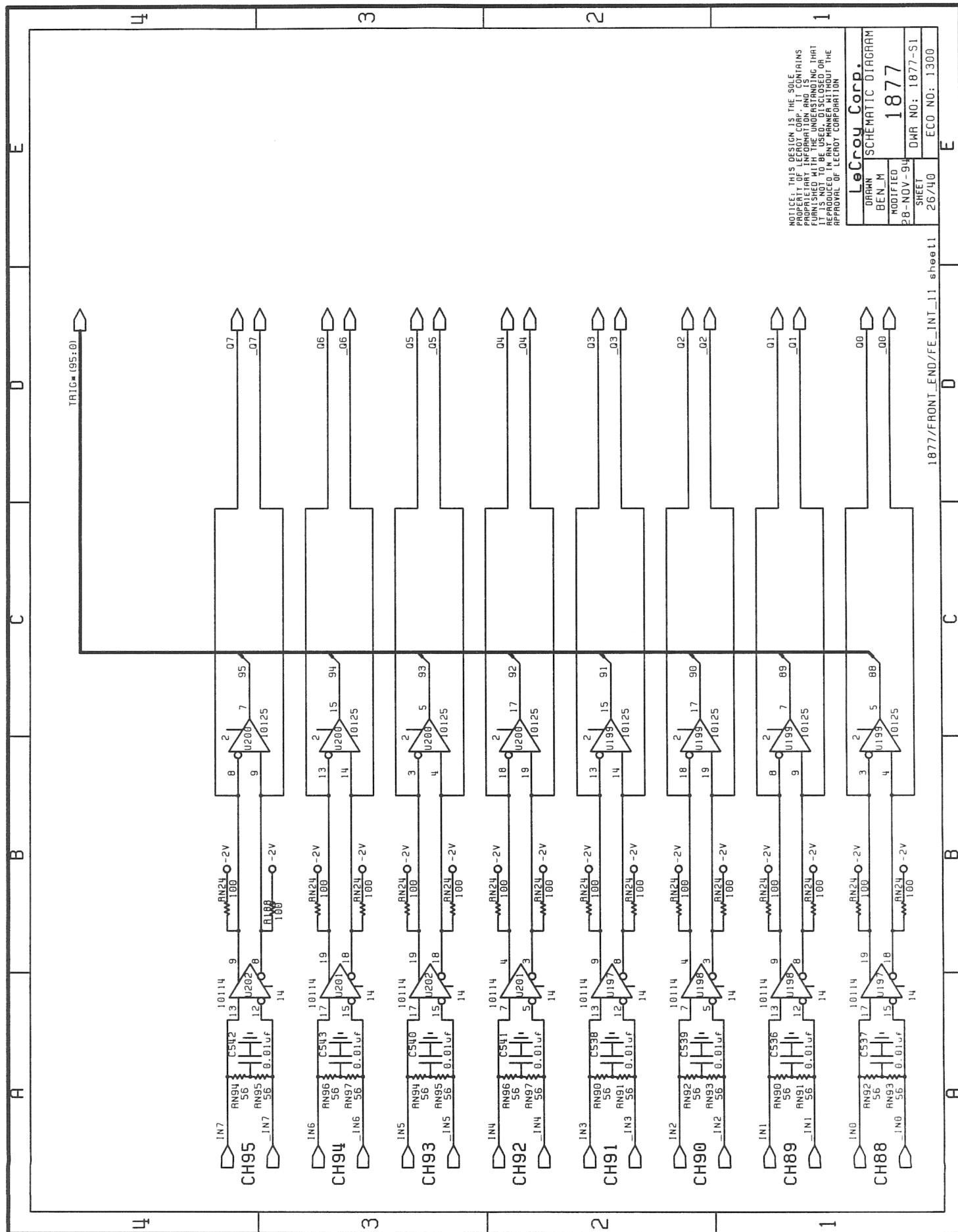
18777/FRONT_END/FE_INT_0 sheet1



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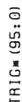
LeCroy Corp.	
DRAWN	SCHEMATIC DIAGRAM
BEN M	1877
MODIFIED	28-NOV-94
SHEET	24/40
DWG NO:	1877-S1
ECO NO:	1300

1877/Front_End/FE_INT_1 sheet 1



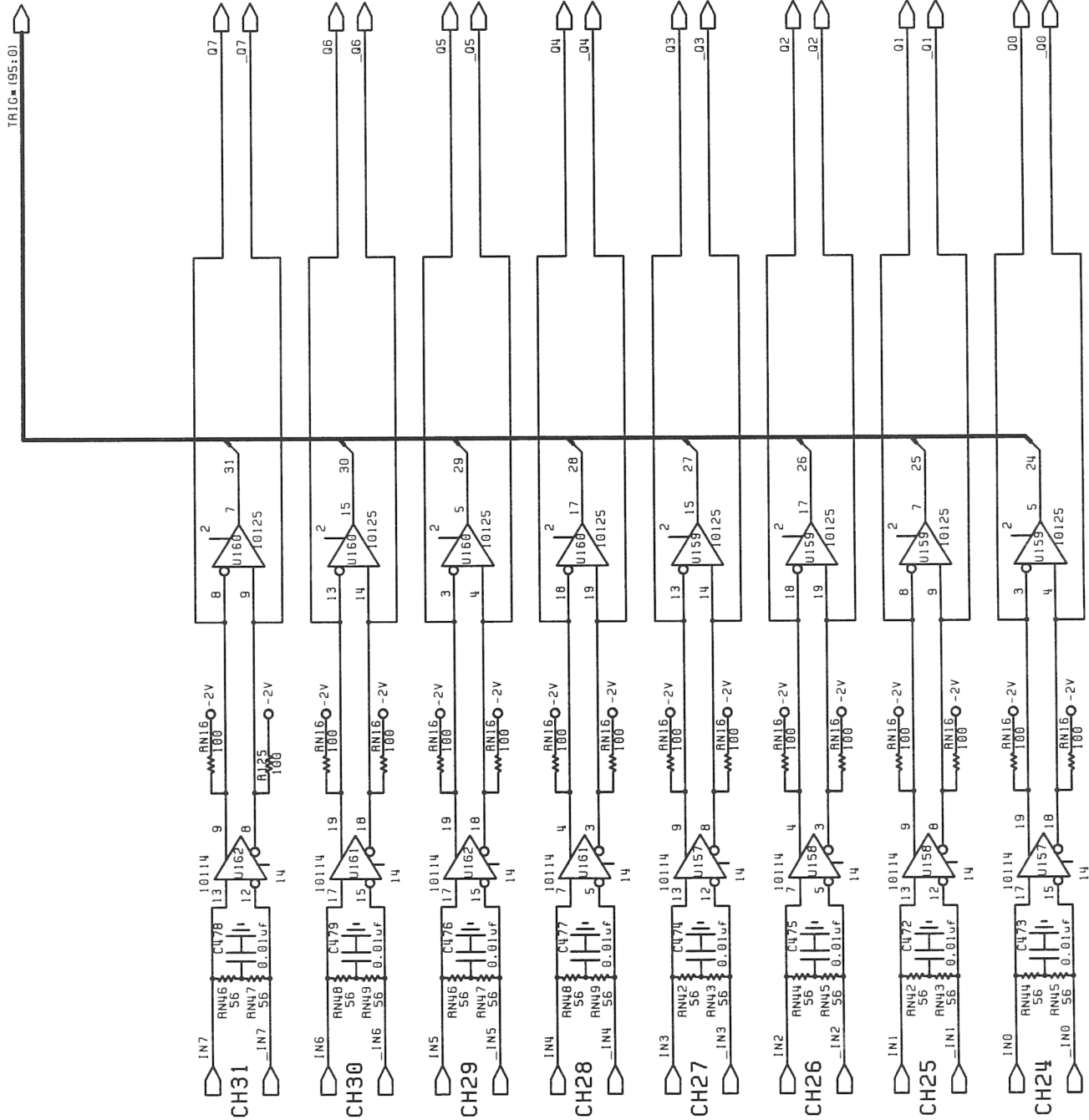
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LeCroy Corp.	
DRAWN	BEN_M
SCHEMATIC DIAGRAM	
1877	
MODIFIED	28-NOV-94
SHEET	DWR NO: 1877-S1
26/40	ECO NO: 1300



LeCroy Corp.	
DRAWN BEN_M	SCHEMATIC DIAGRAM
MODIFIED	1877
28-NOV-94	DWR NO: 1877-S1
SHEET	ECO NO: 1300
27/40	

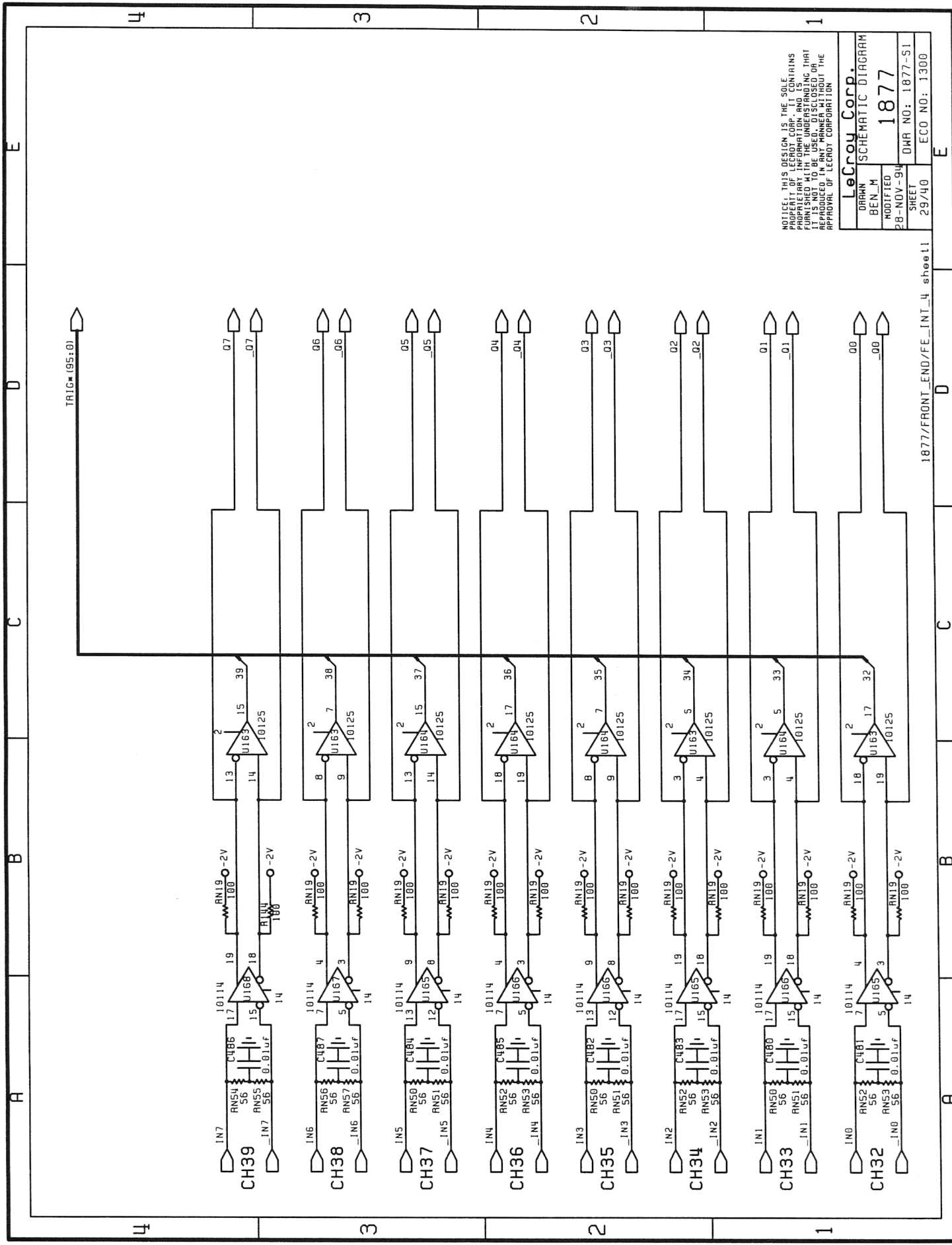
1877/Front_End/FE_INT_2_sheet1



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LeCroy Corp.	DRWN	BEN M	1877	ECO NO: 1300
SCHEMATIC DIAGRAM	MODIFIED	28-NOV-94	DWR NO: 1877-S1	
SHEET	28/40			

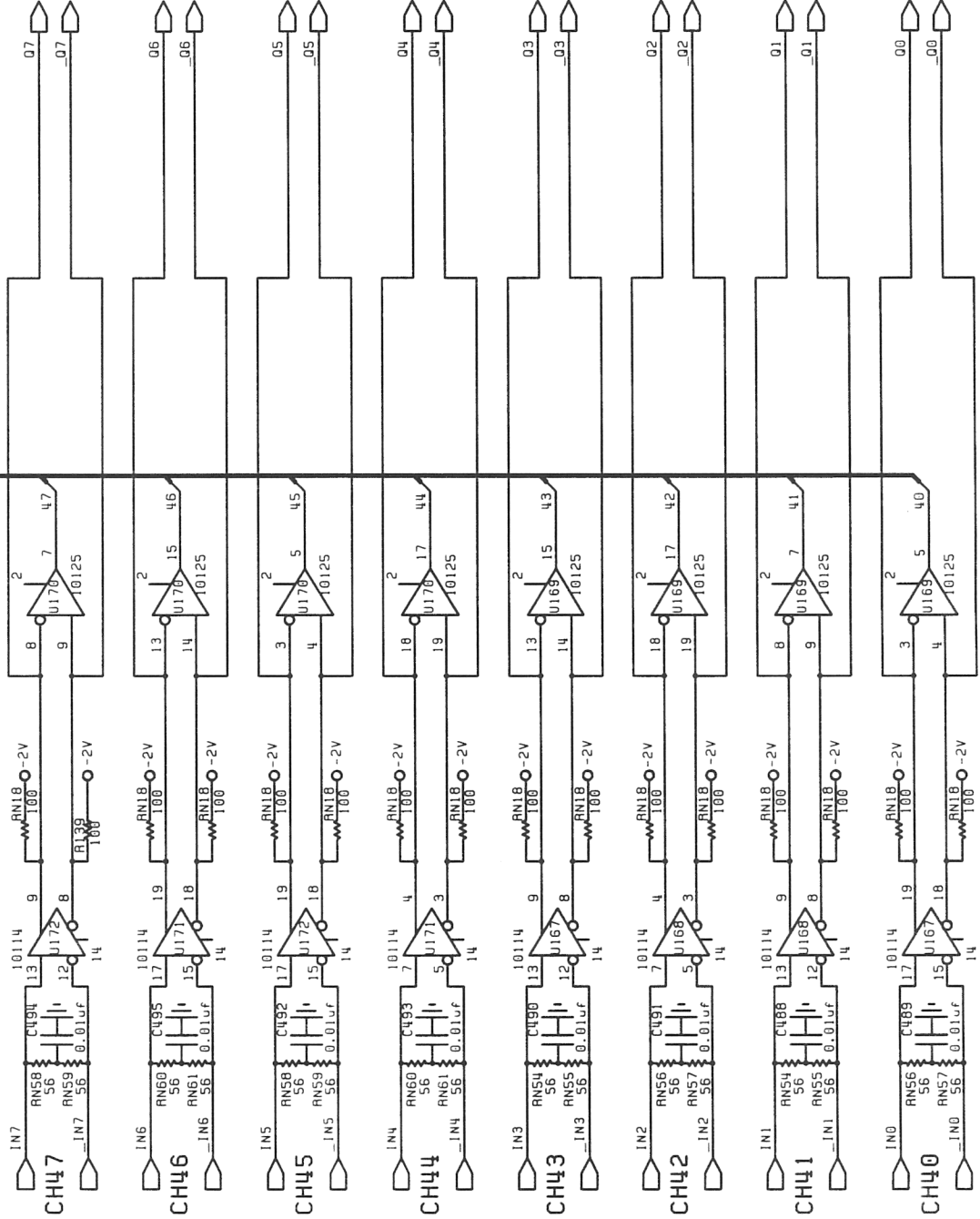
1877/Front_End/FE_INT_3 sheet 1



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LeCroy Corp.	
DRAWN	BEN_M
MODIFIED	1877
28-NOV-94	DWR NO: 1877-S1
SHEET	29/40
ECO NO: 1300	

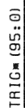
TRIG# (95:0)



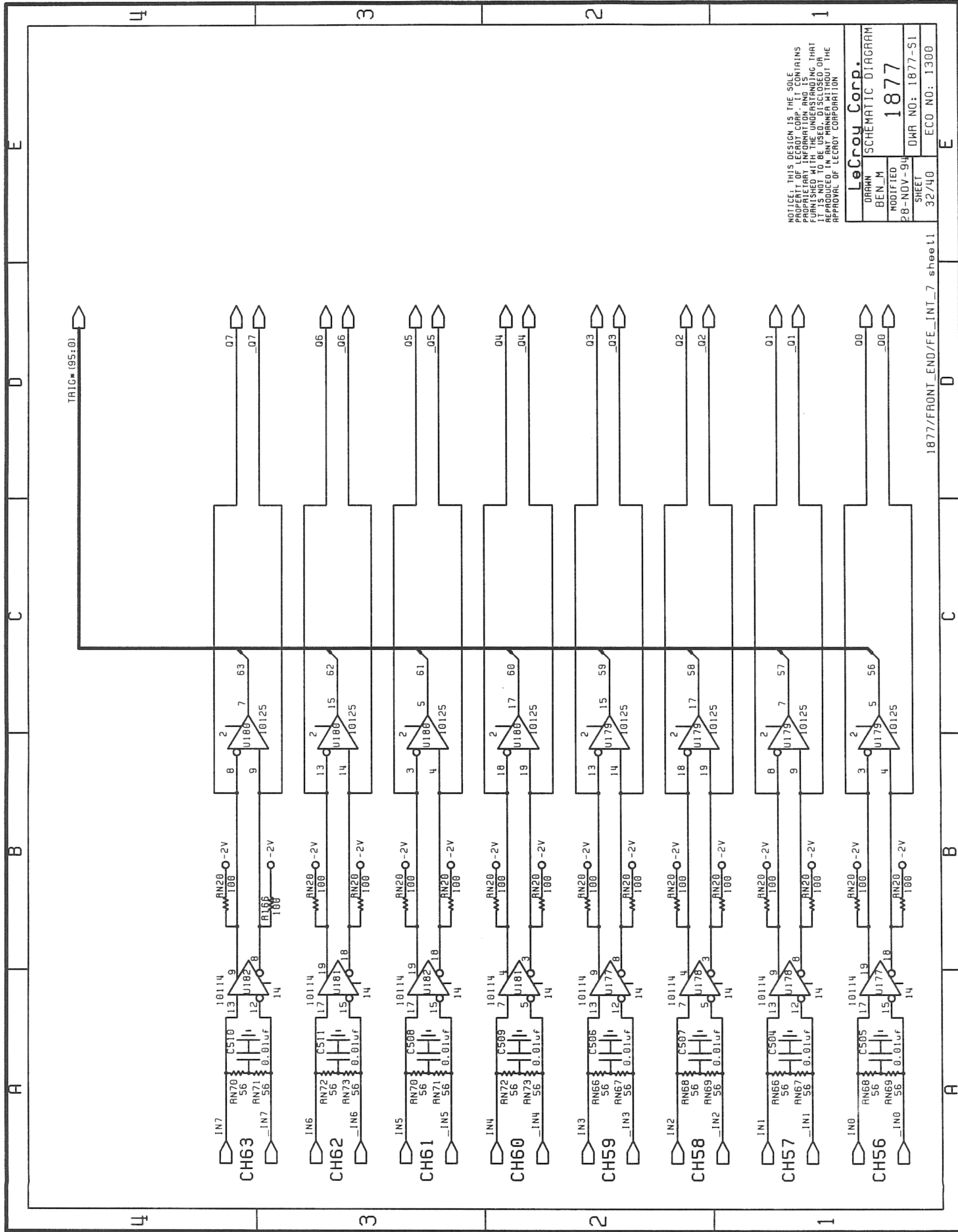
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LeCroy Corp.	
DRAWN	BEN M
MODIFIED	28-NOV-94
SHEET	30/40
1877 SCHEMATIC DIAGRAM	
DWR NO: 1877-S1	
ECO NO: 1300	

1877/Front_End/FE_INT_5 sheet 1



LeCroy Corp.	
SCHEMATIC DIAGRAM	
DRAWN BEN_M	1877
MODIFIED 8-NOV-94	DWR NO: 1877-S1
SHEET 31/40	ECO NO: 1300



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LeCroy Corp.	
DRAWN	SCHEMATIC DIAGRAM
BEN_M	1877
MODIFIED	28-NOV-94
SHEET	32/40
ECO NO:	1877-S1

1877/Front_End/FE_INT_7 sheet 1

E

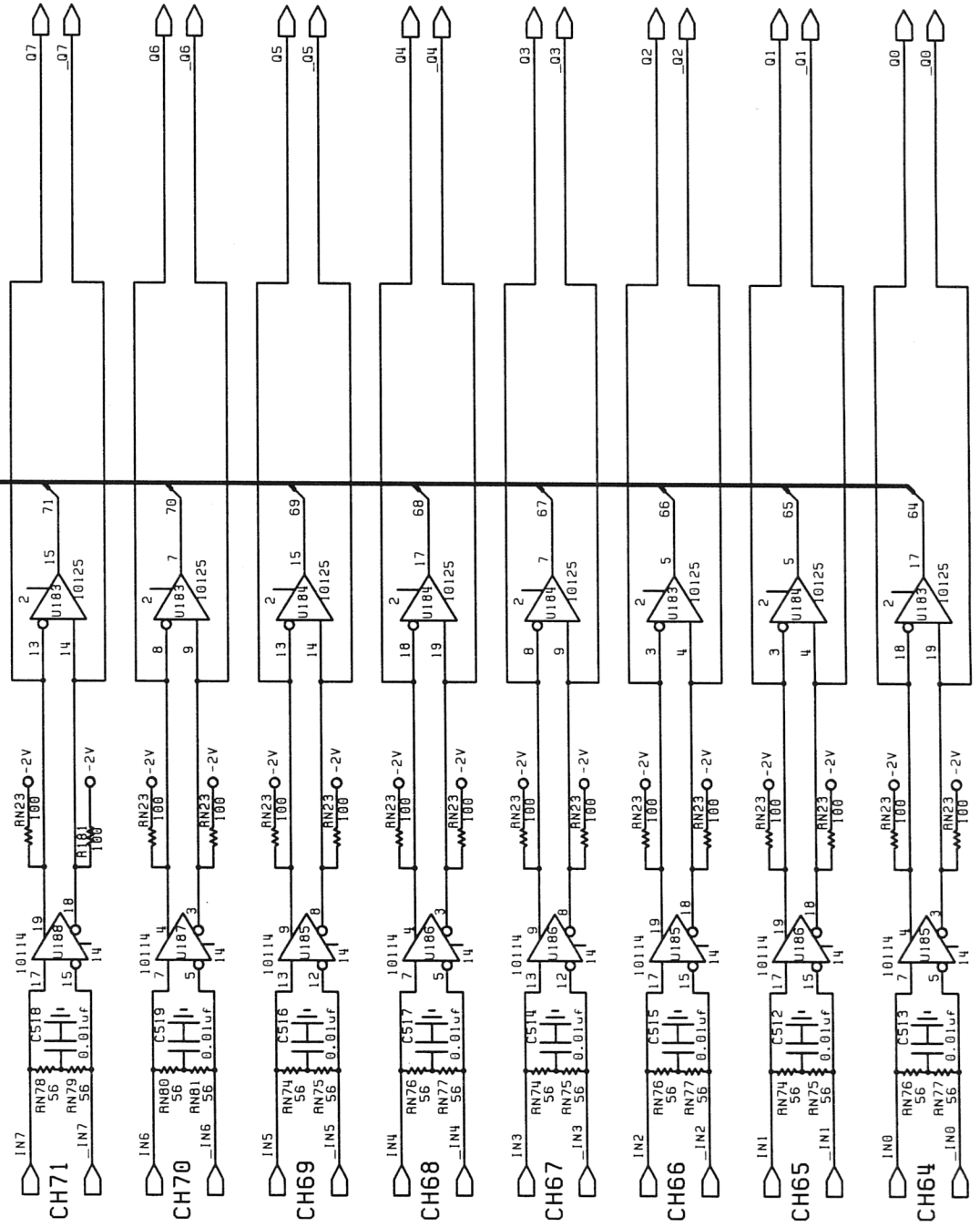
D

C

B

A

TR1G (95±0)



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LeCroy Corp.	
DRAWN	BEN M
MODIFIED	1877
28-NOV-94	DWR NO: 1877-S1
SHEET	ECO NO: 1300
33/40	

1877/Front_End/FE_INT_8 sheet 1

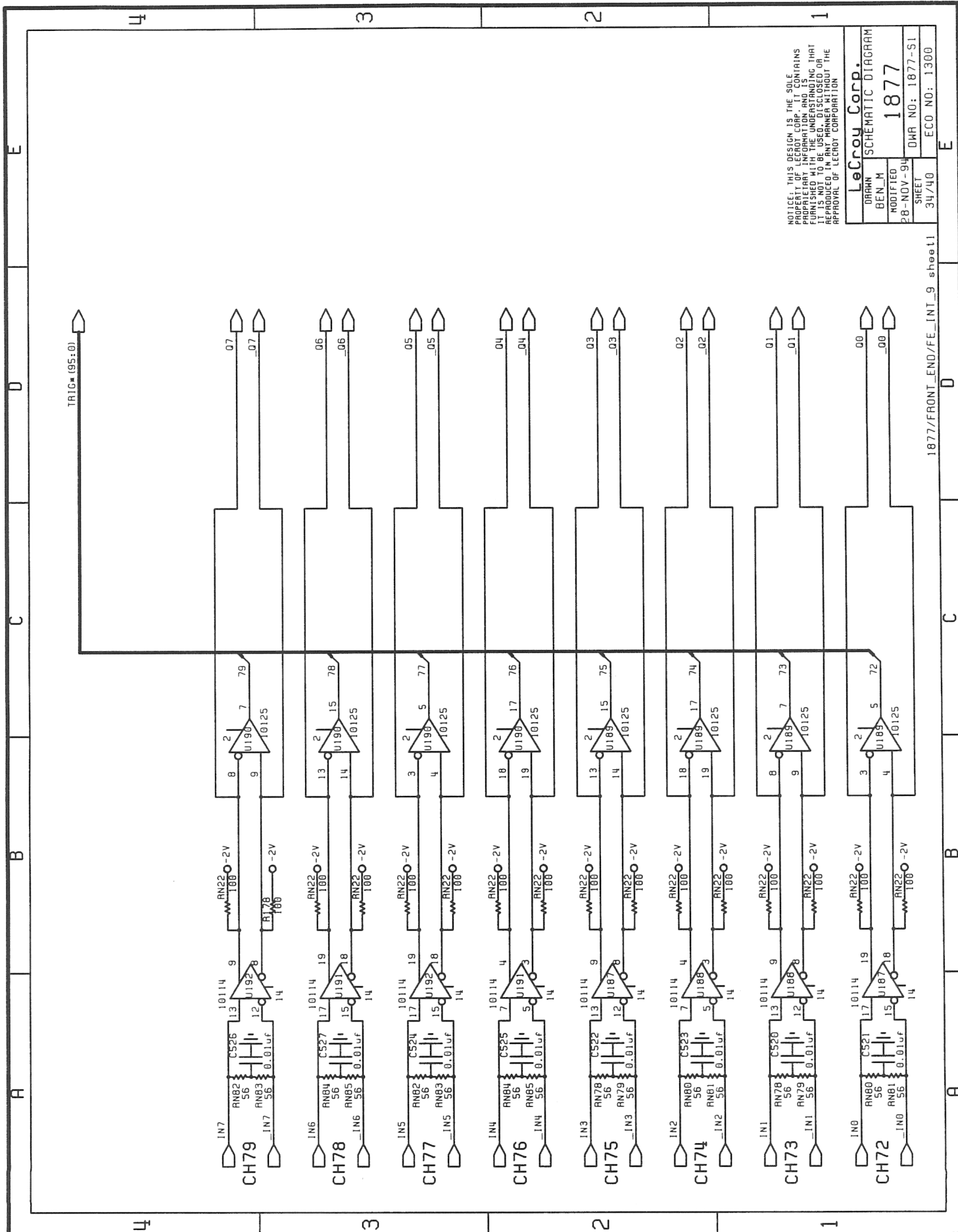
E

D

C

B

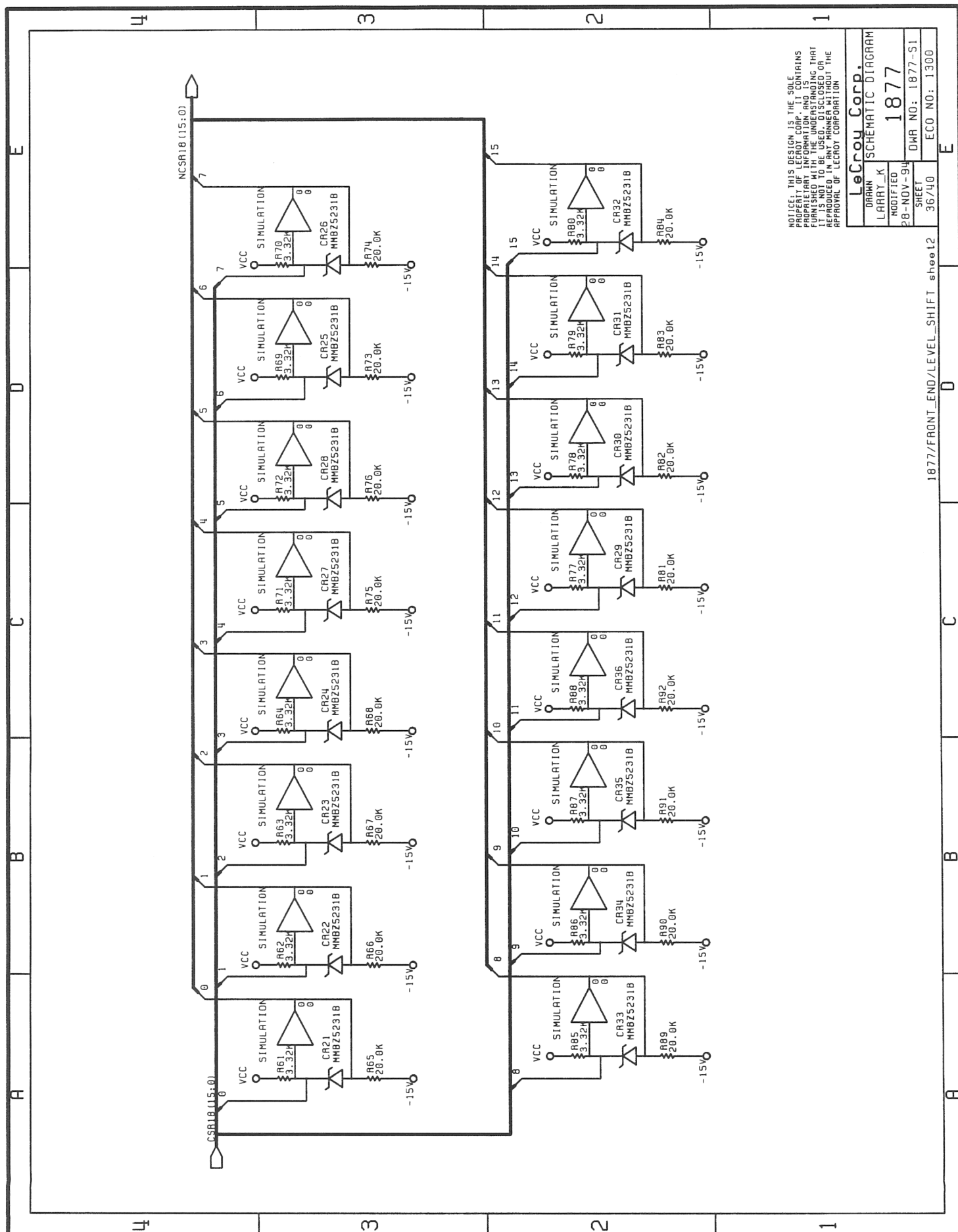
A



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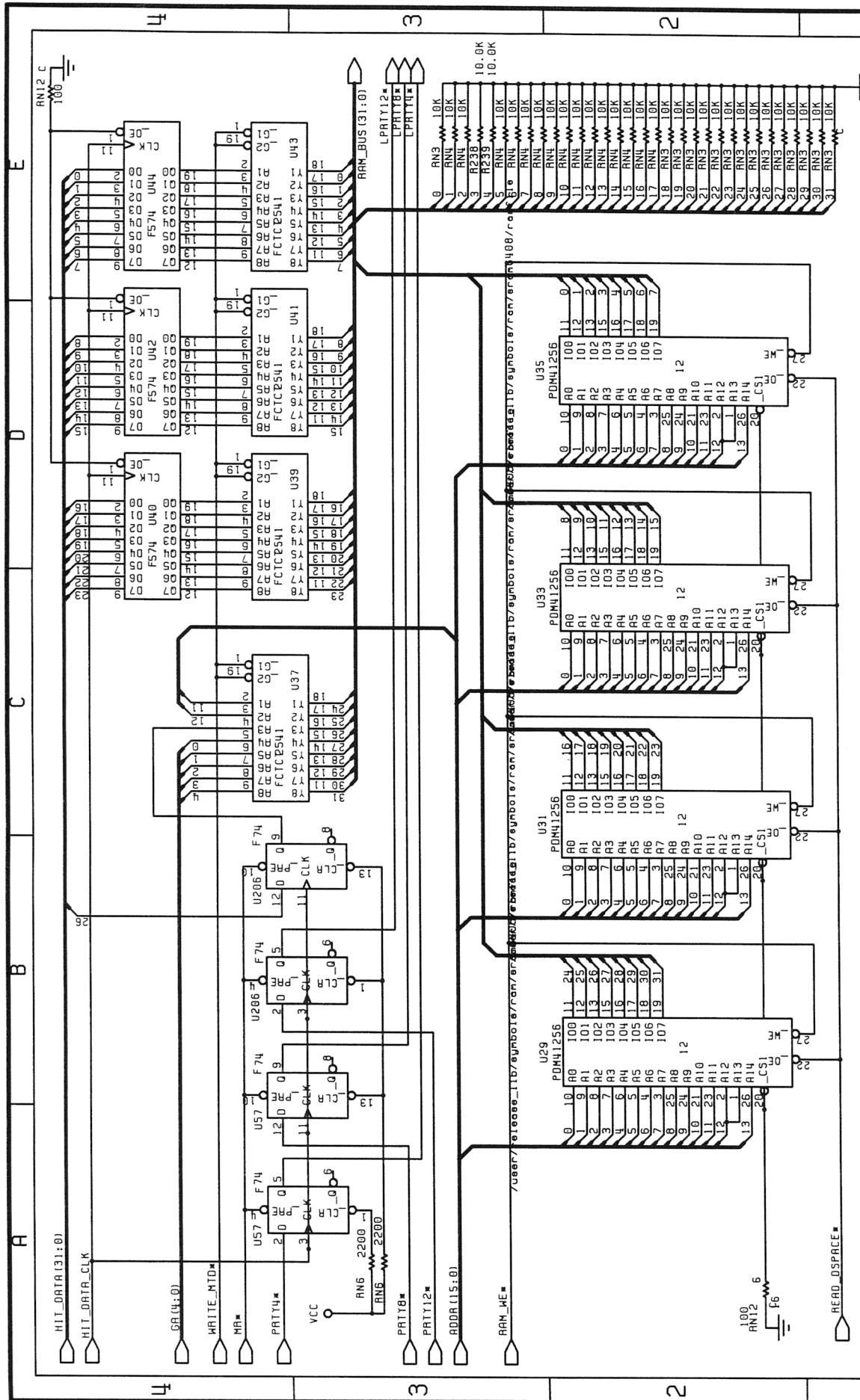
LeCroy Corp.	
DRWN	SCHEMATIC DIAGRAM
BEN_M	1877
MODIFIED	28-NOV-94
SHEET	34/40
DWR NO:	1877-S1
ECO NO:	1300

1877/Front_End/FE_INT_9 sheet1



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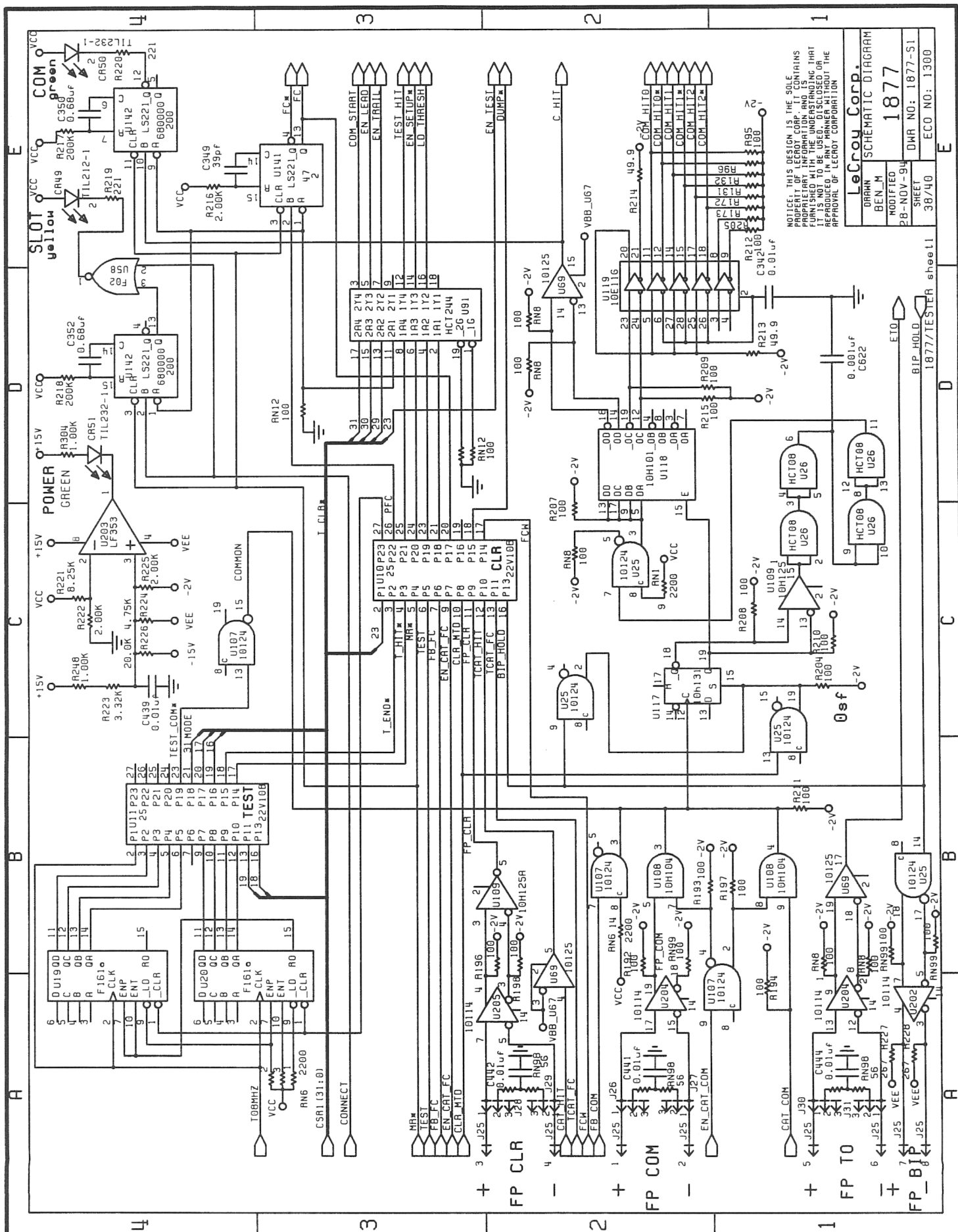
Lecroy Corp.	
DRAWN	LARRY_K
MODIFIED	1877
DATE	28-NOV-94
SHEET	36/40
ECO NO:	1300

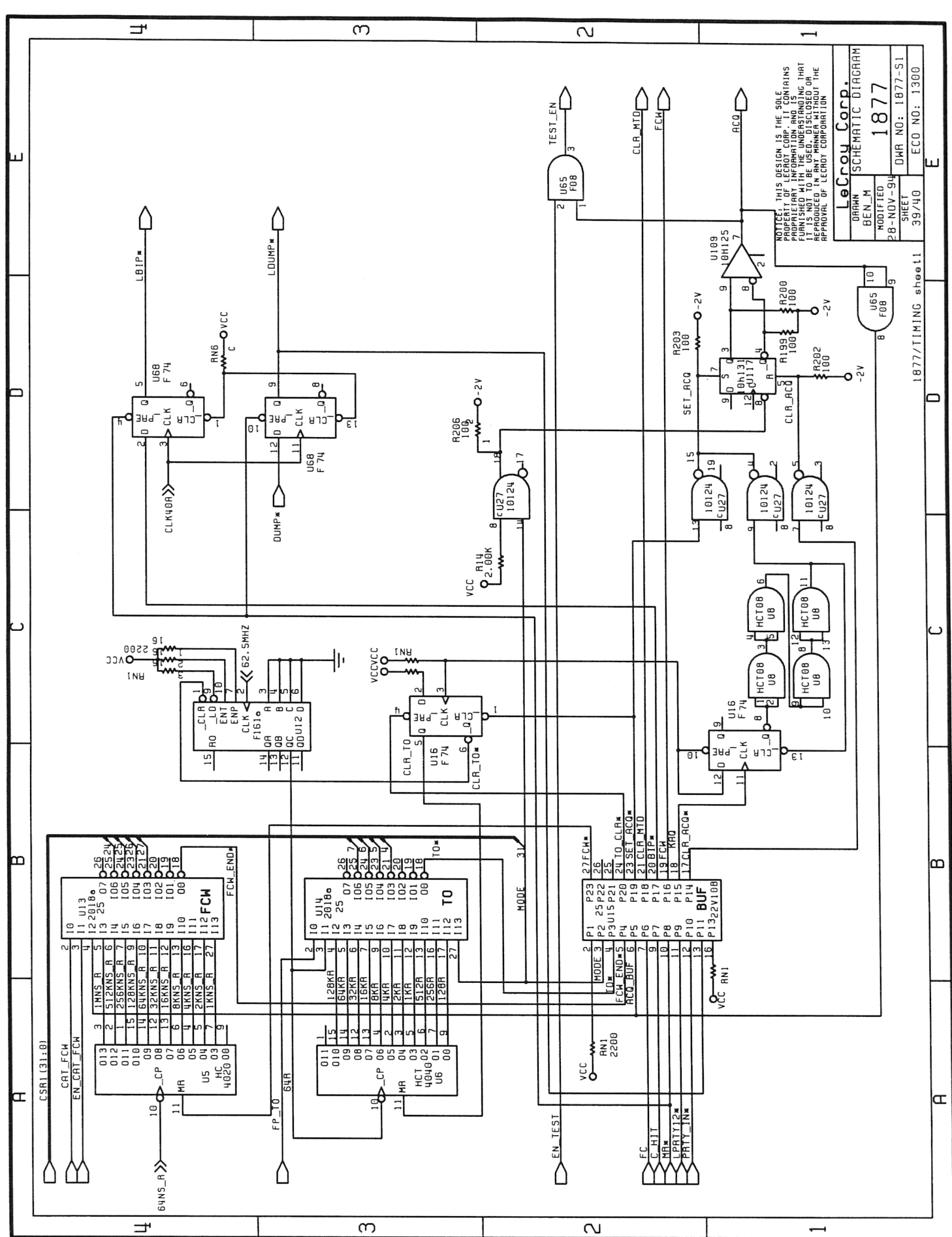


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LeCroy Corp.	
DRAWN	LARRY_K
MODIFIED	1877
DATE	28-NOV-94
SHEET	DWR NO: 1877-S1
37/40	ECO NO: 1300

1877/MEMORY sheet11

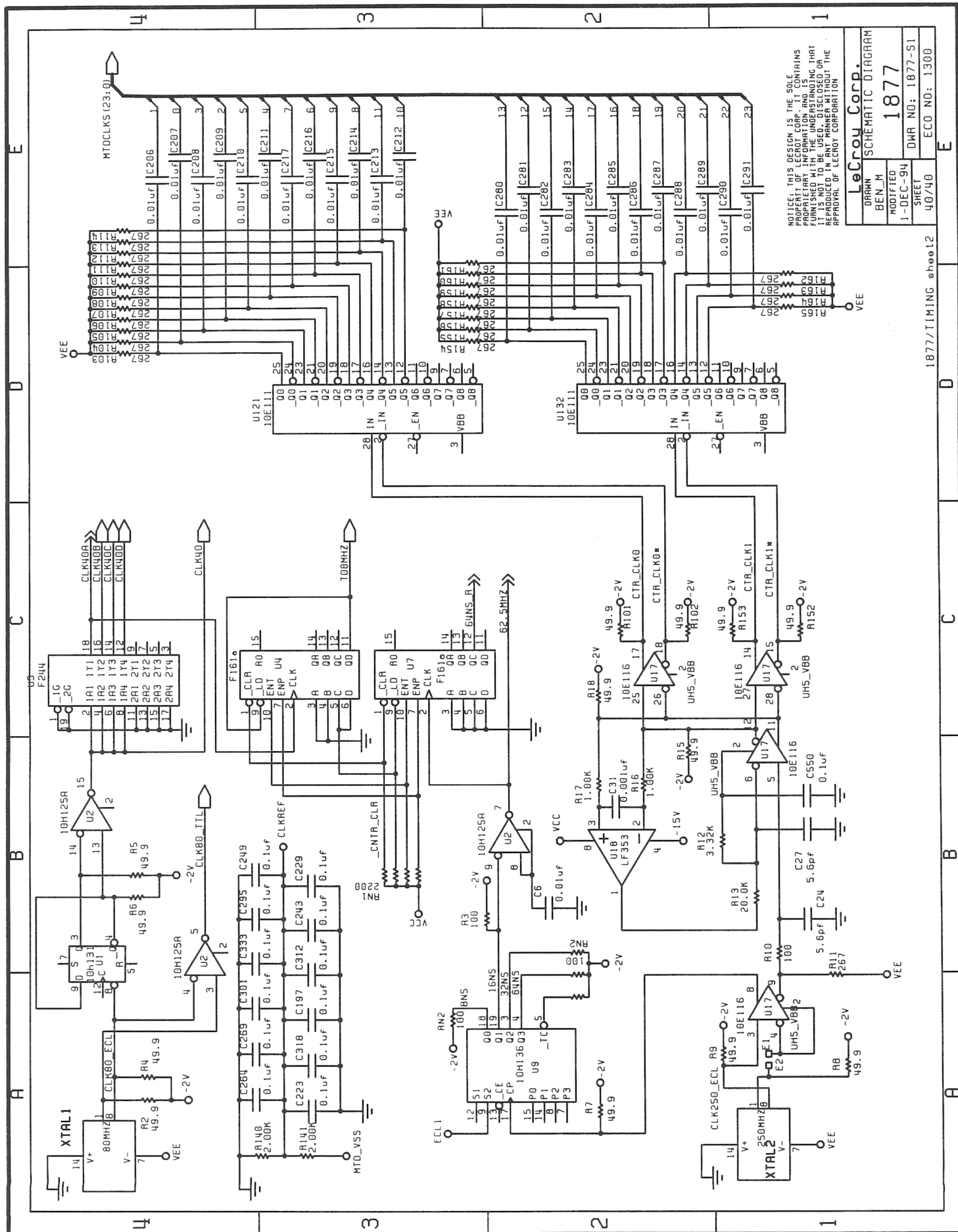




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LeCroy Corp.			
DRAWN	BEN M	SCHEMATIC DIAGRAM	
MODIFIED		1877	
SHEET	39/40	DWR NO: 1877-S1	
PB-NDV-94			

1877/TIMING sheet 1



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LeCroy Corp.	
DRAWN	BEN_M
MODIFIED	1-DEC-94
SHEET	40/40
ECO NO:	1877-S1
1877/TIMING sheet2	

1877/TIMING sheet2