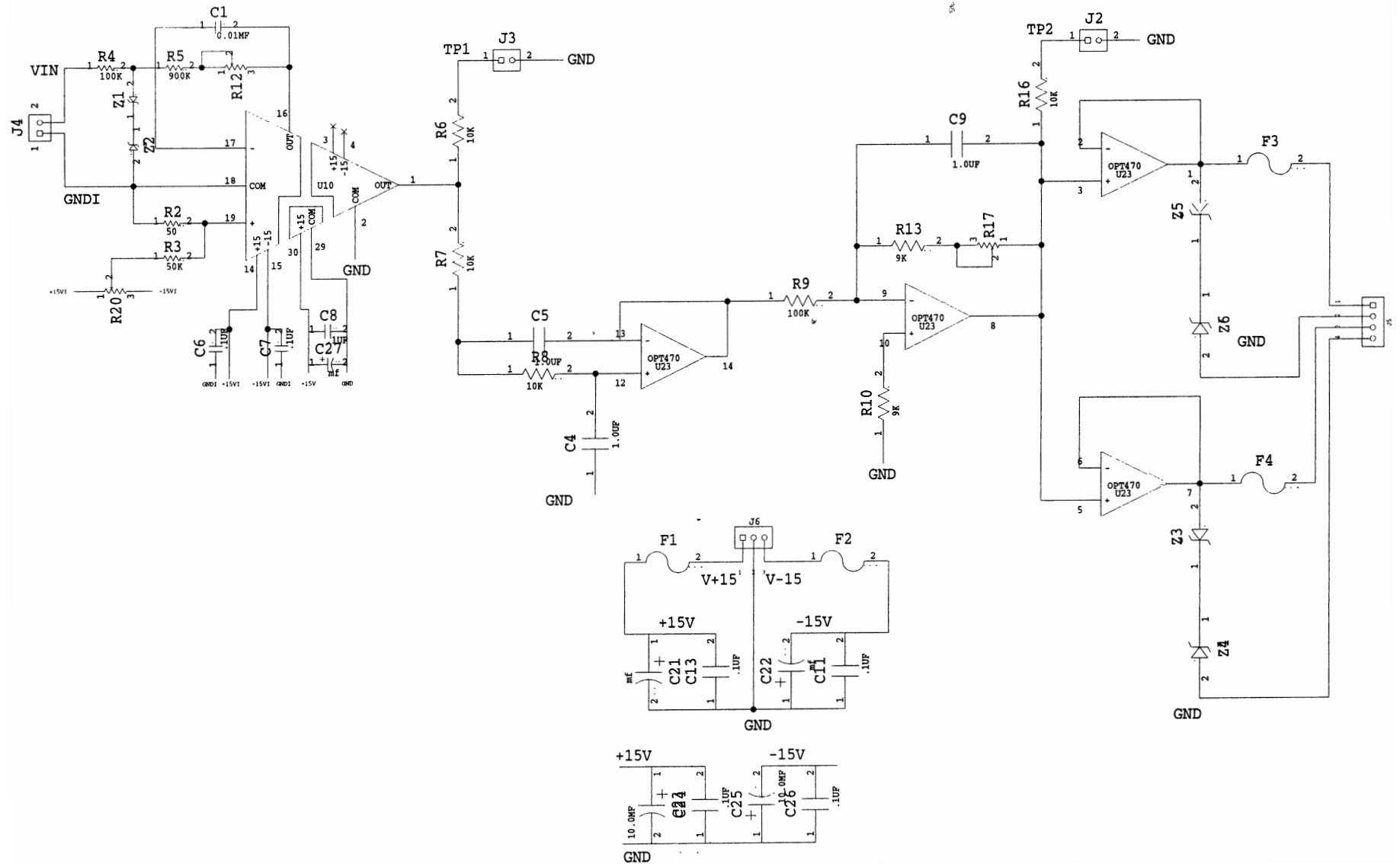
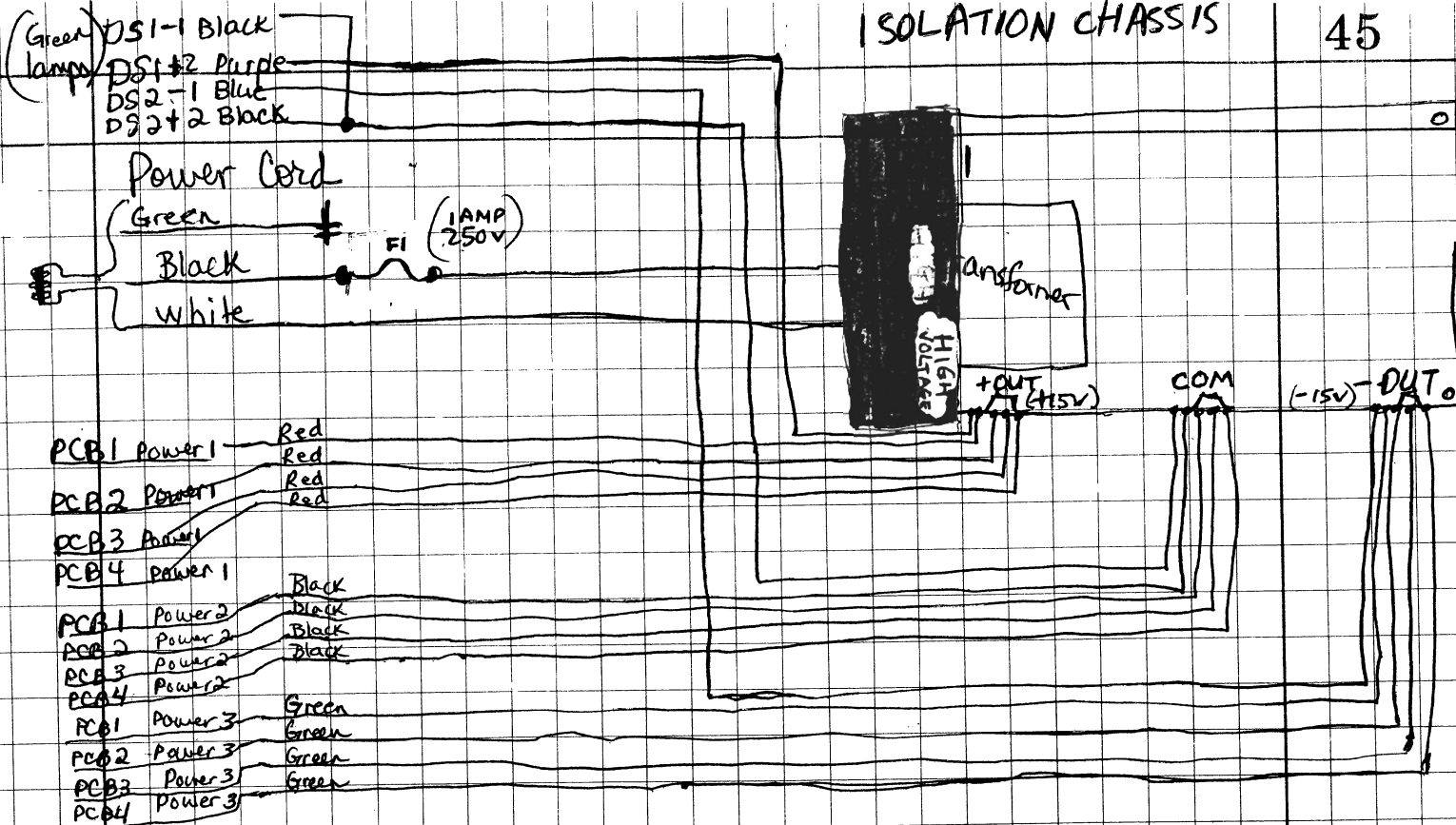
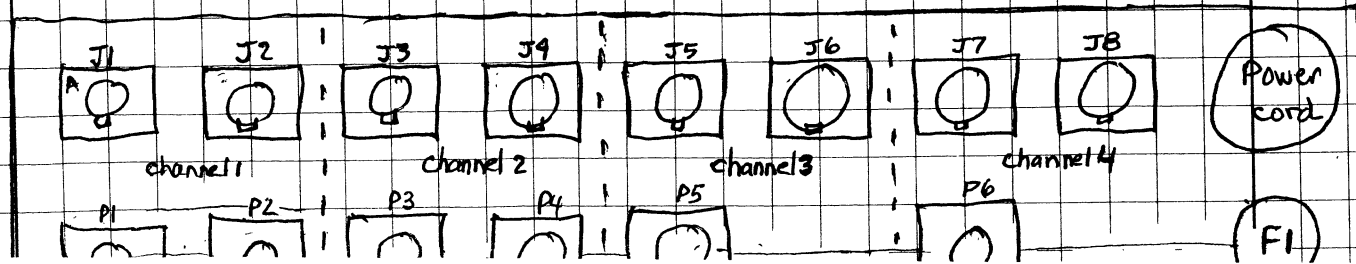
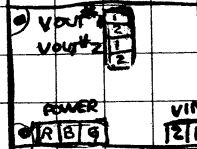


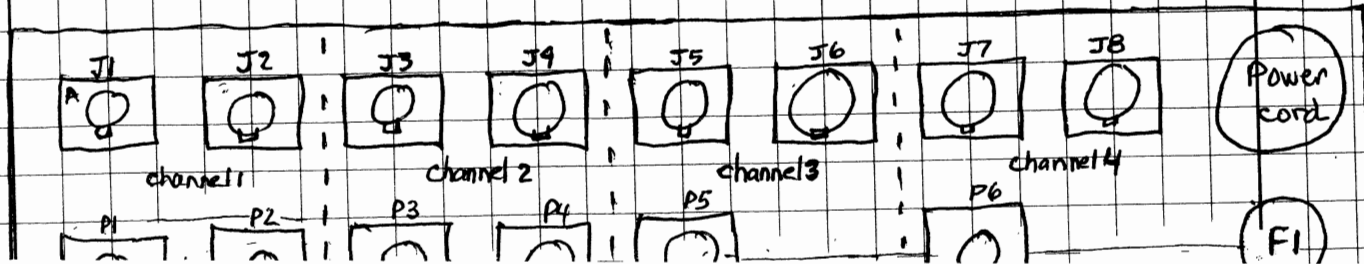
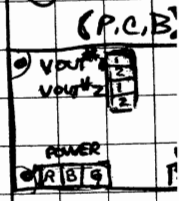
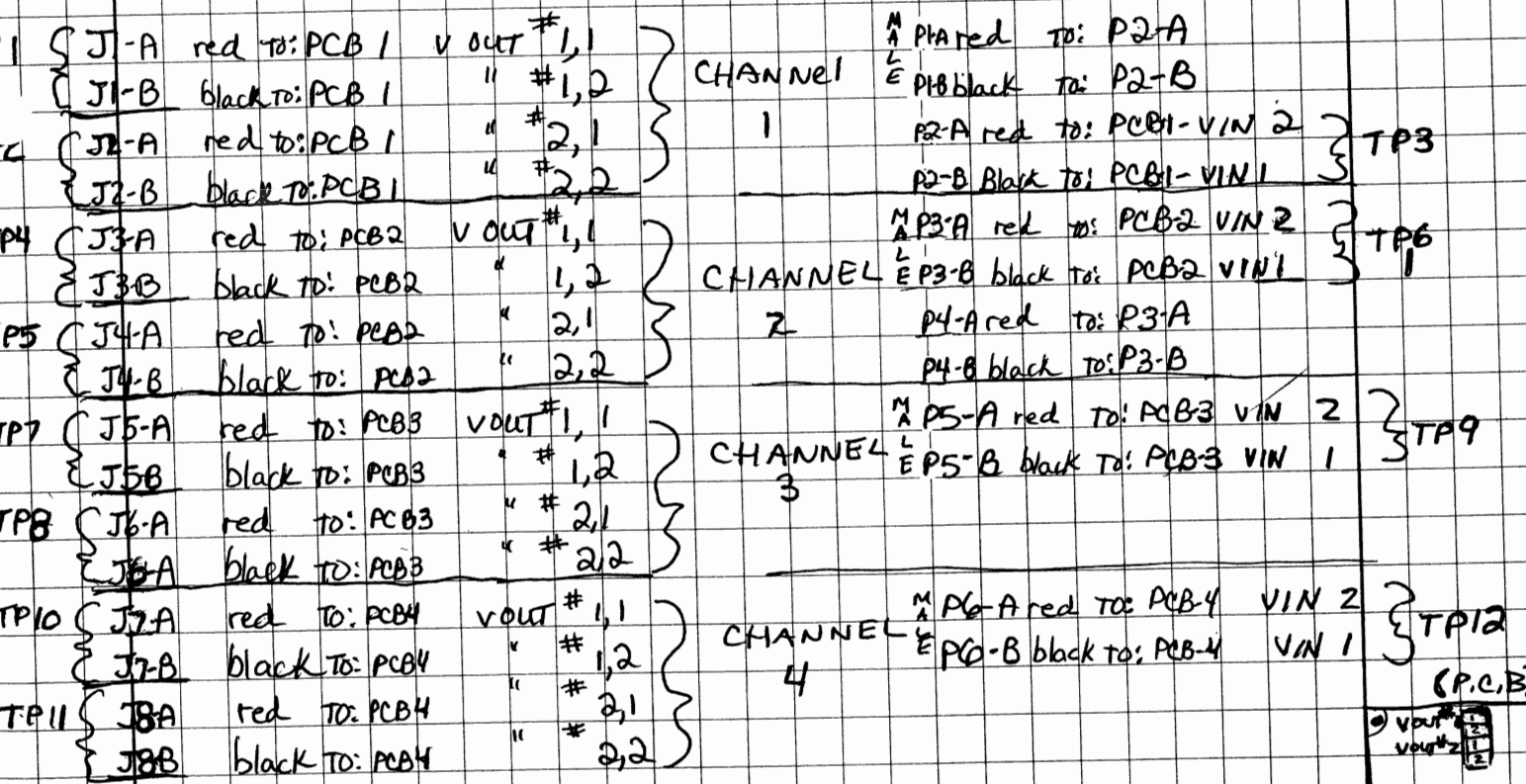
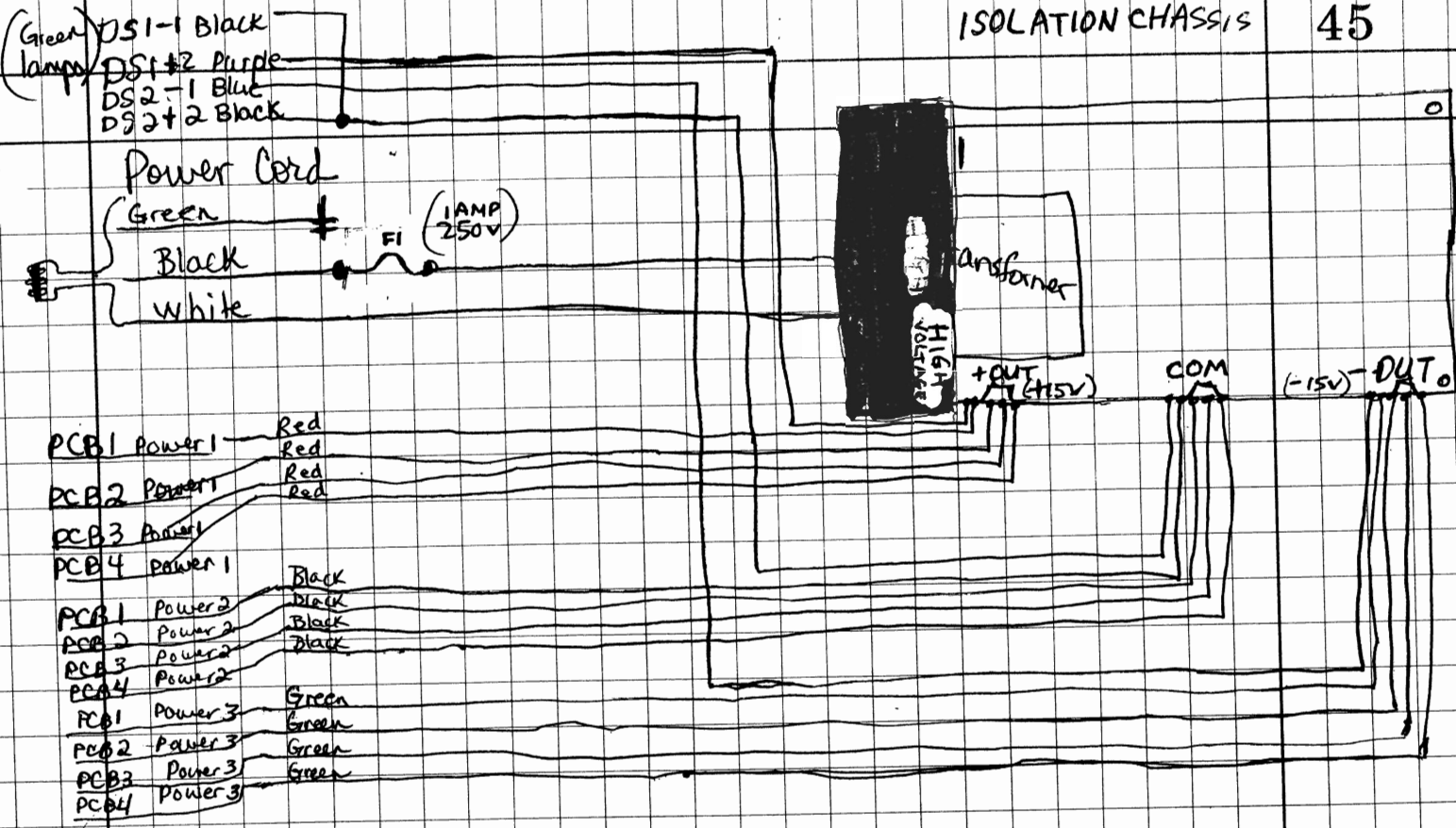
# HALLA ISOLATION CIRCUIT





P1	J1-A red to: PCB 1	V OUT #1,1	CHANNEL 1	P1-A red to: P2-A	TP3
	J1-B black to: PCB 1	" #1,2		P1-B black to: P2-B	
TP2	J2-A red to: PCB 1	" #2,1	1	P2-A red to: PCB1-VIN 2	TP3
	J2-B black to: PCB 1	" #2,2		P2-B Black to: PCB1-VIN 1	
TP4	J3-A red to: PCB2	V OUT #1,1	CHANNEL 2	P3-A red to: PCB2 VIN 2	TP6
	J3-B black to: PCB2	" 1,2		P3-B black to: PCB2 VIN 1	
TP5	J4-A red to: PCB2	" 2,1	2	P4-A red to: P3-A	TP9
	J4-B black to: PCB2	" 2,2		P4-B black to: P3-B	
TP7	J5-A red to: PCB3	V OUT #1,1	CHANNEL 3	P5-A red to: PCB3 VIN 2	TP9
	J5-B black to: PCB3	" #1,2		P5-B black to: PCB3 VIN 1	
TP8	J6-A red to: PCB3	" #2,1	3	P6-A red to: PCB4 VIN 2	TP12
	J6-B black to: PCB3	" #2,2			
TP10	J7-A red to: PCB4	V OUT #1,1	CHANNEL 4	P6-A red to: PCB4 VIN 2	TP12
	J7-B black to: PCB4	" #1,2			
TP11	J8-A red to: PCB4	" #2,1	4		(P.C.B)
	J8-B black to: PCB4	" #2,2			





**Table 1: Isolation Amplifier Parts List**

Component	Type	Manuf.	Part#	Vendor	Stock#	Designation
AD210BN	Iso OP-AMP	Analog Devices	AD210BN	Newark		U10 ✓
OP470FY	Quad OP-AMP	Analog Devices	OP470FY	Stkrm	5964-20174	U23 ✓
12v Zener			1N5242B	Stkrm	5961-10160	Z1, Z2, Z3, Z4, Z5, Z6 ✓
0.01 uF	Cap			Stkrm	5910-20026	C1 ✓
0.1 uF ●●●●	Cap			Stkrm	5910-20024	C6, C7, C8, C11, C13, C24, C26 ✓
1.0 uF ●●	Cap			Stkrm	5910-20027	C4, C5, C9
4.7 uF ○	Cap			Stkrm	5910-14110	C21, C22 ✓
100 uF	Cap			Stkrm	5910-14155	C27 ✓
<del>100K</del>	1%, 1/8 w			Stkrm	5905-10080	R2 ✓
<del>100K</del>	1%, 1/8 w			Stkrm	5905-10720	R10, R13 ✓
<del>100K</del>	1%, 1/8 w			Stkrm	5905-10740	R6, R7, R8, R16 ✓
<del>100K</del>	1%, 1/8 w			Stkrm	5905-10960	R3 ✓
<del>10.82M</del>	5%, 1/8 w			Stkrm	5905-21160	(R5) ?
<del>100M</del>	5%, 1/8 w			Stkrm	5905-21170	R5 ✓
<del>2K</del>	Pot, 20-turn	Bourns		Stkrm	5905-70360	R17 ✓
<del>50K</del>	Pot, 20-turn	Bourns		Stkrm	5905-70420	R20 ✓
<del>200K</del>	Pot, 20-turn	Bourns		Newark		R12 ✓
1/16 Amp	pico fuse	Littelfuse		Newark		F3, F4 ✓
1/8 Amp	pico fuse	Littelfuse		Newark		F1, F2 ✓
15V, 0.5A P/S	Power Supply	Aztek		Stkrm	6130-10235	
2-pin housing	Con-F	Molex		Newark		
3-pin housing	Con-F	Molex		Newark		
4-pin housing	Con-F	Molex		Newark		
2-pin header	Con-M	Molex		Newark		
3-pin header	Con-M	Molex		Newark		
4-pin header	Con-M	Molex		Newark		

user  
1  
1  
6  
1  
7  
3  
2  
1  
1  
2  
4  
1  
1  
1  
1  
1  
2

113  
ONE P.C.B.  
3190

100K

**Table 1: Isolation Amplifier Parts List**

Component	Type	Manuf.	Part#	Vendor	Stock#	Designation
Crimp Terminals	Pins	Molex		Newark		
2-pin MS Panel	Con-F		MS3110E8-2S			3 per board
2-pin MS Panel	Con-M		MS3110E8-2P			1 per board
2-pin MS Cable	Con-F		MS3116F8-2S			1 per board
2-pin MS Cable	Con-M		MS3116F8-2P			3 per board
Hex Standoff	3/8", 4-40			Stkrm	5310-92060	4 per board
<del>O2, O3 ONLY:</del>						
100K	1%, 1/8 w			Stkrm	5905-11080	R4, R9
<del>DIPOLE ONLY:</del>						
1M	5%					R4
10K	1%					R9

Jbaw  
5  
303

installed  
1 choice

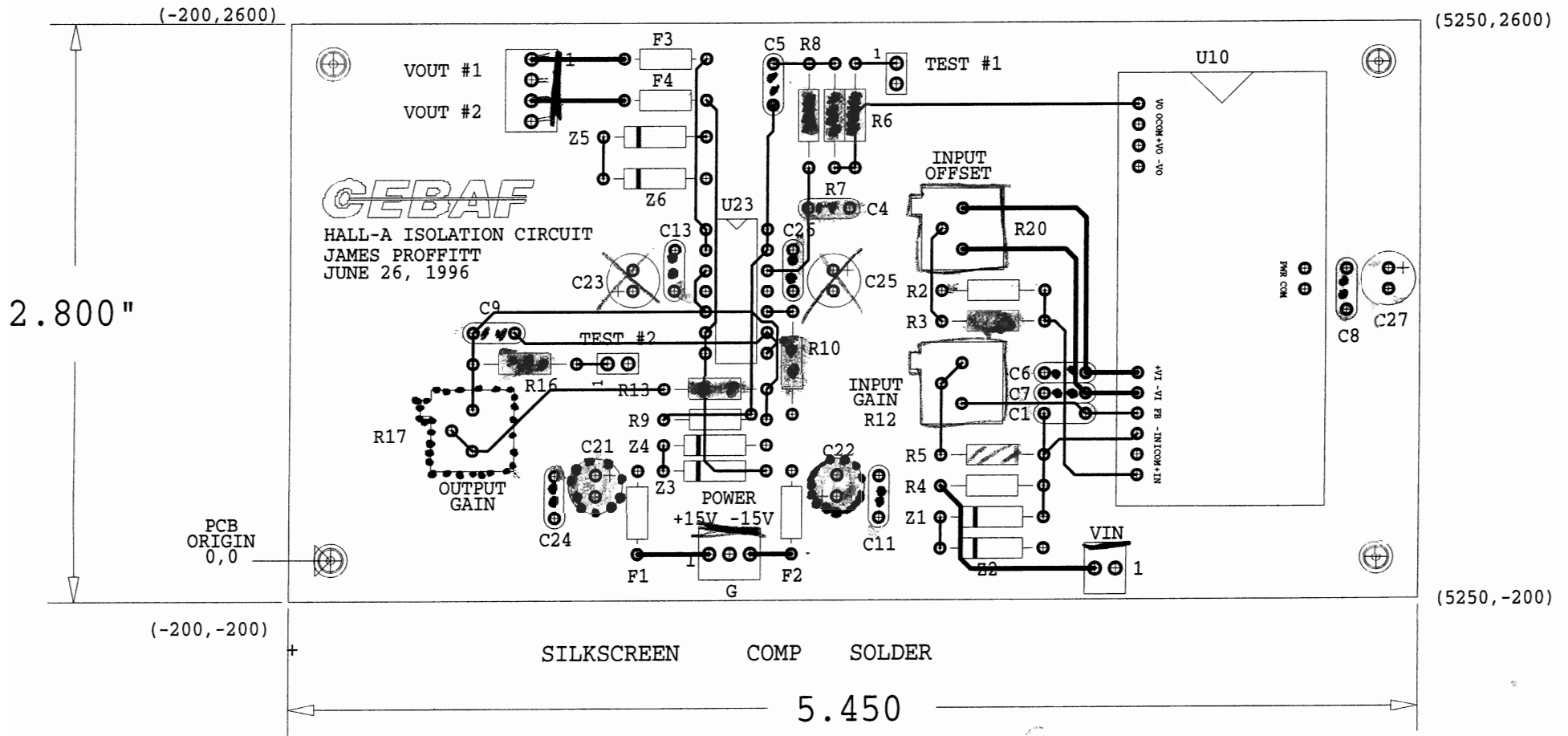
Monday July 29, 1996

Z1-Z6 6 per need 30

3PC  
4PC

P/N 5961 10/60 zener 12v  
 R4 1Meg, 5 5970 1/4w  
 P/N 5905 31180  
 10.K 1% 1/8w  
 R6, R7, R8, R16, R9, 5905 10740

# CEBAF JOB A100R2



1004



# HADRON FLAG heater Pin-outs

Male Plug. MS3126F16-85

FLAG A+ #1 Pr. B - Blk 120VAC  
G - Red Neut.

#2 Pr. D - Red PR-9  
E - Blk

FLAG B- #1 Pr. B - Blk 120VAC  
G - Red NEUT.

#2 Pr. D - Red PR-10  
E - Black

## FEMALE wall mount Receptacle

FLAG A+

V+ B

V- G

I+ D

I- E

TO Newport  
Temp Control

P6 - 1 NO  
ACLO

P9 - 2

P3 - 2

FLAG B-

V+ B

V- G

I+ D

I- E

P6 - 1 NO

ACLO

P9 - 2

P3 - 2



D BLK (6)  
Electron Cryostat

<del>*</del> MASS Flow meter A		Newport
6	RED	6
5	BLK	7 DYNAPWR INTERFACE
11	RED	1
9	BLK	2
7	SALD	Newport 12

<del>*</del> MASS Flow meter B		Newport
6	RED	6
5	BLK	7 DYNAPWR INTERFACE
11	RED	1
9	BLK	2
7	SALD	Newport 12

0-5 VDC INPUT  
0-5 VDC OUTPUT

0 = open  
X = closed

CONFIGURATION

Dip switches

1 2 3 4 5 6 7 8  
X X 0 0 0 X X X

Input SV  
DEC.P XXX.X

Input values

RDS.O

IN 1 000.0  
RD 1 000.0  
IN 2 199.9  
RD 2 250.0

value conversion of 5.0 vdc

RD.CF

R.1 = T  
R.2 = 3  
R.3 = F

OT.S.O

R.D1 = 000.0  
OUT1 = 00.00  
RD2 = 250.0  
OUT2 = 05.00

S1.CF S.1 = A  
S.2 = U

S2.CF S.1 = A  
S.2 = U

LK.CF

SP = E  
RS = E  
L.3 = 0

OT.CF

O.1 = E  
O.2 = V  
O.3 = A

SP1 = 080.0  
SP2 = 000.0

For set point  
USE N.O. contact  
AND common

DIPOLÉ (WANG)

Newport Flow Meters

SAC/AY  
QZ  
Newport Flow Meters

4-20 mA - INPUT  
4-20 mA - OUTPUT

Dip Switches

1 2 3 4 5 6 7 8  
X 0 X X 0 X X 0

INPUT: 0-20  
DEC.P: XXX.X

RANGE  
0-100 SLPM's

INPUT VALUES

RD.S.O

IN 1	199.6	value conversion (VARIES)
RD 1	000.0	
IN 2	998.9	value conversion (VARIES)
RD 2	100.0	

RD.C.F

R.1 = T  
R.2 = 4  
R.3 = F

OT.S.O

RD1 = 000.0  
OUT1 = 04.00  
RD2 = 100.00  
OUT2 = 20.00

S1.C.F

S.1 = A  
S.2 = U

LK.C.F

SP. = E  
RS. = E

S2.C.F

S.2 = A  
S.2 = U

SP1 = 000.0

SP2 = 000.0

OT.C.F

O.1 = E  
O.2 = C  
O.3 = A

# HADRON

## MASS Flow Meter A

5	Black	signal common	Newport Controller 7
6	Red	signal output	6
7	shield		12
9	white	-15 vdc	DYNAPower chassis 2
11	BLACK	+15 vdc	1

## MASS Flow Meter B

5	BLACK	0V	Newport Controller 7
6	Red	5Vdc	6
7	shield		12
9	white	-15Vdc	DYNAPower chassis 2
11	BLACK	+15 vdc	1

# Electron Cryostat

Pg 1

## Level sensors

J1

J1 (EP460)

Lite # 1      A    Red    (2)

                  B    BLACK (3)

                  C    Red    (4)

                  D    BLK    (6)

Lite # 2, 3, 4, 5.

J2

J21 EP461

# 2      { D    Yellow (1)  
          { R    Green (2)  
          { V    Black (3)  
          { L    Red (4)

# 3      { E    Blue (5)  
          { S    Brown (6)  
          { T    Black (7)  
          { L

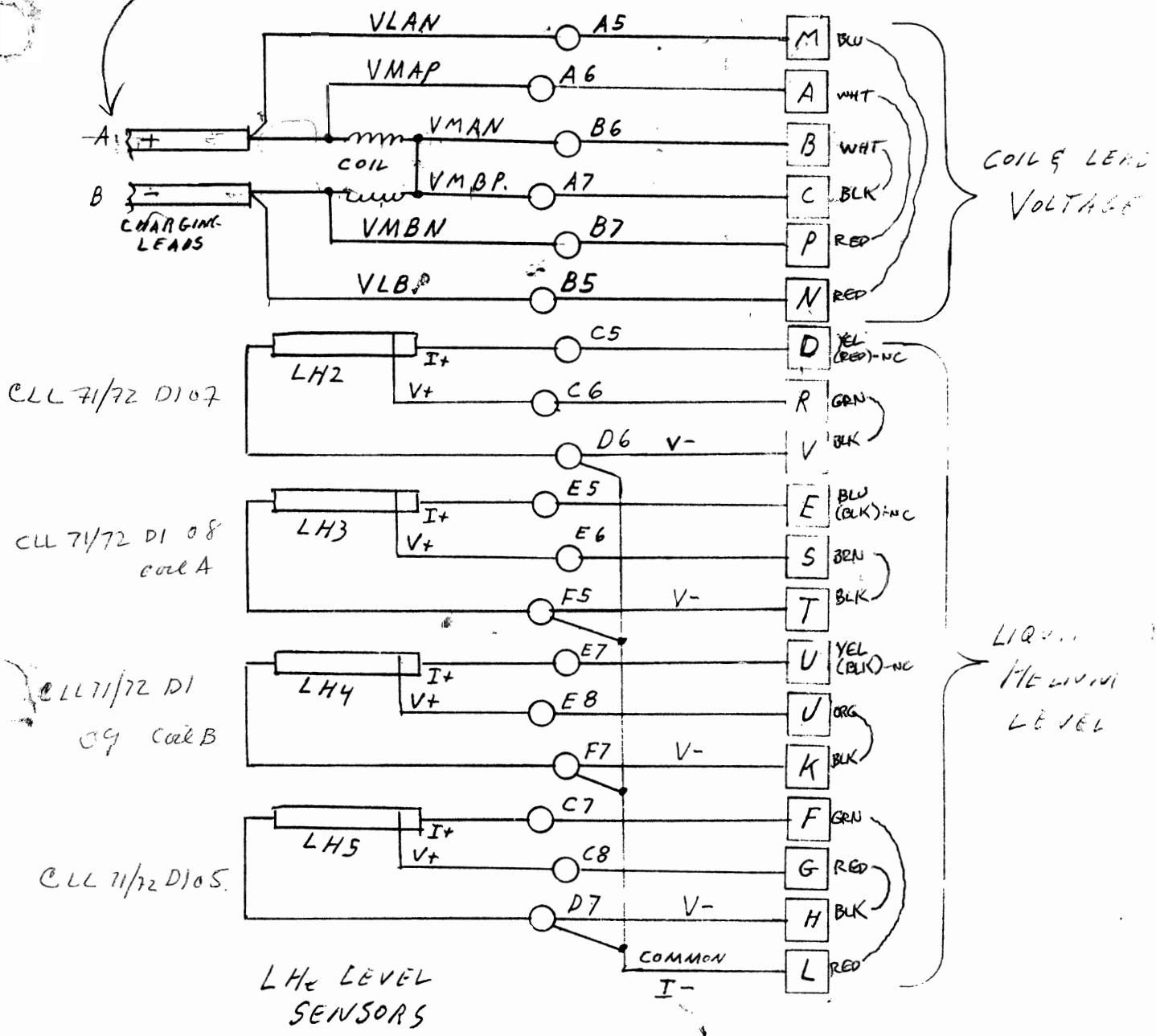
# 4      { U    Yellow (8)  
          { J    Orange (9)  
          { K    Black (10)  
          { L

# 5      { F    Green (11)  
          { G    Red (12)  
          { H    Black (14)  
          { L

# ELECTRON

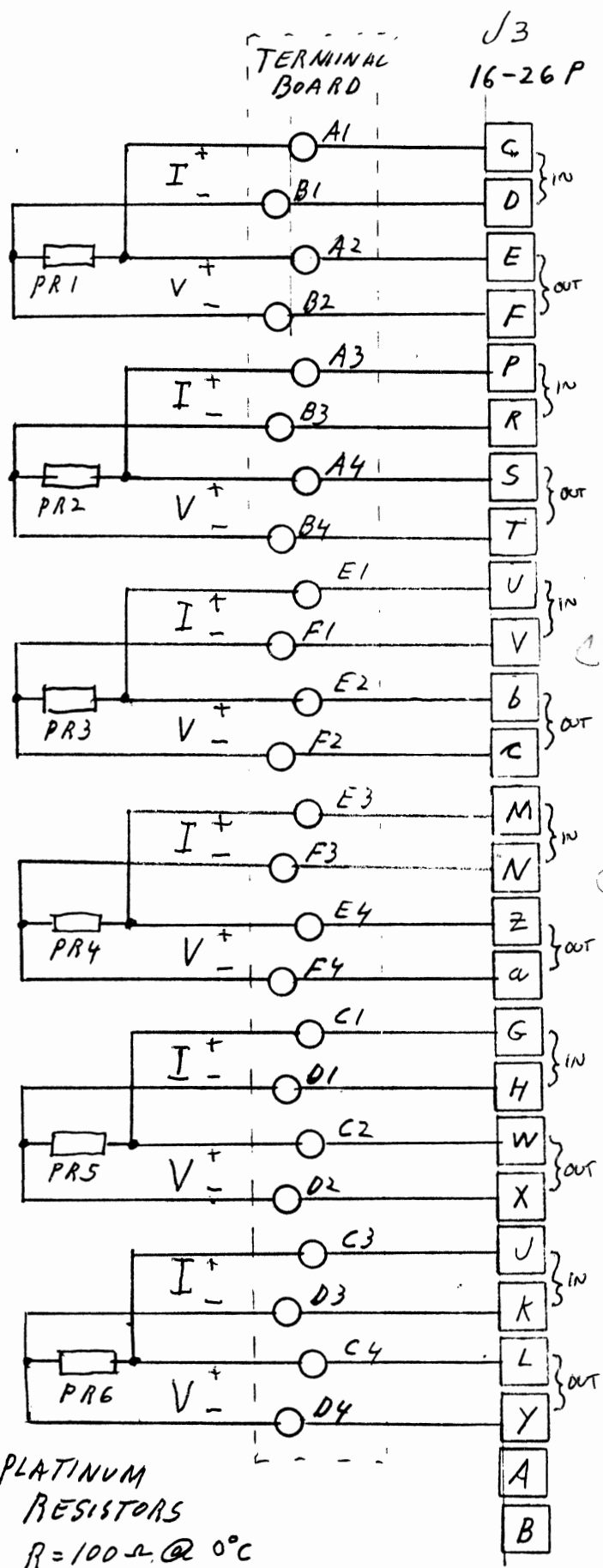
1.1  $\Omega$  / coil

+ LEAD ON LEFT FACING TARGET FROM PLATFORM <sup>J2</sup> 14-19



COIL VOLTAGE  
& L He  
MAGN. <sup>J2</sup>  
CEBAF-EP811 7/25/91





PLATINUM  
RESISTORS  
 $R = 100 \Omega @ 0^\circ C$

COIL TEMP  
SENSORS  
MAGNET J3  
CEBAF-EP 812  
7/29/94



**Cryostat 4K Cooldown**  
**VME Card Channel Assignments**  
 by: James Proffitt 2/6/95

**Table 1: Cryostat Signals**

Device	Signal	Card Type	Card	Channel
N2 Level	Level	ADC	VMIVME-3122	55 * ✓
GHe Valve Pos	Valve Position	ADC	VMIVME-3122	63 ✓
TF Valve Pos	Valve Position	ADC	VMIVME-3122	62 ✓
BF Valve Pos	Valve Position	ADC	VMIVME-3122	61 ✓
N2 Valve Pos	Valve Position	ADC	VMIVME-3122	60 ✓
N2 Pressure	Pressure	ADC	VMIVME-3122	59 ✓
He Pressure	Pressure	ADC	VMIVME-3122	58 ✓
Cold Cathode	Pressure	ADC	VMIVME-3122	57 ✓
Convectron	Pressure	ADC	VMIVME-3122	56
Flow Transducer	+ Lead flow	ADC	VMIVME-3122	54 * ✓
Flow Transducer	- Lead flow	ADC	VMIVME-3122	53 * ✓
Protection Circuit	+ Lead drop	ADC	VMIVME-3122	52 * ✓
Protection Circuit	- Lead drop	ADC	VMIVME-3122	51 * ✓
Protection Circuit	+ Coil drop	ADC	VMIVME-3122	50 * ✓
Protection Circuit	- Coil drop	ADC	VMIVME-3122	49 * ✓
PR1	Temperature	RTD Scanner	V460 #1	4 ✓
PR2	Temperature	RTD Scanner	V460 #1	5 ✓
PR3	Temperature	RTD Scanner	V460 #1	6 ✓
PR4	Temperature	RTD Scanner	V460 #1	7 ✓
PR5	Temperature	RTD Scanner	V460 #1	
PR6	Temperature	RTD Scanner	V460 #1	
PR7 / <del>SD1</del>	Temperature	RTD Scanner	V460 #1	
SD2	Temperature	RTD Scanner	V460 #1	
SD3	Temperature	RTD Scanner	V460 #1	
SD4	Temperature	RTD Scanner	V460 #1	
SD5	Temperature	RTD Scanner	V460 #1	

WEKA

→ 90' CABLE TO CRYOSTAT  
 MODIFY DYNAMOWER F.  
 (EXT. #)

2. INSTALL PROTECTION RESE.  
 BUTTON. DONE.
3. REWIRE DYNAPOWER PS1 +  
 PS2 TO UPS. DONE.
4. GET KLIXONS + MOUNT  
 BLOCKS

-SWAP

WHAT ABOUT DIFF. PRESS. SW. ON COW?

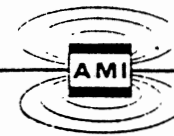
**Table 1: Cryostat Signals**

Device	Signal	Card Type	Card	Channel
Heat Exchanger	He Temperature	RTD Scanner	V460 #1	0/1 ✓
Heat Exchanger	N2 Temperature	RTD Scanner	V460 #1	0/1 ✓
Bayonet Can	He Temperature	RTD Scanner	V460 #1	2/3 * ✓
Bayonet Can	N2 Temperature	RTD Scanner	V460 #1	2/3 * ✓
+Lead	Temperature	RTD Scanner	V460 #2	0 *
-Lead	Temperature	RTD Scanner	V460 #2	1 *
He Level	Probe Control	GPIB	GPIB-1014D	✓
Power Supply	Slow Dump Intck.	Relay Out	VMIVME-2210	8 * ✓
Heat Exchanger	He Valve Motor +	Relay Out	VMIVME-2210	0 * ✓
Heat Exchanger	He Valve Motor -	Relay Out	VMIVME-2210	3 * ✓
Heat Exchanger	N2 Valve Motor +	Relay Out	VMIVME-2210	2 * ✓
Heat Exchanger	N2 Valve Motor -	Relay Out	VMIVME-2210	3 * ✓
+ Lead Valve	Motor +/-	Relay Out (2)	VMIVME-2210	4-5 * ✓
- Lead Valve	Motor +/-	Relay Out (2)	VMIVME-2210	6-7 * ✓
Hx He Valve	Open Lim.	Digital In	PIO-1	17 * ✓
Hx He Valve	Closed Lim.	Digital In	PIO-1	18 * ✓
Hx N2 Valve	Open Lim.	Digital In	PIO-1	19 * ✓
Hx N2 Valve	Closed Lim.	Digital In	PIO-1	20 * ✓
+ Lead Valve	Valve Open Lim.	Digital In	PIO-1	21 * ✓
+ Lead Valve	Valve Closed Lim.	Digital In	PIO-1	22 * ✓
- Lead Valve	Valve Open Lim.	Digital In	PIO-1	23 * ✓
- Lead Valve	Valve Closed Lim.	Digital In	PIO-1	24 * ✓
P/S ON	Interlock status	Digital In (?)	PIO-1	*25 * ✓
GHe Valve Control	Valve Control	DAC	VMIVME-4150	0 ✓
TF Valve Control	Valve Control	DAC	VMIVME-4150	1 ✓
BF Valve Control	Valve Control	DAC	VMIVME-4150	2 ✓
N2 Valve Control	Valve Control	DAC	VMIVME-4150	3 ✓
Heat Exchanger	He Valve Position	LVDT Scanner	V550	0 * ✓
Heat Exchanger	N2 Valve Position	LVDT Scanner	V550	1 * ✓

REPAIRED? ASK ED/HEND

NC 7

WITH JIM  
NEED ALL DYNAPUR  
STATUS OUT  
+ CRYO READY



## INSTALLATION, OPERATION AND MAINTENANCE INSTRUCTIONS FOR THE AMI MODEL 137 LIQUID HELIUM LEVEL INSTRUMENT

### I. INTRODUCTION

The American Magnetics, Inc. (AMI) Model 137 Liquid Helium Level Instrument is an advanced, microprocessor-based, liquid helium level instrument utilizing AMI's patented sample-and-hold principle with automatic helium sensor vacuum burnout protection. The Model 137 is designed for unattended operation in systems where it is important to monitor liquid helium levels and minimize the liquid helium losses.

The Model 137 is designed to be used in conjunction with an AMI liquid helium level sensors. The liquid helium level sensor consists of a small diameter NbTi filament in a hollow tube. A constant current is passed through this filament causing the portion of the filament in helium gas to become resistive while the portion in the liquid helium remains superconducting. The resulting voltage across the resistive portion of the filament is read by the instrument, converted to a liquid level and displayed on the front panel LED display.

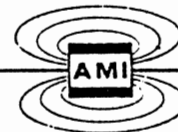
In order to minimize liquid helium loss, the Model 137 automatically energizes the liquid helium level sensor at predetermined time intervals and monitors the normal (resistive) zone as it progresses from the top of the sensor toward the surface of the liquid helium. As soon as the normal zone reaches the liquid surface the level reading is saved and the sensor current is turned off until the next sample interval occurs. A SENSOR CURRENT LED is illuminated during each sample. Sample intervals are user programmable from the front panel and can be set between "0.0" (no delay between samples) to "600.0" minutes or hours. A manual update/contin./sample switch provided on the front panel can be positioned for continuous readings during a helium transfer period or just a quick reading update.

The Model 137 provides automatic helium sensor vacuum burnout protection. A sensor which is energized in a vacuum environment will self-heat to the point of burnout. AMI's innovative microprocessor-based circuitry detects incipient sensor burnout and de-energizes the sensor before damage can occur. A 5% increase in sensor resistance will trigger this protection, causing the current to be switched off for 6 seconds before normal operation continues.

Due to safety concerns, the high voltage power supply used for the sensor is a floating supply. This minimizes the possibility of personnel injury in the inadvertent event of someone who is grounded coming in contact with the sensor electrical wires.

The Model 137 has the capacity of monitoring up to eight liquid helium sensors. Selection between sensors is performed from the front panel of the instrument or remotely with a

Rev. 1, May 1992



## INSTALLATION, OPERATION AND MAINTENANCE INSTRUCTIONS

### FOR THE AMI LIQUID HELIUM

### LEVEL SENSOR

#### I. INTRODUCTION

The AMI liquid helium level sensor uses a small Niobium-Titanium (NbTi) wire as the detector element. A heater creates and helps maintain a normal zone in that portion of the wire above the liquid helium level while that portion of the wire below the liquid helium level remains superconducting. The output voltage of the sensor varies linearly with a change in liquid level.

The AMI liquid helium level sensor is designed to operate with an AMI liquid helium level meter. Each meter is calibrated for a specific sensor length and if sensors of different lengths are interchanged the level meter will require recalibration. Operation of the sensor with other level meters or operation of different length sensor with a meter calibrated for a specific length may void the sensor warranty.

#### II. SPECIFICATIONS

Diameter	_____	1/4"
Active lengths	_____	1 to 80 inches
Overall length	_____	usually 1 inch longer than active length (1/2 inch at top and bottom)
Sensor current	_____	70 milliamperes (nominal)
Sensor voltage	_____	0-60 V dc depending on sensor length.
Nominal sensor resistance	_____	4.5 ohms/cm (11.6 ohms/in) at 10K 5.4 ohms/cm (13.7 ohms/in) at 300K
Maximum magnetic field	_____	10 Tesla

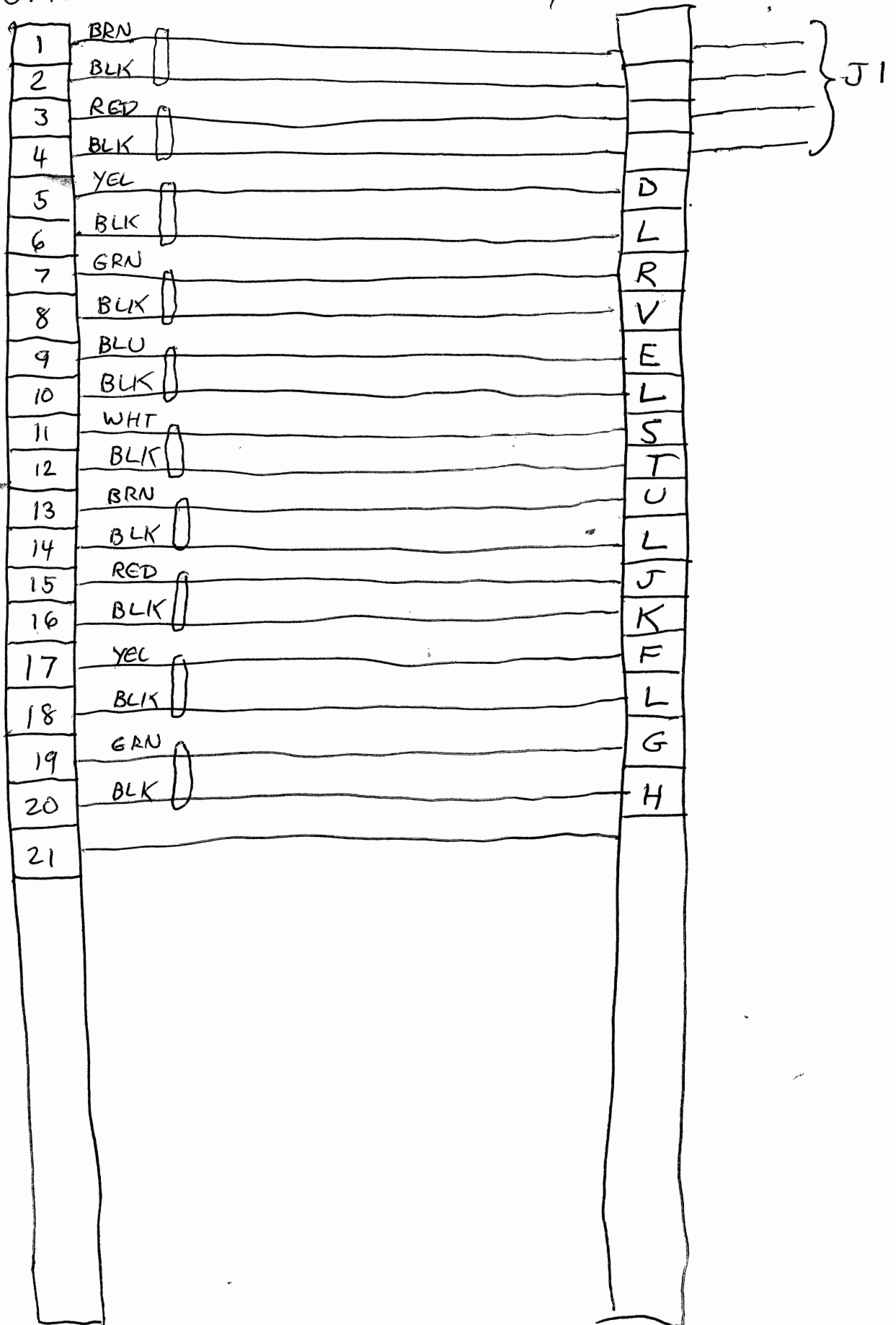
#### III. INSTALLATION

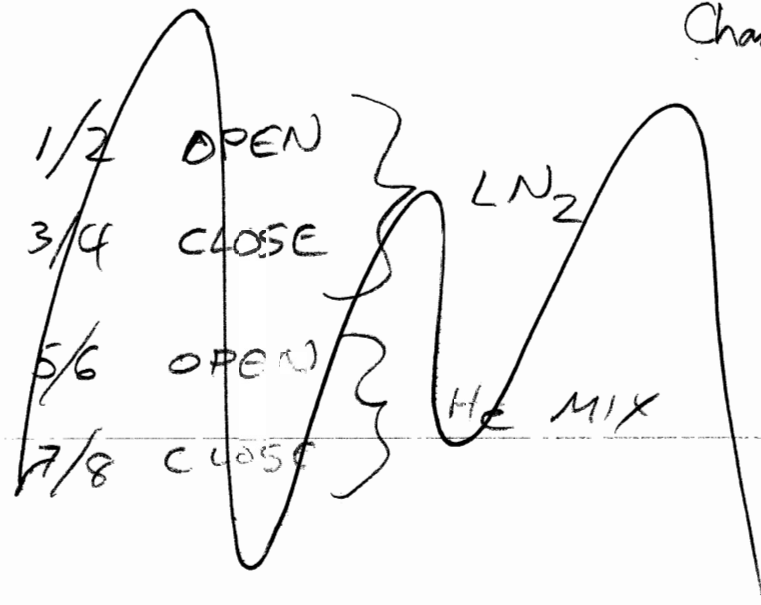
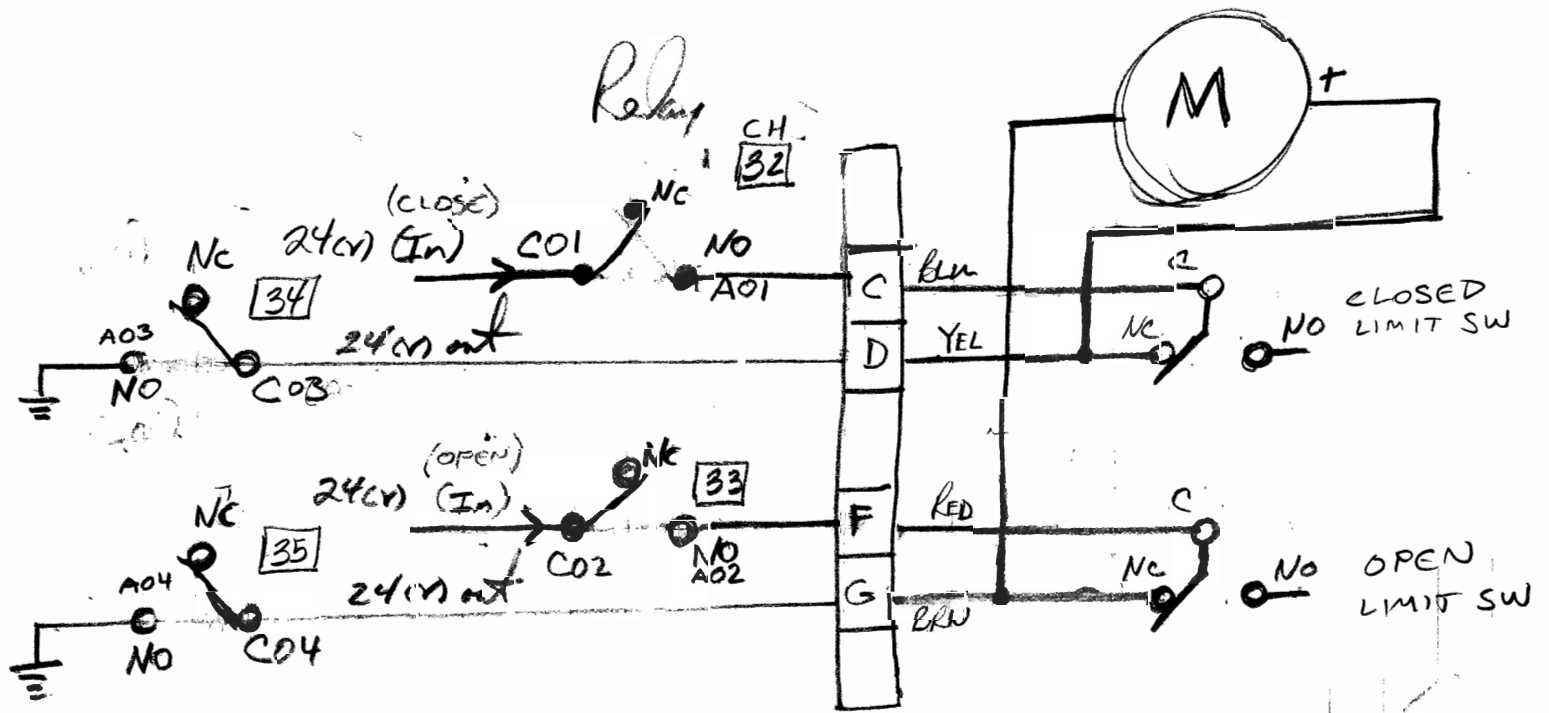
1. Carefully remove the sensor from the shipping tube and remove all packaging material.
2. The sensor must be mounted with the electrical leads coming out of the top.

# AMI 137 TO FIELD CABLE TERMINAL STRIP

37 PIN MALE "D" CONN

J1/J2 TERMINAL STRIP





Channels 1 32 } 24V AC

2 33 }

3 34 } 24V AC RET

4 35 }

1 } CLOSE

4 }

2 }

3 }



# MHR SERIES—MINIATURE

- FOR APPLICATIONS WHERE INSTALLATION SPACE OR WEIGHT IS LIMITED
- LIGHTWEIGHT CORE

The MHR Series is suitable for use where installation space or LVDT weight is limited. It occupies only 25 percent of the volume of standard-size LVDT's. The

MHR's lightweight core is ideal for applications where excessive core weight could influence the motion of sensitive mechanisms. The lightweight core also helps minimize stresses and preserves the structural integrity of the core actuation assembly. High sensitivity results from close electrical coupling between coil and core. A magnetic stainless steel housing provides electromagnetic and electrostatic shielding.

## GENERAL SPECIFICATIONS

Input Voltage . . . . . 3 V rms (nominal)  
 Frequency Range . . . 400 Hz to 20 kHz  
 Temperature Range . . -65°F to +300°F  
 (-55°C to +150°C)  
 Null Voltage . . . . . Less than 0.5% full scale output

Shock Survival . . . . . 1000 g for 11 milliseconds  
 Vibration Tolerance . . 20 g up to 2 kHz  
 Coil Form Material . . . High density, glass-filled polymer  
 Housing Material . . . . . AISI 400 series stainless steel  
 Lead Wires . . . . . 32 AWG, stranded copper, Teflon-insulated, 12 inches (300 mm) long (nominal)

## PERFORMANCE SPECIFICATIONS AND DIMENSIONS (2.5 kHz)

LVDT MODEL NUMBER	NOMINAL LINEAR RANGE Inches	LINEARITY ± PERCENT FULL RANGE				SENSITIVITY mV Out/ Volt In Per 101 In.	IMPEDANCE Ohms		PHASE SHIFT Degrees	WEIGHT Grams		DIMENSIONS A (Body) B (Core) Inches	
		50	100	125	150		PA.	Sec.		Body	Core	Inches	Inches
005 MHR	±0.005	0.20	0.25	0.30	0.40	2.7	90	260	+71	2	0.1	0.38	0.18
010 MHR	±0.010	0.10	0.25	0.35	0.35	3.4	80	110	+58	3	0.2	0.54	0.23
025 MHR	±0.025	0.15	0.25	0.25	0.30	4.5	115	280	+60	5	0.4	0.66	0.40
050 MHR	±0.050	0.15	0.25	0.35	0.50	2.7	140	90	+34	6	0.4	0.80	0.50
100 MHR	±0.100	0.15	0.25	0.25	0.30	2.4	150	110	+30	6	0.5	1.00	0.62
250 MHR	±0.250	0.15	0.25	0.35	0.50	2.0	180	280	+28	9	0.9	1.85	1.12
500 MHR	±0.500	0.15	0.25	0.30	0.75	1.6	135	435	+17	17	1.6	3.30	2.00
1000 MHR	±1.000	0.20	0.25	0.50	—	0.8	100	385	+5	26	2.5	5.60	3.00

## (10 kHz)

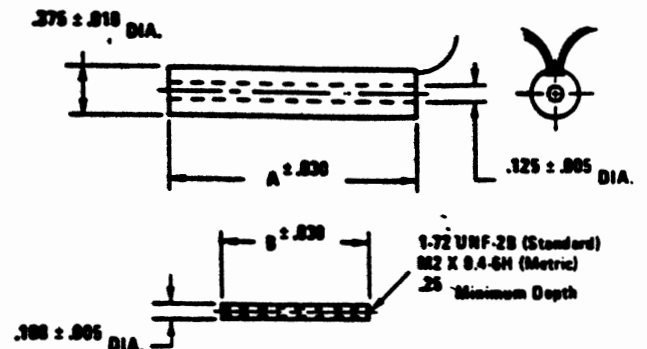
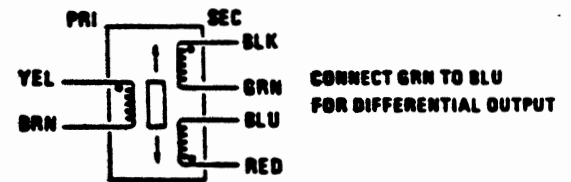
005 MHR	±0.005	0.20	0.25	0.30	0.40	8.4	75	315	+40	2	0.1	0.38	0.18
010 MHR	±0.010	0.10	0.25	0.35	0.35	6.1	165	300	+16	3	0.2	0.54	0.23
025 MHR	±0.025	0.15	0.25	0.25	0.30	7.8	220	500	+22	5	0.4	0.66	0.40
050 MHR	±0.050	0.15	0.25	0.35	0.50	3.3	450	150	+9	6	0.4	0.80	0.50
100 MHR	±0.100	0.15	0.25	0.25	0.30	2.5	450	190	+8	6	0.5	1.00	0.62
250 MHR	±0.250	0.15	0.25	0.35	0.50	2.1	350	430	+8	9	0.9	1.85	1.12
500 MHR	±0.500	0.15	0.25	0.30	0.75	1.8	235	750	+4	17	1.6	3.30	2.00
1000 MHR	±1.000	0.20	0.25	0.50	—	0.8	170	450	-1	26	2.5	5.60	3.00

## ORDERING INFORMATION

(Fold out page 32 for instructions on how to use this chart.)

OPTION NO.	002	003	006	010	020	040	000
MODEL NO.							
005 MHR	A	A	N	X	X	F	X
010 MHR	A	A	N	X	X	F	X
025 MHR	A	A	N	X	X	F	X
050 MHR	A	A	N	X	X	F	X
100 MHR	A	A	N	X	X	F	X
250 MHR	A	A	N	X	X	F	X
500 MHR	A	A	N	X	X	F	X
1000 MHR	A	A	N	X	X	F	X

Note 1: See outline drawing for metric thread size  
 Note 2: See frequency option note on page 32

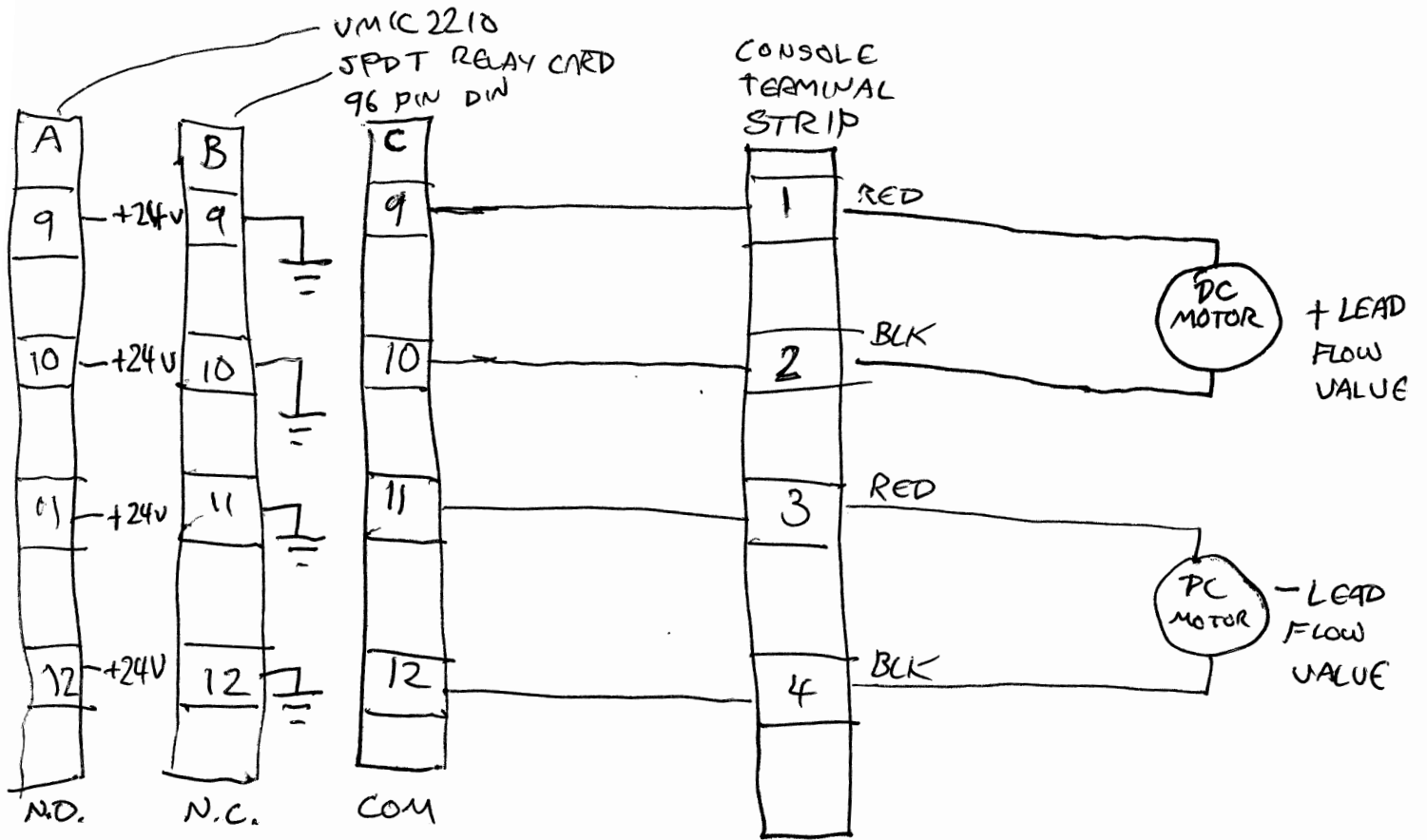


SEE SCHAEVITZ SERIES 70 BULLETINS FOR COMPATIBLE SIGNAL-CONDITIONING AND READOUT EQUIPMENT

\* FOR OUR STANDARD 9/16" STROKE VALVE



# LEAD FLOW VALUE CABLES



FLOW METER CABLES (100' 2 PR)

8' PWR

+ FLOW METER:

15 PIN FEMALE D

PIN #	SIGNAL	WIRE COLOR
5	COM	BLK
6	0-5V OUT	RED
9	-15VDC	BLK
11	+15VDC	RED

CONSOLE:

TERMINAL STRIP:

TERMINAL #

5	A 1 BLK	VM1VME-3122, P4, PIN C-10
5	Red 2 <del>BLK</del>	+15VDC PWR SUP, COMMON
6		VM1VME-3122, P4, PIN A-10
9	✓	-15VDC (PWR SUP)
11	✓	+15VDC (PWR SUP)

END DEVICE:

VME CRATE

- FLOW METER

5	COM	BLK
6	0-5V OUT	RED
9	-15V	BLK
11	+15V	RED

5	B BLK	VM1VME 3122, P4, PIN C-11
	RED	+15V COMMON
6		VM1VME 3122, P4, PIN A-11
9		-15V
11		+15V

\* Inps P.S.

flow meters

18"

GO over cap tank  
w/ meter wiring  
new order

# Flow Meter

In

24(v) PS 1 GRD  
2 24(v)

5 GRD → out to cap in case

6 signal

7 signal

8

9 -15(v)

11 +15(v)

Out

0.5(v)

In

24(v) PS 24(v) 1

GRD 2 out

±15(v) PS GRD

GRD 5 C10+41 A to Power

6

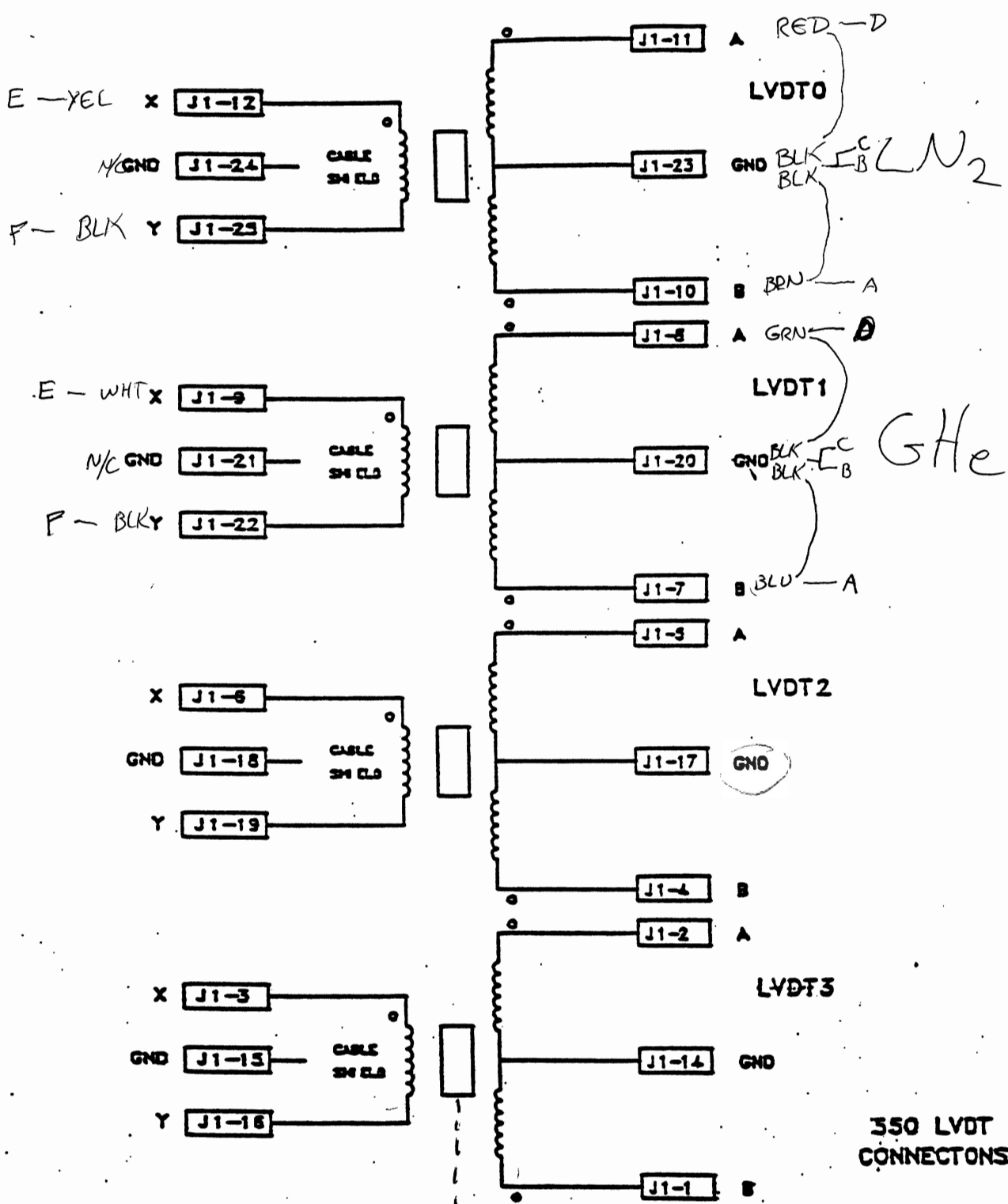
7

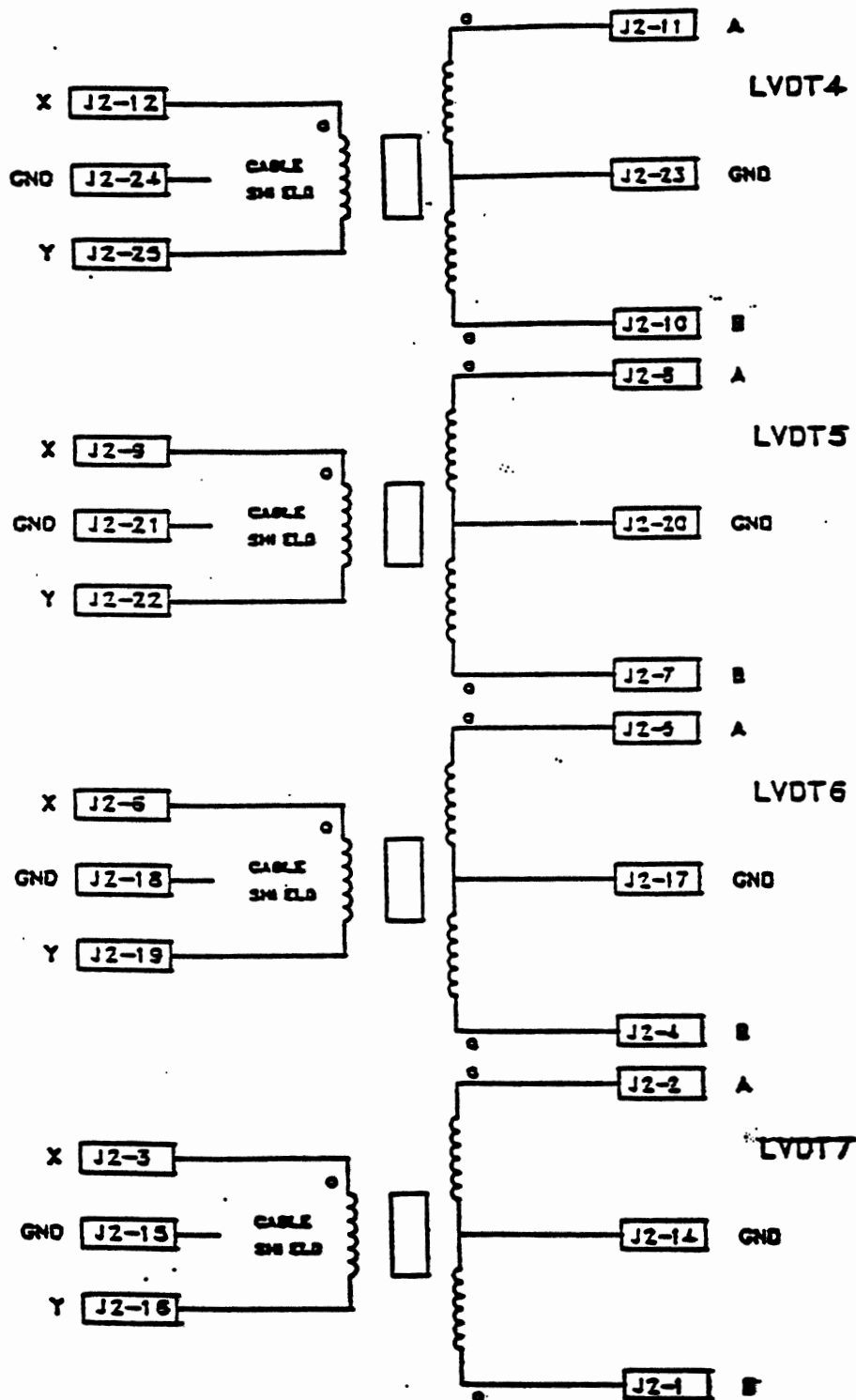
±15(v) PS -15(v) 9

" +15(v) 11

Out

Highland V550  
 LVDT Card  
 25-Pin D-Sub





150 LVDT  
CONNECTIONS

### 5.4 CONNECTOR CONFIGURATION

The VMIVME-2210 uses two 96-pin DIN connectors on the front panel. These connectors can be used with a discrete wire connector housing and shell from HARTING ELEKTRONIK INC. or a mass-terminated cable and connector from ERNI components. The specification sheet for this board contains detailed ordering information about these connectors and cables. These cables and connectors will bring out all of the contacts from the board. The contacts are configured as 1 Form C (SPDT); however, the connector layout shown in Figures 5.4-1 and 5.4-2 permits a 64-conductor cable and full C DIN connector to bring out the contacts as a 1 Form A (SPST N.O.).

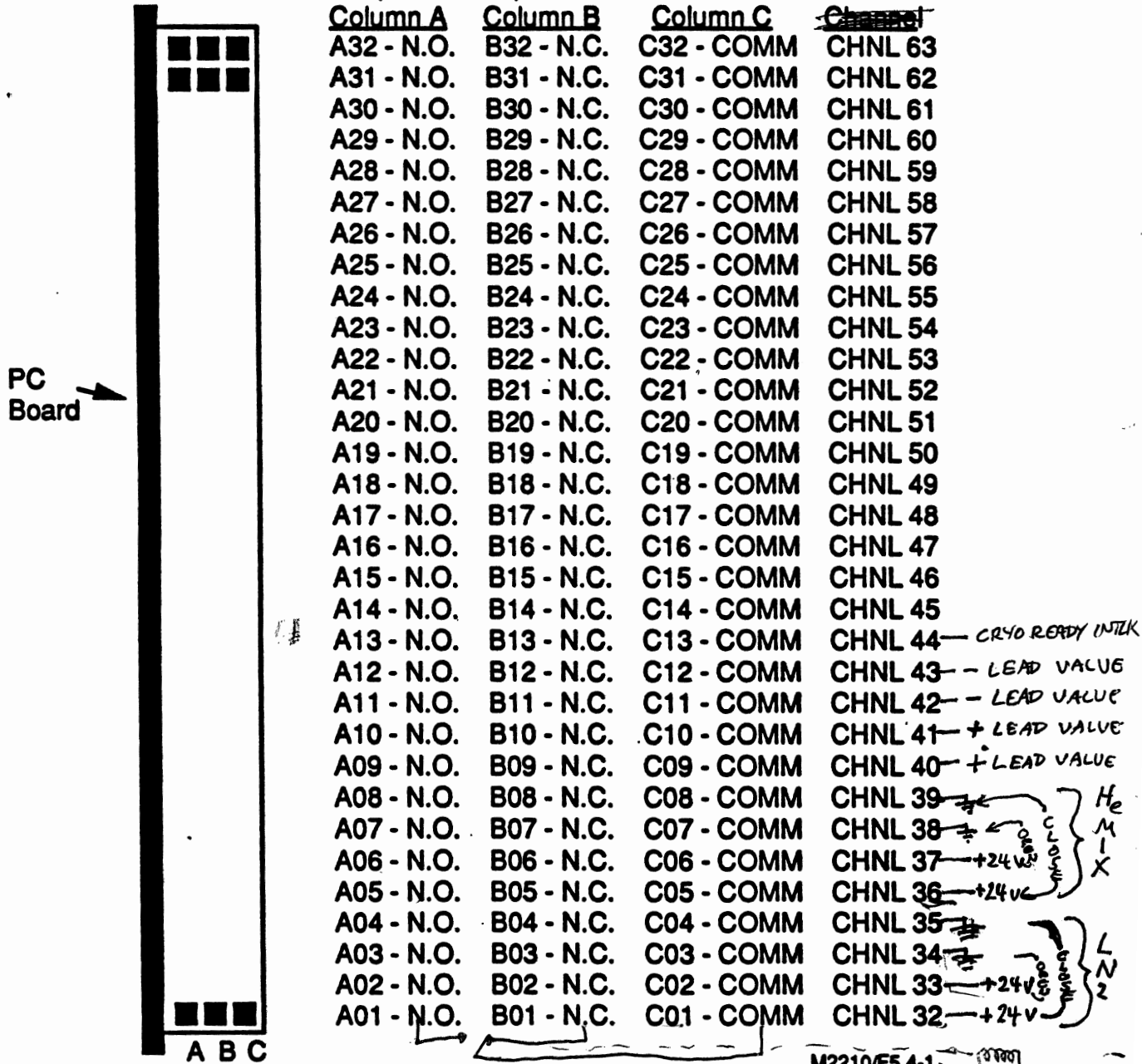


Figure 5.4-1. P3's Connector Layout and Pin Assignments

Figure 13. Front Panel Connectors P3 and P4

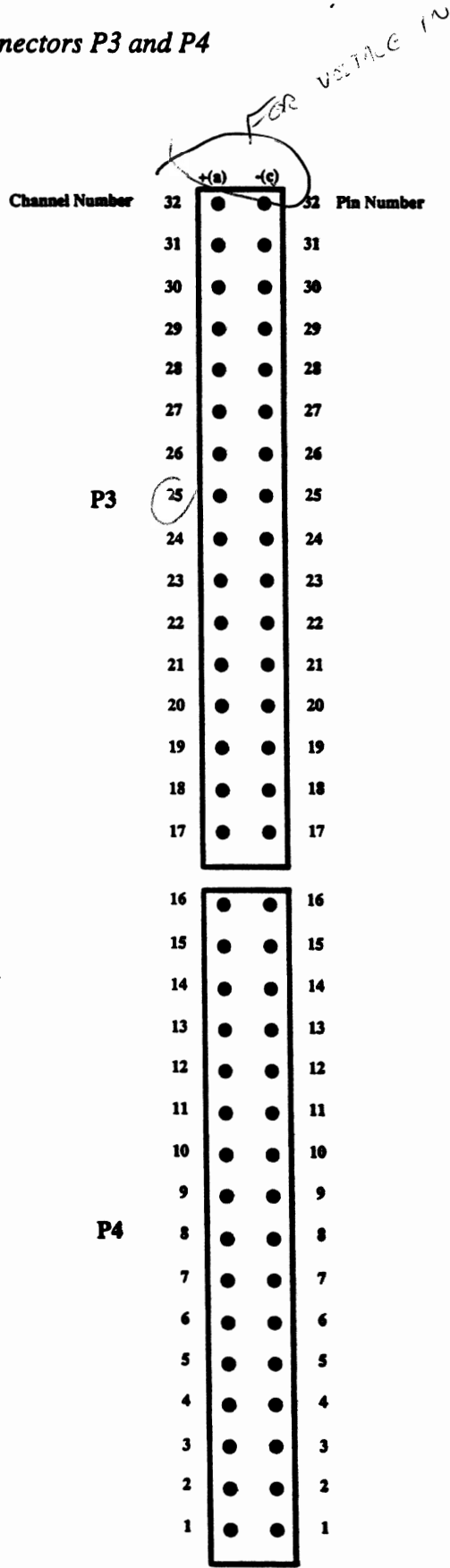


Table 5.5.3-2. P3 Connector Pinout

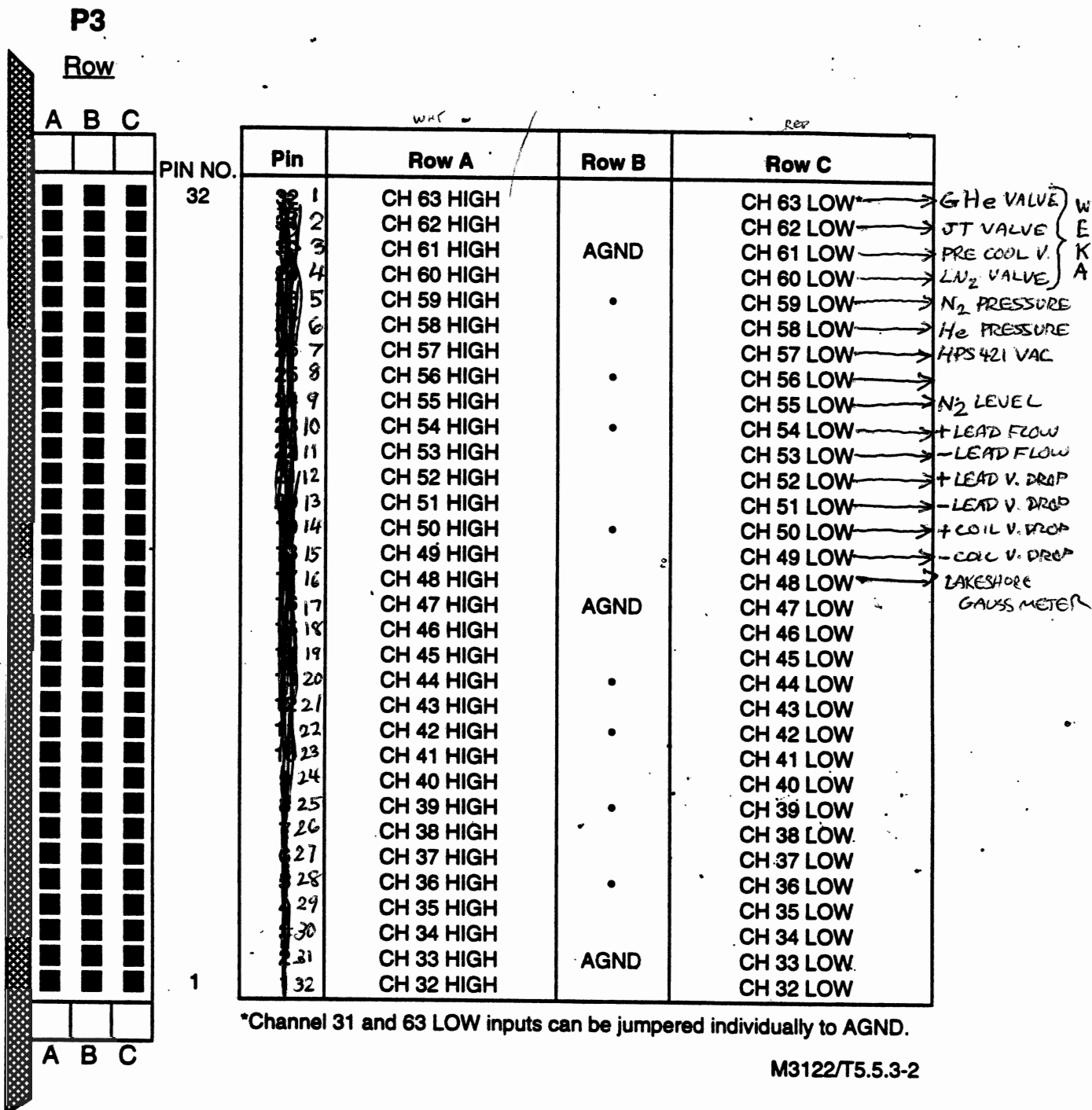




Table 5.5.3-3. P4 Connector Pinout

**P4**

Row

A B C

PIN NO.	Pin	Row A	Row B	Row C
32	32	CH 31 HIGH		CH 31 LOW*
	31	CH 30 HIGH		CH 30 LOW
	30	CH 29 HIGH	AGND	CH 29 LOW
	29	CH 28 HIGH		CH 28 LOW
	28	CH 27 HIGH	•	CH 27 LOW
	27	CH 26 HIGH		CH 26 LOW
	26	CH 25 HIGH		CH 25 LOW
	25	CH 24 HIGH	•	CH 24 LOW
	24	CH 23 HIGH		CH 23 LOW
	23	CH 22 HIGH		CH 22 LOW
	22	CH 21 HIGH	•	CH 21 LOW
	21	CH 20 HIGH		CH 20 LOW
	20	CH 19 HIGH		CH 19 LOW
	19	CH 18 HIGH	•	CH 18 LOW
	18	CH 17 HIGH		CH 17 LOW
	17	CH 16 HIGH		CH 16 LOW
	16	CH 15 HIGH	AGND	CH 15 LOW
	15	CH 14 HIGH		CH 14 LOW
	14	CH 13 HIGH	•	CH 13 LOW
	13	CH 12 HIGH		CH 12 LOW
	12	CH 11 HIGH		CH 11 LOW
	11	CH 10 HIGH	•	CH 10 LOW
	10	CH 09 HIGH		CH 09 LOW
	9	CH 08 HIGH		CH 08 LOW
	8	CH 07 HIGH	•	CH 07 LOW
	7	CH 06 HIGH		CH 06 LOW
	6	CH 05 HIGH		CH 05 LOW
	5	CH 04 HIGH	•	CH 04 LOW
	4	CH 03 HIGH		CH 03 LOW
	3	CH 02 HIGH		CH 02 LOW
	2	CH 01 HIGH	AGND	CH 01 LOW
1	1	CH 00 HIGH		CH 00 LOW

A B C

\*Channel 31 and 63 LOW inputs can be jumpered individually to AGND.

M3122/T5.5.3-3

IN	FUNCTION	PIN	FUNCTION	COMMENT
==	=====	===	=====	=====
-2	W0	J2-2	W8	SENSOR POSITIVE DRIVE
-3	X0	J2-3	X8	SENSOR POSITIVE SENSE
-21	Y0	J2-21	Y8	SENSOR NEGATIVE SENSE
-22	Z0	J2-22	Z8	SENSOR DRIVE RETURN
-4	W1	J2-4	W9	
-5	X1	J2-5	X9	
-23	Y1	J2-23	Y9	
-24	Z1	J2-24	Z9	
-6	W2	J2-6	W10	
-7	X2	J2-7	X10	
-25	Y2	J2-25	Y10	
-26	Z2	J2-26	Z10	
-8	W3	J2-8	W11	
-9	X3	J2-9	X11	
-27	Y3	J2-27	Y11	
-28	Z3	J2-28	Z11	
10	W4	J2-10	W12	
-11	X4	J2-11	X12	
-29	Y4	J2-29	Y12	
-30	Z4	J2-30	Z12	
-12	W5	J2-12	W13	SENSOR POSITIVE DRIVE
-13	X5	J2-13	X13	SENSOR POSITIVE SENSE
-31	Y5	J2-31	Y13	SENSOR NEGATIVE SENSE
-32	Z5	J2-32	Z13	SENSOR DRIVE RETURN
-14	W6	J2-14	W14	
-15	X6	J2-15	X14	
-33	Y6	J2-33	Y14	
-34	Z6	J2-34	Z14	
-16	W7	J2-16	W15	
-17	X7	J2-17	X15	
-35	Y7	J2-35	Y15	
-36	Z7	J2-36	Z15	
-1	COMMON	J2-1	COMMON	VME CIRCUIT COMMON
-18	COMMON	J2-18	COMMON	
-20	COMMON	J2-20	COMMON	
-37	COMMON	J2-37	COMMON	
	+12 VOLTS	J2-19	+12 VOLTS	FUSED VME +12 SUPPLY

CAN above Heat EXchange Non Zoro binhi

A } V+ Diode A  
B } V- LAkeshore #470 ~~WIA~~ Supply  
C } I+  
D } I-

CONN1  
on can

E } V+  
F } V- Diode B  
G } I+ LAkeshore #470 GHE RETURN  
H } I-

check & report location of diodes

wires complete



D1 - <sup>I</sup> from S1 Boy

D1 =  $\begin{matrix} I+ \\ I- \end{matrix}$  Net  
Black

D2  $\begin{matrix} I+ \\ I- \end{matrix}$  white/Net  
Black

D3  $\begin{matrix} I+ \\ I- \end{matrix}$  orange  
white/Black

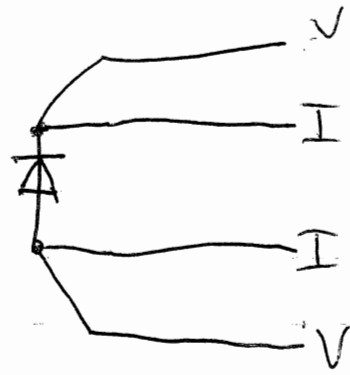
D4  $\begin{matrix} I+ \\ I- \end{matrix}$  white, orange  
white black

D5  $\begin{matrix} I+ \\ I- \end{matrix}$  Purple  
white/gray

D6  $\begin{matrix} I+ \\ I- \end{matrix}$  white/purple  
white/gray

CD 3-~~A~~

CD ~~4~~-~~A~~



CD 3  
Left side

$A = V+$   
 $B = V-$   
 $C = I+$   
 $D = I-$

CD 4  
Right side

$E = V+$   
 $F = V-$   
 $G = I+$   
 $H = I-$



CD 5  
Left side

$A \text{ B} = V+$   
 $B = V-$   
 $C = I+$   
 $D = I-$

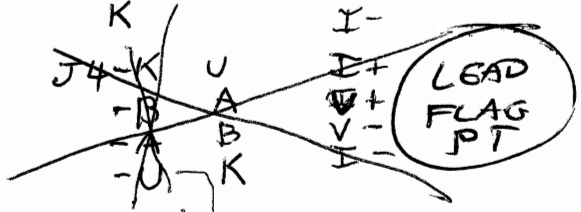
CD 6  
Right side

$E = V+$   
 $F = V-$   
 $G = I+$   
 $H = I-$



J2

IN ==	FUNCTION =====	PIN ===	FUNCTION =====	CRYOSTAT CONNECTOR/PIN	SIGNAL NAME	SIGNAL VOLUME	SENSOR UNIT
1-2	W0	J2-2	W8	J3-G	I+		PR5
1-3	X0	J2-3	X8	W	V+		
1-21	Y0	J2-21	Y8	X	V-		
1-22	Z0	J2-22	Z8	H	I-		
1-4	W1	J2-4	W9	J3-J	I+		PR6
1-5	X1	J2-5	X9	L	V+		
1-23	Y1	J2-23	Y9	Y	V-		
1-24	Z1	J2-24	Z9	K	I-		
1-6	W2	J2-6	W10	J4-K	I+		<del>PR7</del>
1-7	X2	J2-7	X10	U	V+		<del>EN2 DIODE</del>
1-25	Y2	J2-25	Y10	A	V-		<del>TOP</del>
1-26	Z2	J2-26	Z10	B	I-		<del>BOTTOM</del>
1-8	W3	J2-8	W11	J4-U	I+		<del>SD8 (wings)</del>
1-9	X3	J2-9	X11	T	V+		<del>SD8</del>
1-27	Y3	J2-27	Y11	V	V-		PR7
1-28	Z3	J2-28	Z11	L	I-		
1-10	W4	J2-10	W12	J7-C	I+		SD1
1-11	X4	J2-11	X12	A	V+		SD2
1-29	Y4	J2-29	Y12	B	V-		
1-30	Z4	J2-30	Z12	D	I-		
1-12	W5	J2-12	W13	J7-G	I+		SD6
1-13	X5	J2-13	X13	F	V+		SD3
1-31	Y5	J2-31	Y13	M	V-		
1-32	Z5	J2-32	Z13	H	I-		
1-14	W6	J2-14	W14	J8-C	I+		SDI
1-15	X6	J2-15	X14	A	V+		SD4
1-33	Y6	J2-33	Y14	B	V-		
1-34	Z6	J2-34	Z14	D	I-		
1-16	W7	J2-16	W15	J8-G	I+		SDJ
1-17	X7	J2-17	X15	E	V+		SD5
1-35	Y7	J2-35	Y15	F	V-		
1-36	Z7	J2-36	Z15	H	I-		
1-1	COMMON	J2-1	COMMON	VME CIRCUIT COMMON			
1-18	COMMON	J2-18	COMMON				
1-20	COMMON	J2-20	COMMON				
1-37	COMMON	J2-37	COMMON				
1-19	+12 VOLTS	J2-19	+12 VOLTS	FUSED VME +12 SUPPLY			



CRYOSTAT ADD-ON DIODES

Table 5.6-1. P3 Pin Assignments

BLK

RED

Pin	Data Bit	Pin	Data Bit
19	OUT 0	37	COMM 0
18	VEXT 0	36	N/C
17	N/C	35	N/C
16	OUT 1	34	COMM 1
15	VEXT 1	33	N/C
14	N/C	32	N/C
13	OUT 2	31	COMM 2
12	VEXT 2	30	N/C
11	N/C	29	N/C
10	OUT 3	28	COMM 3
9	VEXT 3	27	N/C
8	N/C	26	N/C
7	OUT 4	25	COMM 4
6	VEXT 4	24	N/C
5	N/C	23	N/C
4	OUT 5	22	COMM 5
3	VEXT 5	21	N/C
2	N/C	20	N/C
1	N/C		

GHe VALVE (20-4)

ST VALVE

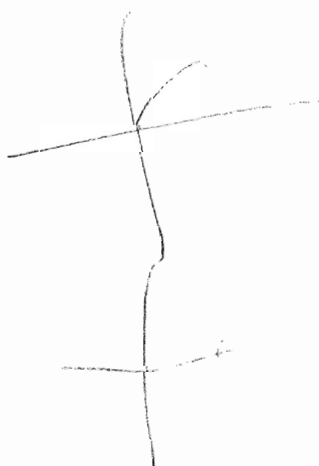
PRE-COOL VALVE

LN<sub>2</sub> VALVE

30x60 =  
1800  
0.500  
900 Mb.

Table 5.6-2. P4 Pin Assignments

Pin	Data Bit	Pin	Data Bit
19	OUT 6	37	COMM 6
18	VEXT 6	36	N/C
17	N/C	35	N/C
16	OUT 7	34	COMM 7
15	VEXT 7	33	N/C
14	N/C	32	N/C
13	OUT 8	31	COMM 8
12	VEXT 8	30	N/C
11	N/C	29	N/C
10	OUT 9	28	COMM 9
9	VEXT 9	27	N/C
8	N/C	26	N/C
7	OUT 10	25	COMM 10
6	VEXT 10	24	N/C
5	N/C	23	N/C
4	OUT 11	22	COMM 11
3	VEXT 11	21	N/C
2	N/C	20	N/C
1	N/C		



2.4  
1.4  
4.2  
1.8  
5.6



Highland Card for  
Diode & 11AT100V Resistor readouts

PIN ===	FUNCTION =====	PIN ===	FUNCTION =====	COMMENT -----
J1-2	W0	J2-2	W8	SENSOR POSITIVE DRIVE
J1-3	X0	J2-3	X8	SENSOR POSITIVE SENSE
J1-21	Y0	J2-21	Y8	SENSOR NEGATIVE SENSE
J1-22	Z0	J2-22	Z8	SENSOR DRIVE RETURN
J1-4	W1	J2-4	W9	
J1-5	X1	J2-5	X9	
J1-23	Y1	J2-23	Y9	
J1-24	Z1	J2-24	Z9	
J1-6	W2	J2-6	W10	
J1-7	X2	J2-7	X10	
J1-25	Y2	J2-25	Y10	
J1-26	Z2	J2-26	Z10	
J1-8	W3	J2-8	W11	
J1-9	X3	J2-9	X11	
J1-27	Y3	J2-27	Y11	
J1-28	Z3	J2-28	Z11	
J1-10	W4	J2-10	W12	
J1-11	X4	J2-11	X12	
J1-29	Y4	J2-29	Y12	
J1-30	Z4	J2-30	Z12	
J1-12	W5	J2-12	W13	SENSOR POSITIVE DRIVE
J1-13	X5	J2-13	X13	SENSOR POSITIVE SENSE
J1-31	Y5	J2-31	Y13	SENSOR NEGATIVE SENSE
J1-32	Z5	J2-32	Z13	SENSOR DRIVE RETURN
J1-14	W6	J2-14	W14	
J1-15	X6	J2-15	X14	
J1-33	Y6	J2-33	Y14	
J1-34	Z6	J2-34	Z14	
J1-16	W7	J2-16	W15	
J1-17	X7	J2-17	X15	
J1-35	Y7	J2-35	Y15	
J1-36	Z7	J2-36	Z15	
J1-1	COMMON	J2-1	COMMON	VME CIRCUIT COMMON
J1-18	COMMON	J2-18	COMMON	
J1-20	COMMON	J2-20	COMMON	
J1-37	COMMON	J2-37	COMMON	
J1-19	+12 VOLTS	J2-19	+12 VOLTS	FUSED VME +12 SUPPLY

## 5.6 I/O CABLE AND FRONT CONNECTOR CONFIGURATION

The front input connectors (P3 and P4) on the VMIVME-4150 are standard subminiature 37-pin female D-shell connectors. The P3/P4 connector pin layout is shown in Figure 5.6-1. The pin assignments for P3 and P4 are shown in Table 5.6-1 and 5.6-2.

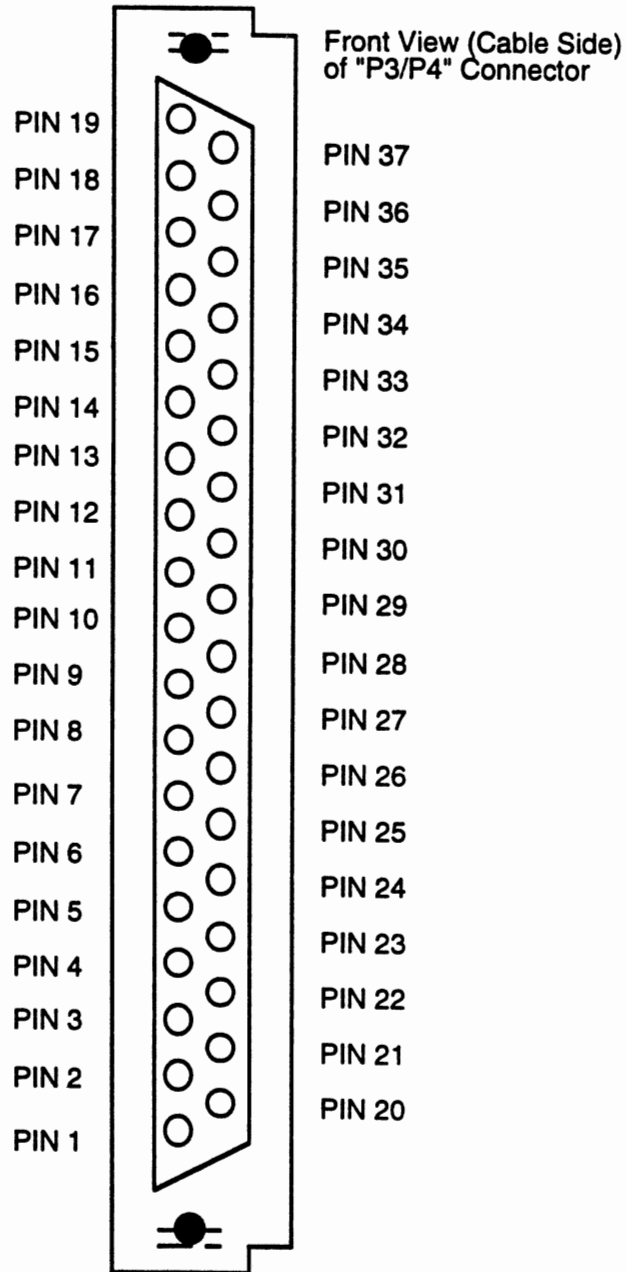


Figure 5.6-1. P3/P4 Connector Pin Layout

Table 5.6-1. P3 Pin Assignments

Pin	Data Bit	Pin	Data Bit
19	OUT 0	37	COMM 0
18	VEXT 0	36	N/C
17	N/C	35	N/C
16	OUT 1	34	COMM 1
15	VEXT 1	33	N/C
14	N/C	32	N/C
13	OUT 2	31	COMM 2
12	VEXT 2	30	N/C
11	N/C	29	N/C
10	OUT 3	28	COMM 3
9	VEXT 3	27	N/C
8	N/C	26	N/C
7	OUT 4	25	COMM 4
6	VEXT 4	24	N/C
5	N/C	23	N/C
4	OUT 5	22	COMM 5
3	VEXT 5	21	N/C
2	N/C	20	N/C
1	N/C		

ch 0

ch 1

ch 2

Table 5.6-2. P4 Pin Assignments

Pin	Data Bit	Pin	Data Bit
19	OUT 6	37	COMM 6
18	VEXT 6	36	N/C
17	N/C	35	N/C
16	OUT 7	34	COMM 7
15	VEXT 7	33	N/C
14	N/C	32	N/C
13	OUT 8	31	COMM 8
12	VEXT 8	30	N/C
11	N/C	29	N/C
10	OUT 9	28	COMM 9
9	VEXT 9	27	N/C
8	N/C	26	N/C
7	OUT 10	25	COMM 10
6	VEXT 10	24	N/C
5	N/C	23	N/C
4	OUT 11	22	COMM 11
3	VEXT 11	21	N/C
2	N/C	20	N/C
1	N/C		

ch 7

Not  
Used