

NEO-M9N

u-blox M9 standard precision module

Data sheet



Abstract

Technical data sheet describing the u-blox NEO-M9N module. NEO-M9N offers ultra-robust meter-level GNSS positioning performance with concurrent reception of up to four GNSS (GPS, GLONASS, BeiDou, Galileo) in a 12.2 x 16.0 mm package.

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This document applies to the following products:

Product name	Type number	Firmware version	PCN reference
NEO-M9N	NEO-M9N-00B-00	SPG 4.00	N/A

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1 Functional description

1.1 Overview

The NEO-M9N GNSS receiver features the u-blox M9 standard precision GNSS platform, and provides exceptional sensitivity and acquisition times for all L1 GNSS systems. u-blox M9 receivers are available in different variants to serve automotive and industrial tracking applications, such as navigation, telematics and UAVs.

The u-blox M9 standard precision GNSS platform, which delivers meter-level accuracy, succeeds the well-known u-blox M8 product range.

u-blox M9 receivers support concurrent reception of four GNSS. The high number of visible satellites allows the receiver to select the best signals. This maximizes the position accuracy, in particular under challenging conditions such as deep urban canyons.

u-blox M9 receivers detect jamming and spoofing events and report them to the host, which allows the system to react to such events. Advanced filtering algorithms mitigate the impact of RF interference and jamming, thus enabling the product to operate as intended.

The receiver also provides higher navigation rate and improved security features compared to previous u-blox GNSS generations.

The NEO-M9N module is available in the 12.2 x 16.0 mm NEO form factor LCC package.

1.2 Performance

Parameter		Specification				
Receiver type		Multi-constellation GNSS standard precision receiver				
Accuracy of time pulse signal		RMS		30ns		
		99%		60ns		
Frequency of time pulse signal		0.25 Hz to 10 MHz (configurable)				
Operational limits ¹		Dynamics		≤ 4 g		
		Altitude		80,000 m		
		Velocity		500 m/s		
Velocity accuracy ²		0.05 m/s				
Dynamic heading accuracy		0.3 deg				
GNSS		GPS+GLO+GAL+BDS	GPS+GLO+GAL	GPS+GLO	GPS+BDS	GPS+GAL
Acquisition ³	Cold start	24 s	25 s	26 s	28 s	29 s
	Hot start	2 s	2 s	2 s	2 s	2 s
	Aided start ⁴	2 s	2 s	2 s	2 s	2 s
Nav. update rate	PVT	25 Hz	25 Hz	25 Hz	25 Hz	25 Hz

¹ Assuming Airborne 4 g platform

² 50% @ 30 m/s for dynamic operation

³ Commanded starts. All satellites at -130 dBm. GPS always in combination with QZSS and SBAS. Measured at room temperature.

⁴ Dependent on the speed and latency of the aiding data connection, commanded starts.

GNSS		GPS+GLO+GAL+BDS	GPS+GLO+GAL	GPS+GLO	GPS+BDS	GPS+GAL
Sensitivity ⁵	Tracking and nav.	-167 dBm	-167 dBm	-167 dBm	-166 dBm	-166 dBm
	Reacquisition	-160 dBm	-160 dBm	-160 dBm	-160 dBm	-160 dBm
	Cold start	-148 dBm	-148 dBm	-148 dBm	-148 dBm	-148 dBm
	Hot start	-159 dBm	-159 dBm	-159 dBm	-159 dBm	-159 dBm
Position accuracy	PVT	2.0 m CEP	2.0 m CEP	2.0 m CEP	2.0 m CEP	2.0 m CEP

Table 1: NEO-M9N typical performance in multi-constellation GNSS modes

GNSS		GPS	GLONASS	BEIDOU	GALILEO
Acquisition ³	Cold start	29 s	27 s	32 s	42 s
	Hot start	2 s	2 s	2 s	2 s
	Aided start ⁴	2 s	2 s	2 s	2 s
Nav. update rate	PVT	25 Hz	25 Hz	25 Hz	25 Hz
Sensitivity ⁵	Tracking and nav.	-166 dBm	-164 dBm	-160 dBm	-159 dBm
	Reacquisition	-160 dBm	-155 dBm	-157 dBm	-154 dBm
	Cold start	-148 dBm	-145 dBm	-145 dBm	-140 dBm
	Hot start	-159 dBm	-156 dBm	-159 dBm	-154 dBm
Position accuracy	PVT	2.0 m CEP	4.0 m CEP	3.0 m CEP	3.0 m CEP

Table 2: NEO-M9N typical performance in single-GNSS modes

1.3 Supported GNSS constellations

The NEO-M9N is a concurrent GNSS receiver which can receive and track multiple GNSS systems. Owing to the multi-band RF front-end architecture all four major GNSS constellations, GPS, Galileo, GLONASS and BeiDou can be received concurrently. The NEO-M9N receiver can be configured for concurrent GPS, GLONASS, Galileo and BeiDou plus SBAS and QZSS reception. If power consumption is a key factor, then the receiver can be configured for a sub-set of GNSS constellations.

The NEO-M9N supports the GNSS and their signals as shown in [Table 3](#).

GPS	GLONASS	Galileo	BeiDou
L1C/A (1575.42 MHz)	L1OF (1602 MHz + k*562.5 kHz, k = -7,..., 5, 6)	E1-B/C (1575.42 MHz)	B1I (1561.098 MHz)

Table 3: Supported GNSS and signals on NEO-M9N

The following GNSS assistance services can be activated on NEO-M9N:

AssistNow™ Online	AssistNow™ Offline	AssistNow™ Autonomous
Supported	Supported	Supported

Table 4: Supported Assisted GNSS (A-GNSS) Services

NEO-M9N supports the following augmentation systems:

SBAS	QZSS	IMES	Differential GNSS
EGNOS, GAGAN, MSAS and WAAS supported	L1s (SAIF) supported	Not supported	RTCM 3.3

Table 5: Supported Augmentation Systems of NEO-M9N


The augmentation systems SBAS and QZSS can be enabled only if GPS operation is also enabled.

⁵ Demonstrated with a good external LNA. Measured at room temperature.

1.4 Supported protocols

The NEO-M9N supports the following protocols:

Protocol	Type
UBX	Input/output, binary, u-blox proprietary
NMEA 4.10	Input/output, ASCII
RTCM 3.3	Input only, binary

Table 6: Supported protocols

For specification of the protocols, see the u-blox NEO-M9N Interface description [2].

1.5 Firmware features

Feature	Description
Assisted GNSS	AssistNow Online, AssistNow Offline and AssistNow Autonomous supported
Backup modes	Hardware backup mode, software backup mode
Data batching	Autonomous tracking up to 5 min
Data-logger	Position, velocity, time, and odometer data
Geo-fencing	Up to 4 circular areas
Power save modes	On/off, cyclic
Odometer	Measure traveled distance with support for different user profiles
Upgradeable firmware	Firmware can be upgraded via host upload or updated in the internal flash memory.

Table 7: Firmware features

Feature	Description
Anti-jamming	RF interference and jamming detection and reporting; Active GNSS in-band filtering
Anti-spoofing	Spoofing detection and reporting
Configuration lockdown	Receiver configuration can be locked by command
Message integrity	All messages signed with SHA-256
Secure boot	Only signed FW images executed

Table 8: Security features

2 System description

2.1 Block diagram

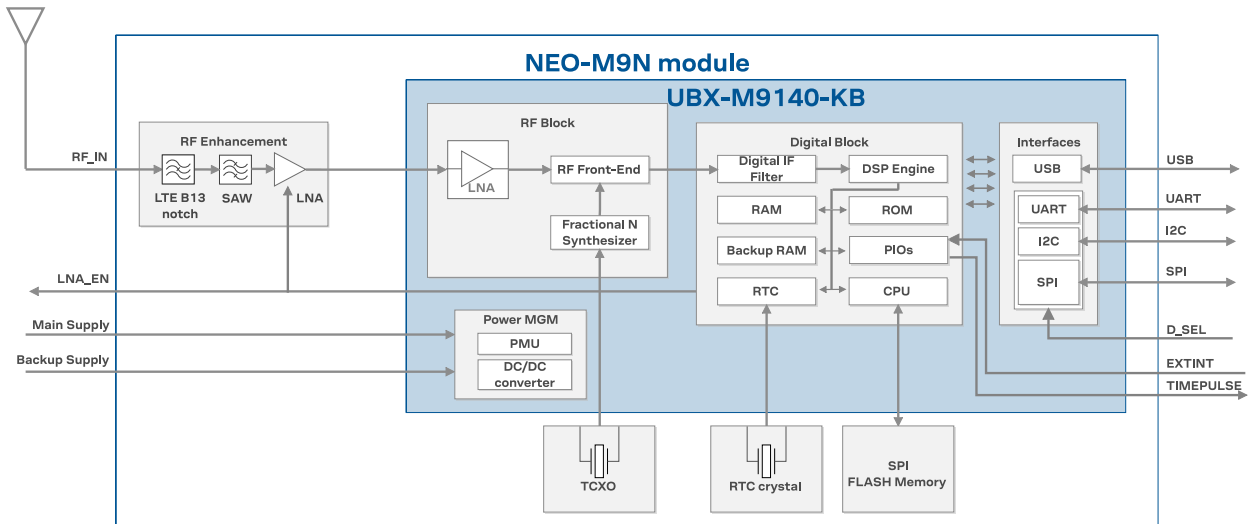


Figure 1: NEO-M9N block diagram

3 Pin definition

3.1 Pin assignment

The pin assignment of the NEO-M9N module is shown in [Figure 2](#). The defined configuration of the PIOs is listed in [Table 9](#).

For detailed information on pin functions and characteristics, see the u-blox NEO-M9N Integration manual [\[1\]](#).

13	GND	GND	12
14	LNA_EN	RF_IN	11
15	Reserved	GND	10
16	Reserved	VCC_RF	9
17	Reserved	RESET_N	8
NEO-M9N Top View			
18	SDA / SPI CS_N	V_USB	7
19	SCL / SPI SLK	USB_DP	6
20	TXD / SPI MISO	USB_DM	5
21	RXD / SPI MOSI	EXTINT	4
22	V_BCKP	TIMEPULSE	3
23	VCC	D_SEL	2
24	GND	SAFEBOOT_N	1

Figure 2: NEO-M9N pin assignment

Pin No	Name	I/O	Description
1	SAFEBOOT_N	I	SAFEBOOT_N (used for FW updates and reconfiguration, leave open)
2	D_SEL	I	Interface select (open or VCC = UART + I2C; GND = SPI)
3	TIMEPULSE	O	TIMEPULSE (1 PPS)
4	EXTINT	I	EXTINT (PIO 7)
5	USB_DM	I/O	USB data (DM)
6	USB_DP	I/O	USB data (DP)
7	V_USB	I	USB Supply
8	RESET_N	I	RESET (active low)
9	VCC_RF	O	Voltage for external LNA
10	GND	I	Ground
11	RF_IN	I	GNSS signal input
12	GND	I	Ground
13	GND	I	Ground
14	LNA_EN	O	Antenna/LNA control
15	Reserved	-	Reserved

Pin No	Name	I/O	Description
16	Reserved	-	Reserved
17	Reserved	-	Reserved
18	SDA / SPI CS_N	I/O	I2C data if D_SEL = VCC (or open); SPI chip select if D_SEL = GND
19	SCL / SPI SLK	I/O	I2C clock if D_SEL = VCC (or open); SPI clock if D_SEL = GND
20	TXD / SPI MISO	O	UART output if D_SEL = VCC (or open); SPI MISO if D_SEL = GND
21	RXD / SPI MOSI	I	UART input if D_SEL = VCC (or open); SPI MOSI if D_SEL = GND
22	V_BCKP	I	Backup voltage supply
23	VCC	I	Supply voltage
24	GND	I	Ground

Table 9: NEO-M9N pin assignment


For detailed information on the pin functions and characteristics see the u-blox NEO-M9N Integration manual [1].

4 Electrical specification



The limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only. Operation of the device at these or at any other conditions above those given below is not implied. Exposure to limiting values for extended periods may affect device reliability.



Where application information is given, it is advisory only and does not form part of the specification.



For detailed information on the device integration, see the u-blox NEO-M9N Integration manual [1].

4.1 Absolute maximum ratings

Parameter	Symbol	Condition	Min	Max	Units
Power supply voltage	VCC		-0.5	3.6	V
Backup battery voltage	V_BCKP		-0.5	3.6	V
Input pin voltage	Vin	VCC ≤ 3.1 V	-0.5	VCC + 0.5	V
		VCC > 3.1 V	-0.5	3.6	V
VCC_RF output current	ICC_RF			100	mA
Supply voltage USB	V_USB		-0.5	3.6	V
USB signals	USB_DN, USB_DP		-0.5	V_USB + 0.5 V	
Input power at RF_IN	Prfin	source impedance = 50 Ω, continuous wave		13 ⁶	dBm
Storage temperature	Tstg		-40	+85	°C

Table 10: Absolute maximum ratings



The product is not protected against overvoltage or reversed voltages. Voltage spikes exceeding the power supply voltage specification, given in the table above, must be limited to values within the specified boundaries by using appropriate protection diodes.

4.2 Operating conditions



All specifications are at an ambient temperature of 25 °C. Extreme operating temperatures can significantly impact the specification values. Applications operating near the temperature limits should be tested to ensure the specification.

Parameter	Symbol	Min	Typical	Max	Units	Condition
Power supply voltage	VCC	2.7	3.0	3.6	V	
Backup battery voltage	V_BCKP	1.65		3.6	V	
Backup battery current	I_BCKP		36		μA	
SW backup current	I_SWBCKP		0.33		mA	
Input pin voltage range	Vin	0		VCC	V	
Digital IO pin low level input voltage	Vil			0.4	V	
Digital IO pin high level input voltage	Vih	0.8 * VCC			V	
Digital IO pin low level output voltage	Vol			0.4	V	Iol = 2 mA
Digital IO pin high level output voltage	Voh	VCC – 0.4			V	Ioh = 2 mA

⁶ +13 dBm for outband; 0 dBm for inband

Parameter	Symbol	Min	Typical	Max	Units	Condition
VCC_RF voltage	VCC_RF		VCC - 0.1		V	
VCC_RF output current	ICC_RF			50	mA	
Receiver chain noise figure ⁷	NFtot		3.5		dB	
Operating temperature	Topr	-40	+25	85	°C	

Table 11: Operating conditions


Operation beyond the specified operating conditions can affect device reliability.

4.3 Indicative power requirements

Table 12 lists examples of the total system supply current including RF and baseband section for a possible application.



Values in **Table 12** are provided for customer information only, as an example of typical current requirements. Values are characterized on samples with using a command cold start. Actual power requirements can vary depending on FW version used, external circuitry, number of SVs tracked, signal strength, type and time of start, duration, and conditions of test.

Symbol	Parameter	Conditions	GPS+GLO+GAL+BDS	GPS+GLO	GPS	Unit
I _{PEAK}	Peak current	Acquisition	100	100	100	mA
I _{VCC} ⁸	VCC current	Acquisition	50	42	37	mA
		Tracking (Continuous mode)	36	31	27	mA
		Tracking (Power save mode)	20	20	19	mA

Table 12: Currents to calculate the indicative power requirements

All values in **Table 12** are measured at 25 °C ambient temperature. SBAS is activated in all measurements.

⁷ Only valid for the GPS

⁸ Simulated signal, current measured at 3.0 V

5 Communications interfaces

There are several communications interfaces including UART, SPI, I2C⁹ and USB.

All the inputs have internal pull-up resistors in normal operation and can be left open if not used. All the PIOs are supplied by VCC, therefore all the voltage levels of the PIO pins are related to VCC supply voltage.

5.1 UART interface

There is one UART interface: UART1, which operates up to and including a speed of 921600 baud. No hardware flow control is supported.

UART1 is enabled by default if D_SEL = 1 or unconnected.

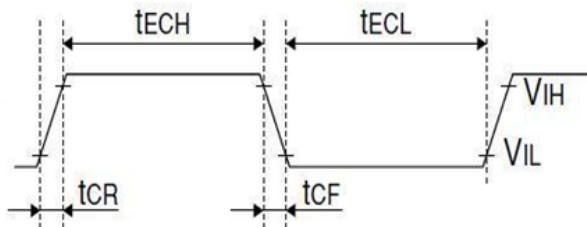


Figure 3: NEO-M9N module UART timing specifications

Symbol	Parameter	Min	Max	Unit
t_{ECH}	High period of external data input	0	0.4	μs
t_{ECL}	Low period of external data input	TBA	TBA	μs
R_u	Baudrate	4800	921600	bd
t_{CR}	Rise time of data		5	ns
t_{CF}	Fall time of data		5	ns

Table 13: NEO-M9N UART timings and specifications

5.2 SPI interface

The NEO-M9N has an SPI slave interface that can be selected by setting D_SEL = 0. The SPI pins available are: SPI_MISO (TXD), SPI_MOSI (RXD), SPI_CS_N, SPI_CLK. The SPI interface is designed to allow communication to a host CPU. The interface can be operated in slave mode only. Note that SPI is not available in the default configuration because its pins are shared with the UART and I2C interfaces. The maximum transfer rate using SPI is 125 kB/s and the maximum SPI clock frequency is 5.5 MHz.

This section provides SPI timing values for the NEO-M9N slave operation. The following tables present timing values under different capacitive loading conditions. Default SPI configuration is CPOL = 0 and CPHA = 0.

⁹ I2C is a registered trademark of Philips/NXP

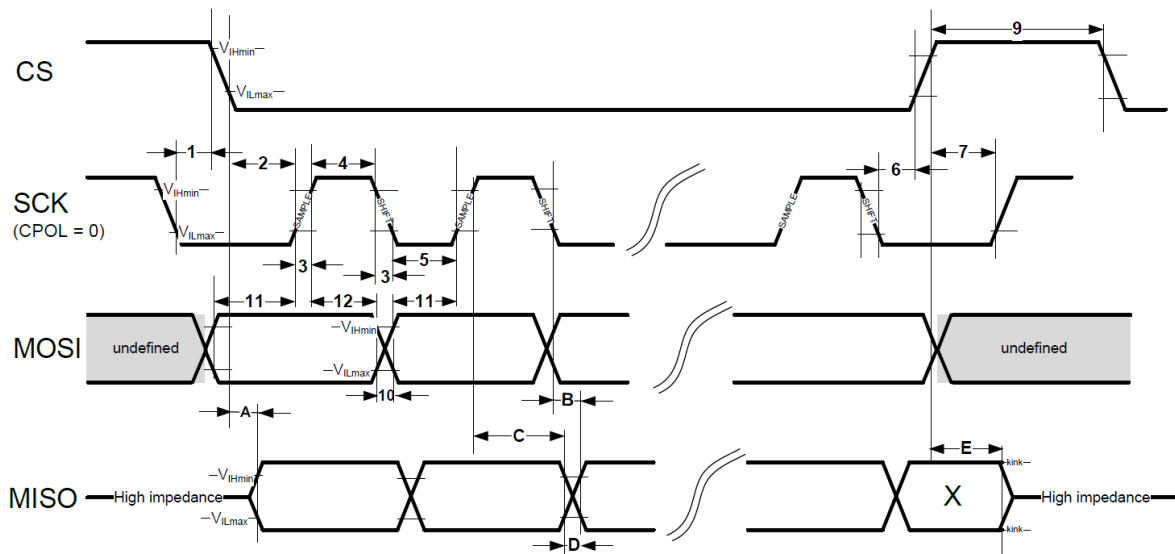


Figure 4: NEO-M9N module SPI specification mode 1: CPHA=0 SCK = 5.33 MHz



Timings 1 - 12 are not specified here as those are depending on SPI master. Timings A - E are specified for SPI slave.

Timing value at 2 pF load	Min (ns)	Max (ns)
"A" - MISO data valid time (CS)	14	38
"B" - MISO data valid time (SCK) weak driver mode	21	38
"C" - MISO data hold time	114	130
"D" - MISO rise/fall time, weak driver mode	1	4
"E" - MISO data disable lag time	20	32

Table 14: NEO-M9N SPI timings at 2pF load

Timing value at 20 pF load	Min (ns)	Max (ns)
"A" - MISO data valid time (CS)	19	52
"B" - MISO data valid time (SCK) weak driver mode	25	51
"C" - MISO data hold time	117	137
"D" - MISO rise/fall time, weak driver mode	6	16
"E" - MISO data disable lag time	20	32

Table 15: NEO-M9N SPI timings at 20pF load

Timing value at 60 pF load	Min (ns)	Max (ns)
"A" - MISO data valid time (CS)	29	79
"B" - MISO data valid time (SCK) weak driver mode	35	78
"C" - MISO data hold time	122	152
"D" - MISO rise/fall time, weak driver mode	15	41
"E" - MISO data disable lag time	20	32

Table 16: NEO-M9N SPI timings at 60pF load

5.3 Slave I2C interface

An I2C compliant interface is available for communication with an external host CPU. The interface can be operated in slave mode only. It is fully compatible with Fast-Mode of the I2C industry

standard. Since the maximum SCL clock frequency is 400 kHz, the maximum bit rate is 400 kbit/s. The interface stretches the clock when slowed down while serving interrupts, therefore the real bit rates may be slightly lower.



The I2C interface is only available with the UART default mode. If the SPI interface is selected by using $D_SEL = 0$, the I2C interface is not available.

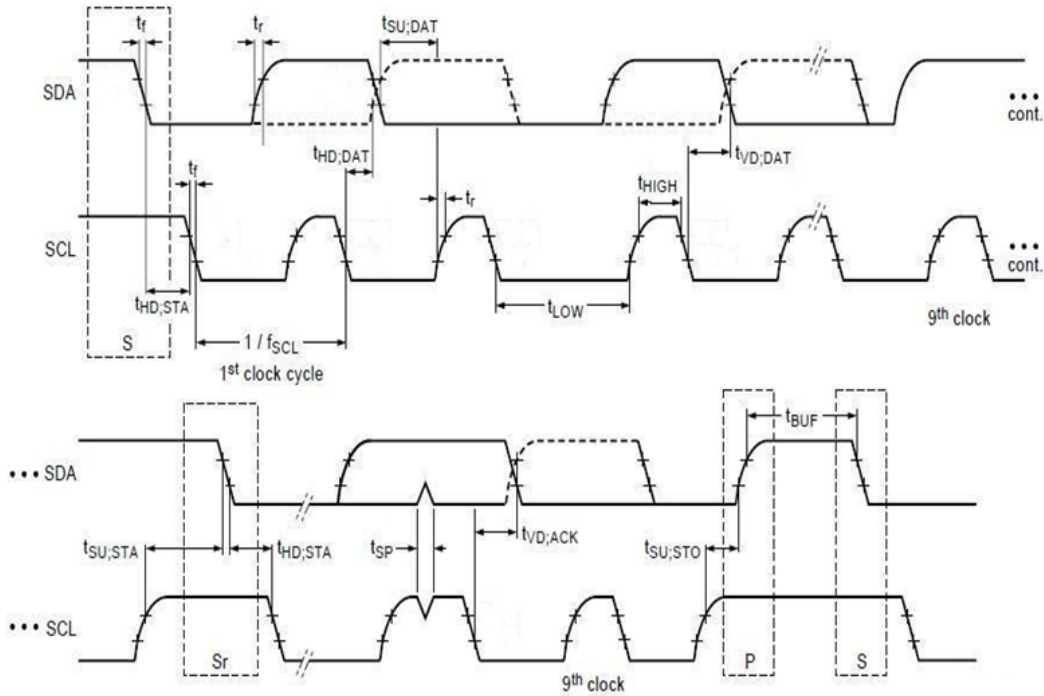


Figure 5: NEO-M9N module I2C slave specification

Symbol	Parameter	Min (Standard / Fast-mode)	Max	Unit
f_{SCL}	SCL clock frequency	0	400	kHz
$t_{HD,STA}$	Hold time (repeated) START condition	4.0/1	-	μs
t_{LOW}	Low period of the SCL clock	5/2	-	μs
t_{HIGH}	High period of the SCL clock	4.0/1	-	μs
$t_{SU,STA}$	Set-up time for a repeated START condition	5/1	-	μs
$t_{HD,DAT}$	Data hold time	0/0	-	μs
$t_{SU,DAT}$	Data set-up time	250/100	-	ns
t_r	Rise time of both SDA and SCL signals	-	1000/300 (for C = 400pF)	ns
t_f	Fall time of both SDA and SCL signals	-	300/300 (for C = 400pF)	ns
$t_{SU,STO}$	Set-up time for STOP condition	4.0/1	-	μs
t_{BUF}	Bus free time between a STOP and START condition	5/2	-	μs
$t_{VD,DAT}$	Data valid time	-	4/1	μs
$t_{VD,ACK}$	Data valid acknowledge time	-	4/1	μs
V_{nL}	Noise margin at the low level	0.1 VCC	-	V
V_{nH}	Noise margin at the high level	0.2 VCC	-	V

Table 17: NEO-M9N I2C slave timings and specifications

5.4 USB interface

A USB interface, which is compatible to USB version 2.0 FS (Full Speed, 12 Mbit/s), can be used for communication to a host. The V_USB pin supplies the USB interface.

5.5 Default interface settings

Interface	Settings
UART	38400 Baud, 8 bits, no parity bit, 1 stop bit. Output messages: NMEA GGA , GLL , GSA , GSV , RMC , VTG , TXT (no UBX). Input protocols: UBX, NMEA and RTCM 3.3.
USB	Output messages activated as in UART. Input protocols available as in UART.
I2C	Output messages activated as in UART. Input protocols available as in UART.
SPI	Output messages activated as in UART. Input protocols available as in UART.

Table 18: Default interface settings



Refer to the u-blox NEO-M9N Interface description [2] for information about further settings.

By default the NEO-M9N outputs NMEA 4.10 messages that include satellite data for all GNSS bands being received. This results in a higher-than-before NMEA load output for each navigation period. Make sure the UART baud rate being used is sufficient for the selected navigation rate and the number of GNSS signals being received.

6 Mechanical specification

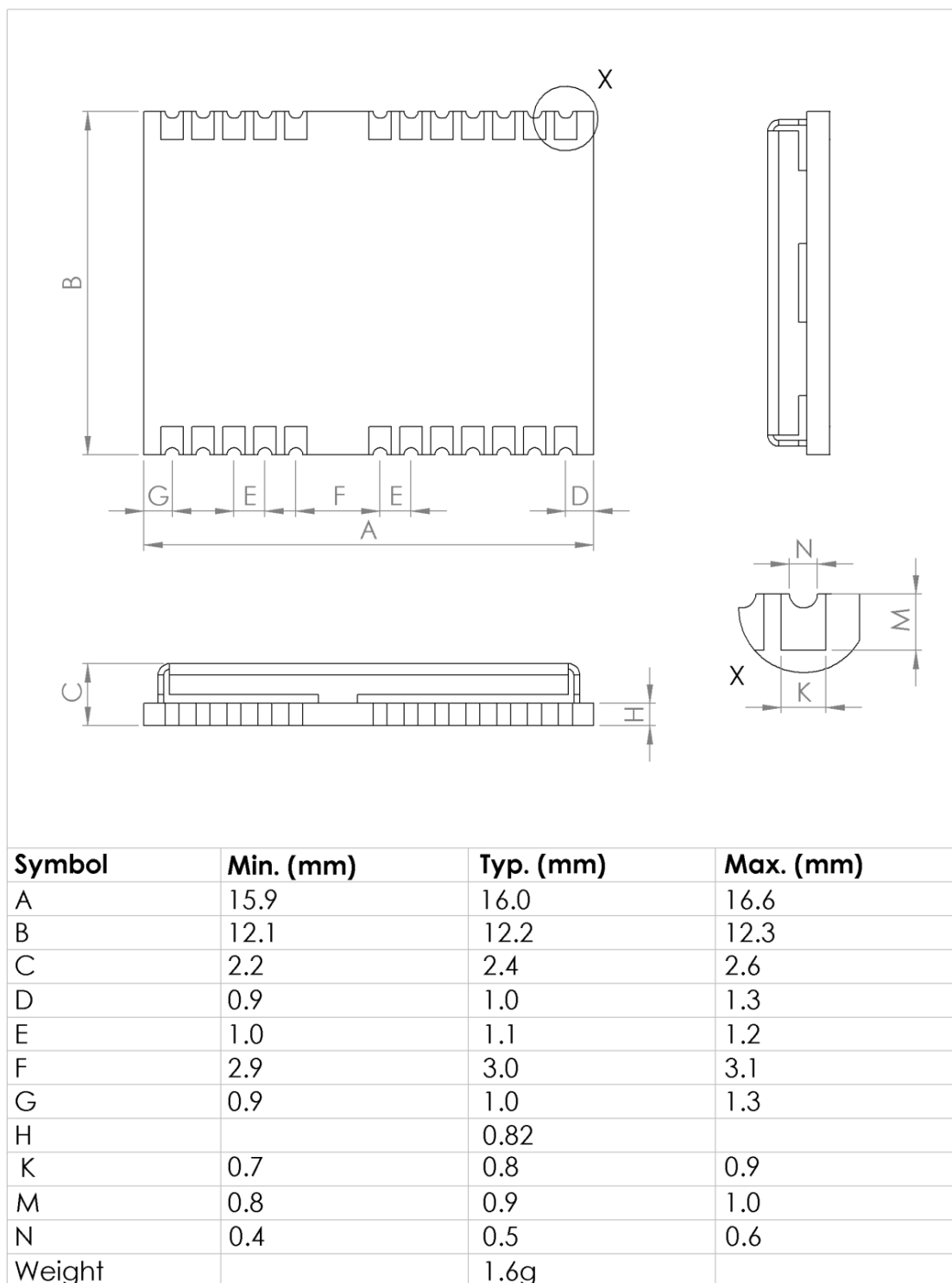


Figure 6: NEO-M9N mechanical drawing

7 Reliability tests and approvals

All u-blox modules are based on AEC-Q100 qualified GNSS chips.

Tests for product family qualifications are according to ISO 16750 "Road vehicles – environmental conditions and testing for electrical and electronic equipment", and appropriate standards.

7.1 Approvals



The NEO-M9N is designed to in compliance with the essential requirements and other relevant provisions of Radio Equipment Directive (RED) 2014/53/EU.

The NEO-M9N complies with the Directive 2011/65/EU (EU RoHS 2) and its amendment Directive (EU) 2015/863 (EU RoHS 3).

Declaration of Conformity (DoC) is available on the [u-blox website](#).

8 Labeling and ordering information

This section provides information about product labeling and ordering. For information about product handling and soldering see the NEO-M9N Integration manual [1].

8.1 Product labeling

The labeling of the NEO-M9N modules provides product information and revision information. For more information contact u-blox sales.

8.2 Explanation of product codes

Three different product code formats are used. The **Product name** is used in documentation such as this data sheet and identifies all u-blox products, independent of packaging and quality grade. The **Ordering code** includes options and quality, while the **Type number** includes the hardware and firmware versions. Table 19 below details these three different formats.

Format	Structure	Code for this product
Product name	PPP-TGV	NEO-M9N
Ordering code	PPP-TGV-NNQ	NEO-M9N-00B
Type number	PPP-TGV-NNQ-XX	NEO-M9N-00B-00

Table 19: Product code formats

The parts of the product code are explained in Table 20.

Code	Meaning	Example
PPP	Product family	NEO
TG	Platform	M9 = u-blox M9
V	Variant	N = Standard precision with SAW and LNA
NNQ	Option / Quality grade	NN: Option [00...99] Q: Grade, A = Automotive, B = Professional
XX	Product detail	Describes hardware and firmware versions

Table 20: Part identification code

8.3 Ordering codes

Ordering code	Product	Remark
NEO-M9N-00B	u-blox NEO-M9N module, professional grade	

Table 21: Product ordering codes



Product changes affecting form, fit or function are documented by u-blox. For a list of Product Change Notifications (PCNs) see our website at: <https://www.u-blox.com/en/product-resources>.

Related documents

- [1] NEO-M9N Integration manual, doc. no. UBX-19014286
- [2] NEO-M9N Interface description, doc. no. UBX-19035940



For regular updates to u-blox documentation and to receive product change notifications please register on our homepage (<http://www.u-blox.com>).

Revision history

Revision	Date	Name	Status / comments
R01	15-Aug-2019	jesk	Objective specification
R02	14-Nov-2019	jesk	Advance information
R03	24-Jan-2020	jesk	Advance information. Added outband value for Prfin, renamed VDD_USB to V_USB.

Contact

For complete contact information visit us at www.u-blox.com.

u-blox Offices

North, Central and South America

u-blox America, Inc.

Phone: +1 703 483 3180
E-mail: info_us@u-blox.com

Regional Office West Coast

Phone: +1 408 573 3640
E-mail: info_us@u-blox.com

Technical Support

Phone: +1 703 483 3185
E-mail: support_us@u-blox.com

Headquarters

Europe, Middle East, Africa

u-blox AG

Phone: +41 44 722 74 44
E-mail: info@u-blox.com
Support: support@u-blox.com

Asia, Australia, Pacific

u-blox Singapore Pte. Ltd.

Phone: +65 6734 3811
E-mail: info_ap@u-blox.com
Support: support_ap@u-blox.com

Regional Office Australia

Phone: +61 2 8448 2016
E-mail: info_au@u-blox.com
Support: support_ap@u-blox.com

Regional Office China (Beijing)

Phone: +86 10 68 133 545
E-mail: info_cn@u-blox.com
Support: support_cn@u-blox.com

Regional Office China (Chongqing)

Phone: +86 23 6815 1588
E-mail: info_cn@u-blox.com
Support: support_cn@u-blox.com

Regional Office China (Shanghai)

Phone: +86 21 6090 4832
E-mail: info_cn@u-blox.com
Support: support_cn@u-blox.com

Regional Office China (Shenzhen)

Phone: +86 755 8627 1083
E-mail: info_cn@u-blox.com
Support: support_cn@u-blox.com

Regional Office India

Phone: +91 80 4050 9200
E-mail: info_in@u-blox.com
Support: support_in@u-blox.com

Regional Office Japan (Osaka)

Phone: +81 6 6941 3660
E-mail: info_jp@u-blox.com
Support: support_jp@u-blox.com

Regional Office Japan (Tokyo)

Phone: +81 3 5775 3850
E-mail: info_jp@u-blox.com
Support: support_jp@u-blox.com

Regional Office Korea

Phone: +82 2 542 0861
E-mail: info_kr@u-blox.com
Support: support_kr@u-blox.com

Regional Office Taiwan

Phone: +886 2 2657 1090
E-mail: info_tw@u-blox.com
Support: support_tw@u-blox.com